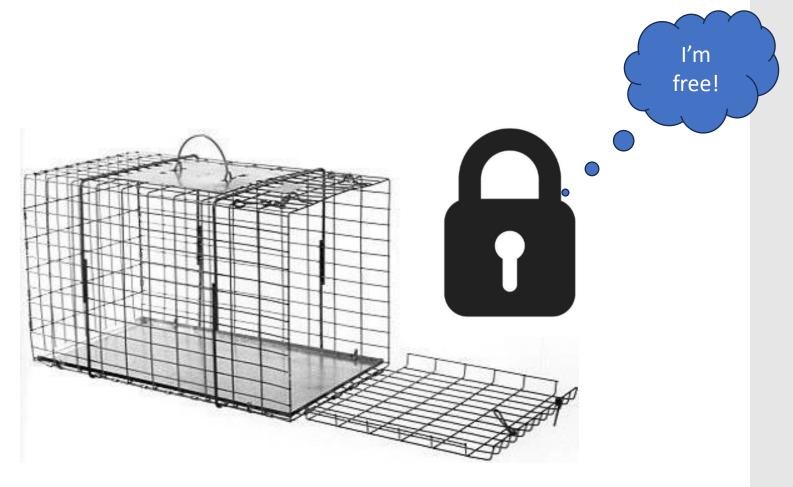
Shared Memory Synchronization Rides Again: Lock Freedom

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Questions?

Administrivia

• Faux Quiz

Agenda:

• Lock Freedom

Faux Quiz Questions: 5 min, pick any 2

- What is obstruction freedom, wait freedom, lock freedom?
- How can one compose lock free data structures?
- What is the difference between linearizability and strong consistency? Between linearizability and serializability?
- What is the ABA problem? Give an example.
- How do lock-free data structures deal with the "inconsistent view" problem?

Locks: a litany of problems

Deadlock

- Deadlock
- Priority inversion

- Deadlock
- Priority inversion
- Convoys

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- Priority inversion
- Convoys
- Fault Isolation

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- Preemption Tolerance

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- Performance

Locks: a litany of problems

- Deadlock
- Priority inversion
- Convoys
- Fault Isolation
- Preemption Tolerance
- Performance

Solution: don't use locks

- Deadlock
- Priority inversion
- Convoys
- Fault Isolation
- Preemption Tolerance
- Performance

• Subset of a broader class: Non-blocking Synchronization

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- Thread-safe access shared mutable state without mutual exclusion

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- Subset of a broader class: Non-blocking Synchronization
- Thread-safe access shared mutable state without mutual exclusion
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 - e.g. Lamport's Concurrent Buffer
 - ...but not really practical wo HW
- Built on atomic instructions like CAS + clever algorithmic tricks
- Lock-free *algorithms* are hard, so
- General approach: encapsulate lock-free algorithms in data structures
 - Queue, list, hash-table, skip list, etc.
 - New LF data structure \rightarrow research result

struct Node
{
 int data;
 struct Node *next;
};

```
struct Node
{
   int data;
   struct Node *next;
};
```

```
void append(Node** head_ref, int new_data) {
    Node* new_node = mknode(new_data, head_ref);
    if (*head_ref == NULL) {
        *head_ref = new_node;
        return;
    }
    while (last->next != NULL)
        last = last->next;
    last->next = new_node;
}
```

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• Is this thread safe?

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struct Node
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        *head_ref = new_node;
        return;
    }
    while (last->next != NULL)
        last = last->next;
        last->next = new_node;
}
```

- Is this thread safe?
- What can go wrong?

```
Example: List Append
                                              struct Node
                                                int data;
                                                struct Node *next;
                                              };
void append(Node** head ref, int new data) {
    Node* new node = mknode (new data, head ref);
    lock();
    if (*head ref == NULL) {
       *head ref = new node;
    } else {
      while (last->next != NULL)
           last = last->next;
       last->next = new node;
   unlock();
```

```
Example: List Append
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    What property do the locks enforce?

   unlock();
```

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   unlock();

    What does the mutual exclusion ensure?
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    What property do the locks enforce?

    unlock();

    What does the mutual exclusion ensure?

    Can we ensure consistent view (invariants hold) sans mutual exclusion?
```

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Example: List Append
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    Node* new node = mknode(new data, head ref);
    lock();
    if (*head ref == NULL) {
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     } else {
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            last = last->next;
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    What property do the locks enforce?

    unlock();

    What does the mutual exclusion ensure?

