CS394R Reinforcement Learning: Theory and Practice

Peter Stone

Department of Computer Science The University of Texas at Austin

Good Morning Colleagues

• Are there any questions?



• First 3 assignments due



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- Think about final project 2 weeks



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- Robotics talk tomorrow at 11: "Robot Teams to Assist Humans in Scientific Discovery"



The Week 1 Task?



• Continuous state, noisy actions



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- What's needed to do the normal thing?



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- How can we get it?



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- How can we get it?
- Keepaway example



- State-space
- Plan-space



• What's the difference between exploration bonus options (p. 238)



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- Is it easier to generalize a policy or a model?