    Can we ensure consistent view (invariants hold) sans mutual exclusion?
```

• Key insight: allow inconsistent view and fix it up algorithmically

```
Fxample: list Annend structure
void append (Node** head ref, int new data) {
                                                    struct Node
     Node* new node = mknode (new data);
                                                           data;
                                                           uct Node *next;
     new node->next = NULL;
     while(TRUE) {
          Node * last = *head ref;
          if(last == NULL) {
               if(cas(head ref, new node, NULL))
                     break;
          while(last->next != NULL)
               last = last->next;
          if(cas(&last->next, new node, NULL))
               break;
                                                           22
                                                           sure?

    Can we ensure consistent view (invariants hold) sans mutual exclusion?

                                 • Key insight: allow inconsistent view and fix it up algorithmically
```

```
Example: SP-SC Queue
```

```
next(x):
    if(x == Q_size-1) return 0;
    else return x+1;
Q_get(data):
    t = Q_tail;
    while(t == Q_head)
    ;
    data = Q_buf[t];
    Q_tail = next(t);
    next(t);
    neturn 0;
    Q_put(data):
    h = Q_put(data):
    h = Q_head;
    while(next(h) == Q_tail)
    ;
    Q_buf[h] = data;
    Q_head = next(h);
```

- Single-producer single-consumer
- Why/when does this work?

Example: SP-SC Queue

```
next(x):
    if(x == Q_size-1) return 0;
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Q_get(data):
    t = Q_tail;
    while(t == Q_head)
    ;
    data = Q_buf[t];
    Q_tail = next(t);
```

- Single-producer single-consumer
- Why/when does this work?

```
Q_put(data):
    h = Q_head;
    while(next(h) == Q_tail)
    ;
    Q_buf[h] = data;
    Q_head = next(h);
```

- 1. Q_head is last write in Q_put, so Q_get never gets "ahead".
- 2. *single* p,c only (as advertised)
- 3. Requires fence before setting Q head
- 4. Devil in the details of "wait"
- 5. No lock \rightarrow "optimistic"

```
void push(int t) {
    Node* node = new Node(t);
    do {
        node->next = head;
    } while (!cas(&head, node, node->next));
bool pop(int& t) {
   Node* current = head;
   while(current) {
       if(cas(&head, current->next, current)) {
          t = current -> data;
          return true;
       current = head;
   return false;
```

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struct Node
{
   int data;
   struct Node *next;
};
```

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};
void push(int t) {
    Node* node = new Node(t);
    do {
        node->next = head;
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          t = current->data; // problem?
          return true;
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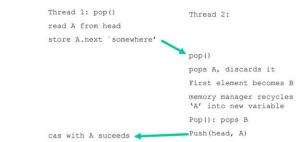
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   while(current) {
       if(cas(&head, current->next, current)) {
          t = current->data; // problem?
          return true;
       current = head;
                                            Why does is it work?

    Does it enforce all invariants?

   return false;
```

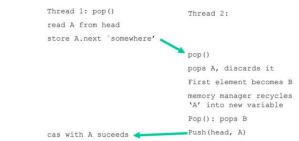
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struct Node
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```



```
Node* pop() {
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    while(current) {
        if(cas(&head, current->next, current))
            return current;
        current = head;
    }
```

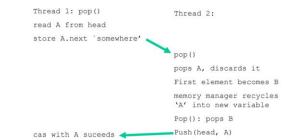
return false;

}



Node* pop() {
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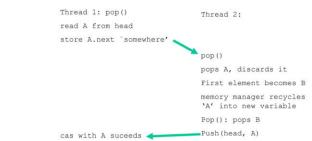
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```

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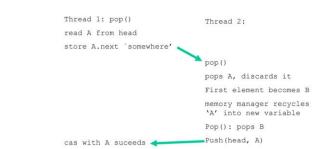
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Node* pop() {
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Node* pop() {
    Node* current = head;
    while(current) {
        if(cas(&head, current->next, current))
            return current;
        current = head;
    }
    return false;
```

```
Node * node = pop();
delete node;
node = new Node(blah_blah);
push(node);
```



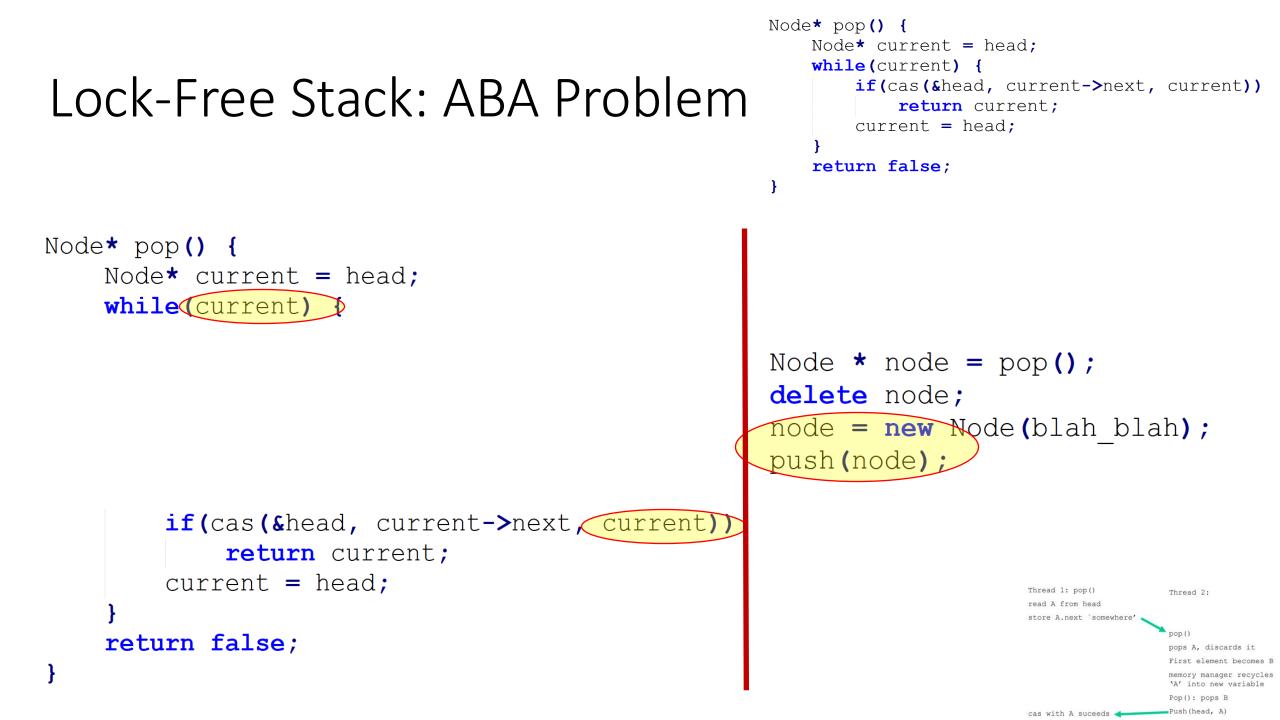
```
Node* pop() {
                                                                     Node* current = head;
                                                                     while(current) {
Lock-Free Stack: ABA Problem
                                                                         if(cas(&head, current->next, current))
                                                                             return current;
                                                                         current = head;
                                                                     return false;
Node* pop() {
     Node* current = head;
     while(current) {
                                                                 Node * node = pop();
                                                                 delete node;
                                                                 node = new Node(blah blah);
                                                                 push(node);
           if(cas(&head, current->next, current))
                return current;
           current = head;
                                                                                         Thread 1: pop()
                                                                                                     Thread 2:
                                                                                         read A from head
                                                                                         store A.next `somewhere'
                                                                                                     pop()
     return false;
                                                                                                     pops A, discards it
                                                                                                     First element becomes B
                                                                                                     memory manager recycles
                                                                                                     'A' into new variable
```

Pop(): pops B Push(head, A)

cas with A suceeds 📥

```
Node* pop() {
                                                                       Node* current = head;
                                                                       while(current) {
Lock-Free Stack: ABA Problem
                                                                           if(cas(&head, current->next, current))
                                                                               return current;
                                                                           current = head;
                                                                       return false;
Node* pop() {
     Node* current = head;
     while (current)
                                                                   Node * node = pop();
                                                                   delete node;
                                                                   node = new Node(blah blah);
                                                                   push(node);
           if(cas(&head, current->next, current))
                return current;
           current = head;
                                                                                            Thread 1: pop()
                                                                                                         Thread 2:
                                                                                            read A from head
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                                                                                                         pop()
     return false;
                                                                                                         pops A, discards it
                                                                                                         First element becomes B
                                                                                                         memory manager recycles
                                                                                                         'A' into new variable
                                                                                                         Pop(): pops B
                                                                                                        -Push(head, A)
```

cas with A suceeds 📥



ABA Problem

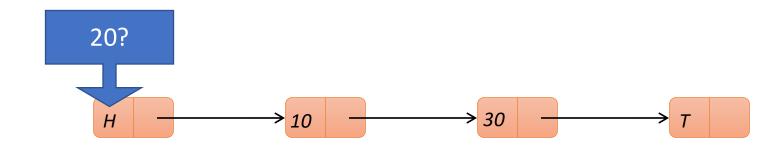
- Thread 1 observes shared variable \rightarrow 'A'
- Thread 1 calculates using that value
- Thread 2 changes variable to B
 - if Thread 1 wakes up now and tries to CAS, CAS fails and Thread 1 retries
- Instead, Thread 2 changes variable back to A!
 - CAS succeeds despite mutated state
 - Very bad if the variables are pointers

- Keep update count \rightarrow DCAS
- Avoid re-using memory
- Multi-CAS support \rightarrow HTM

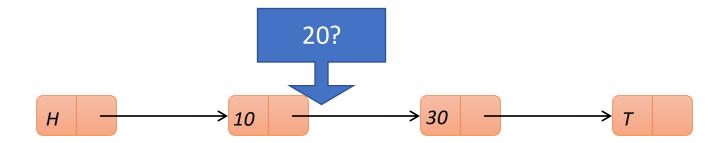
• find(20):



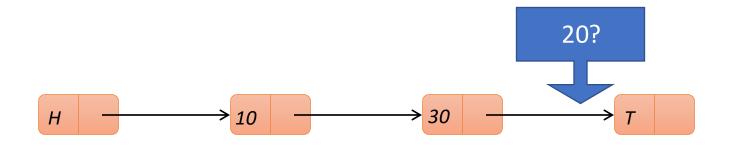
• find(20):



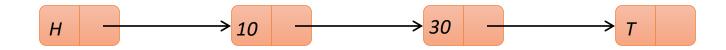
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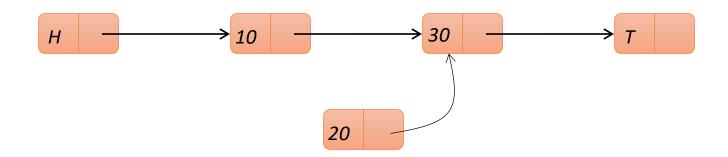


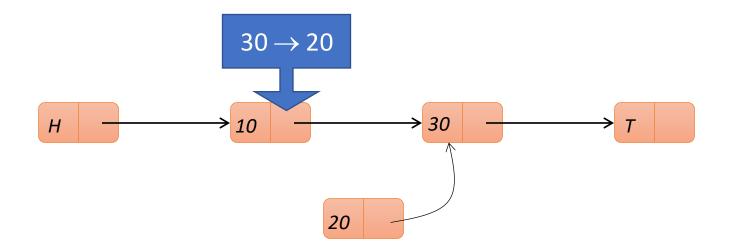
• find(20):



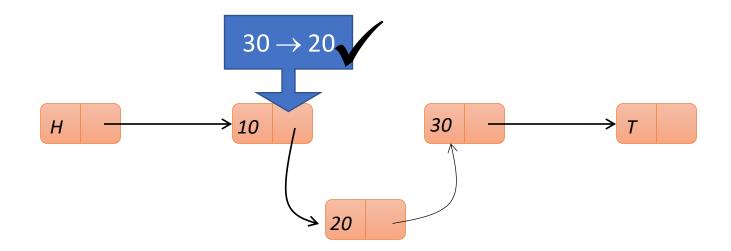
find(20) -> false





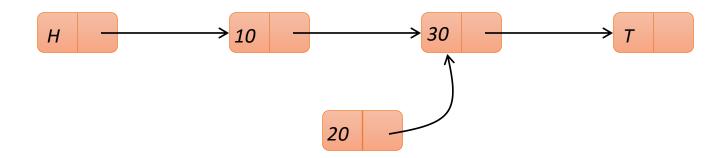


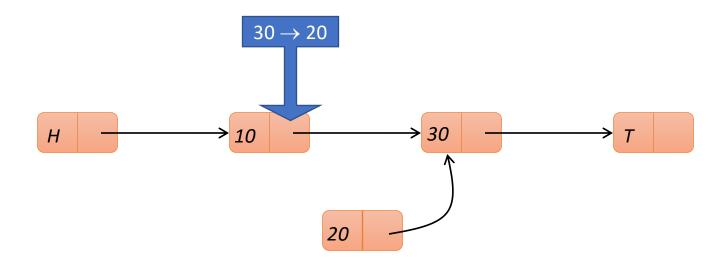
• insert(20):



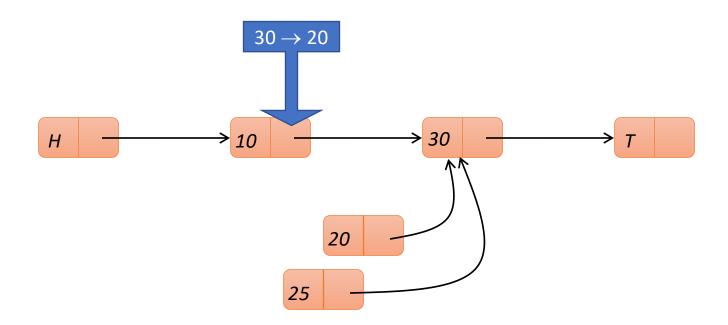
insert(20) -> true



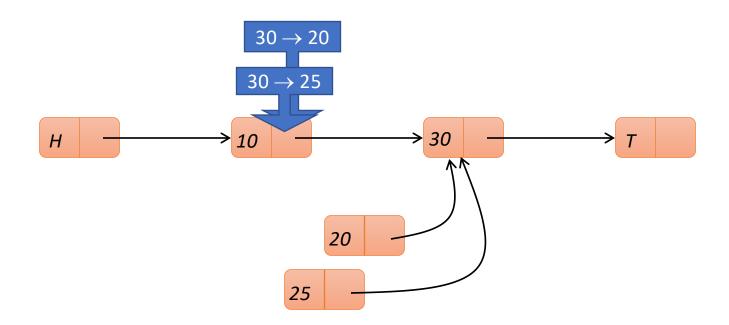




• insert(20): • insert(25):



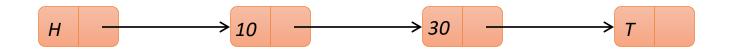
• insert(20): • insert(25):



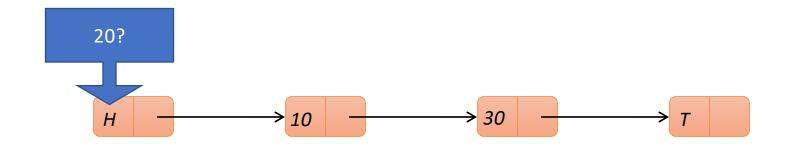
• insert(20): • insert(25): $30 \rightarrow 20$ $30 \rightarrow 25$ 30 Η → 10 Т \mathbf{V} 20 K 25

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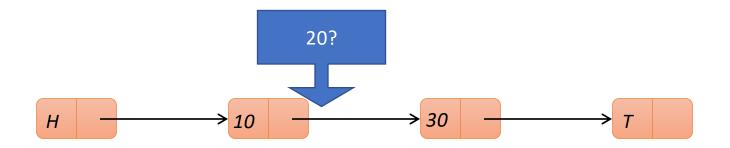
• find(20)



• find(20)

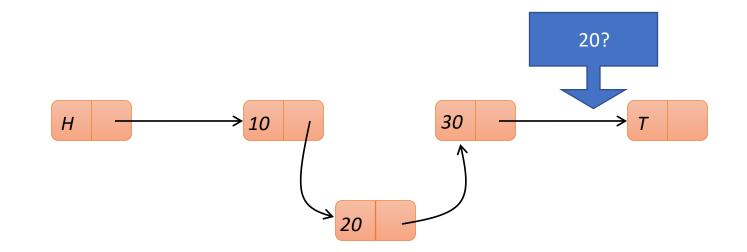


• find(20)

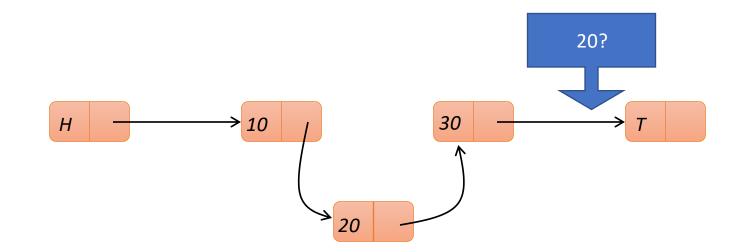


 $H \longrightarrow 10 \longrightarrow 30 \longrightarrow T$

find(20)
 insert(20) -> true



• find(20) -> false • insert(20) -> true



find(20) -> false

This thread saw 20 was not in the set...

insert(20) -> true

...but this thread succeeded in putting it in!

- Is this a correct implementation?
- Should the programmer be surprised if this happens?
- What about more complicated mixes of operations?

Correctness criteria

Informally:

Look at the behavior of the data structure

- what operations are called on it
- what their results are

If behavior is indistinguishable from atomic calls to a sequential implementation then the concurrent implementation is correct.

• No overlapping invocations

time

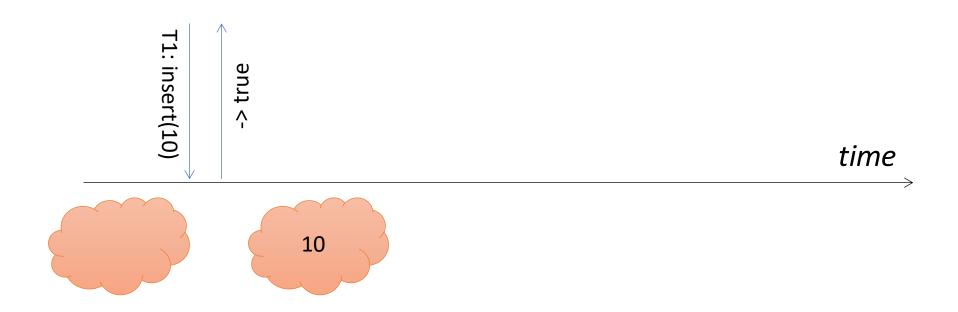
 \rightarrow

• No overlapping invocations

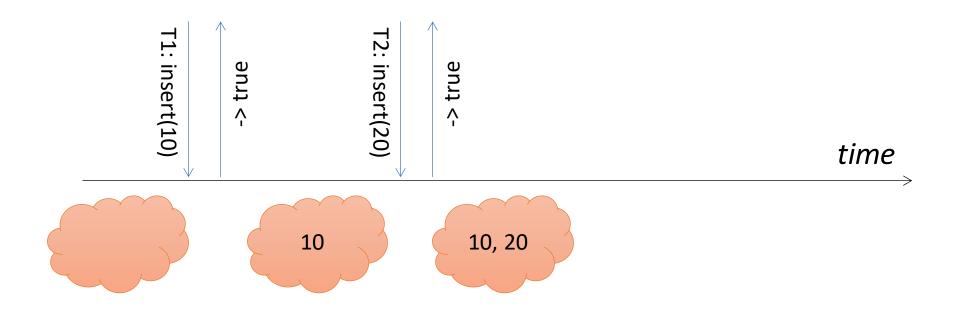


time

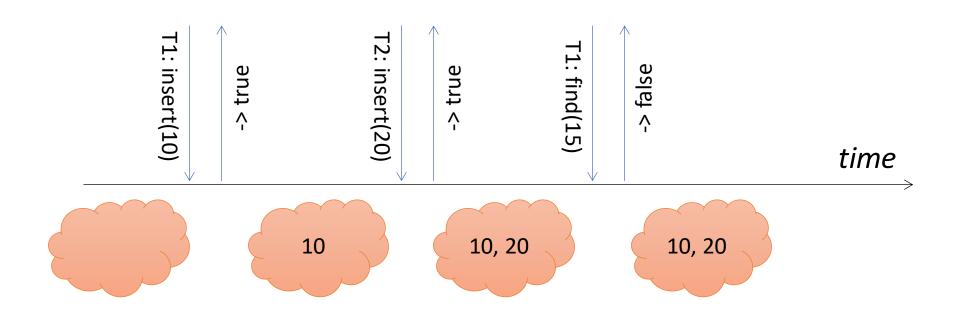
• No overlapping invocations



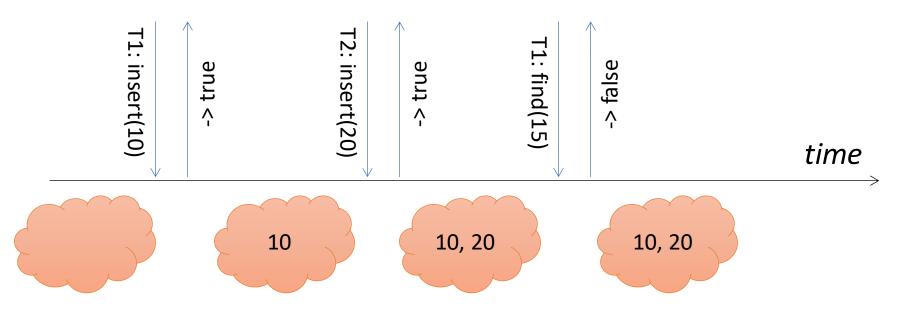
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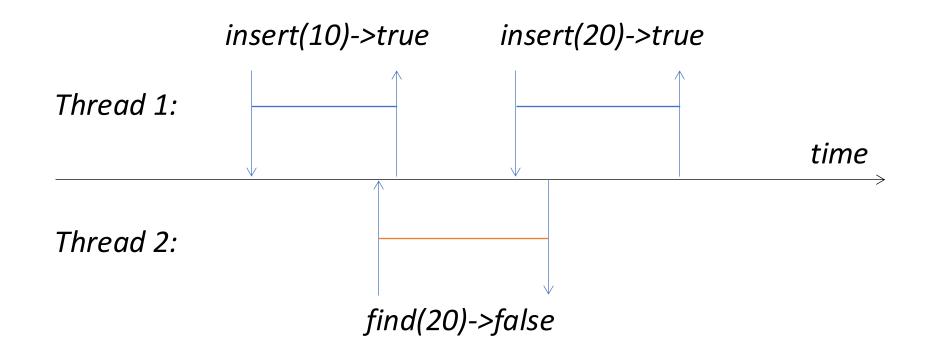


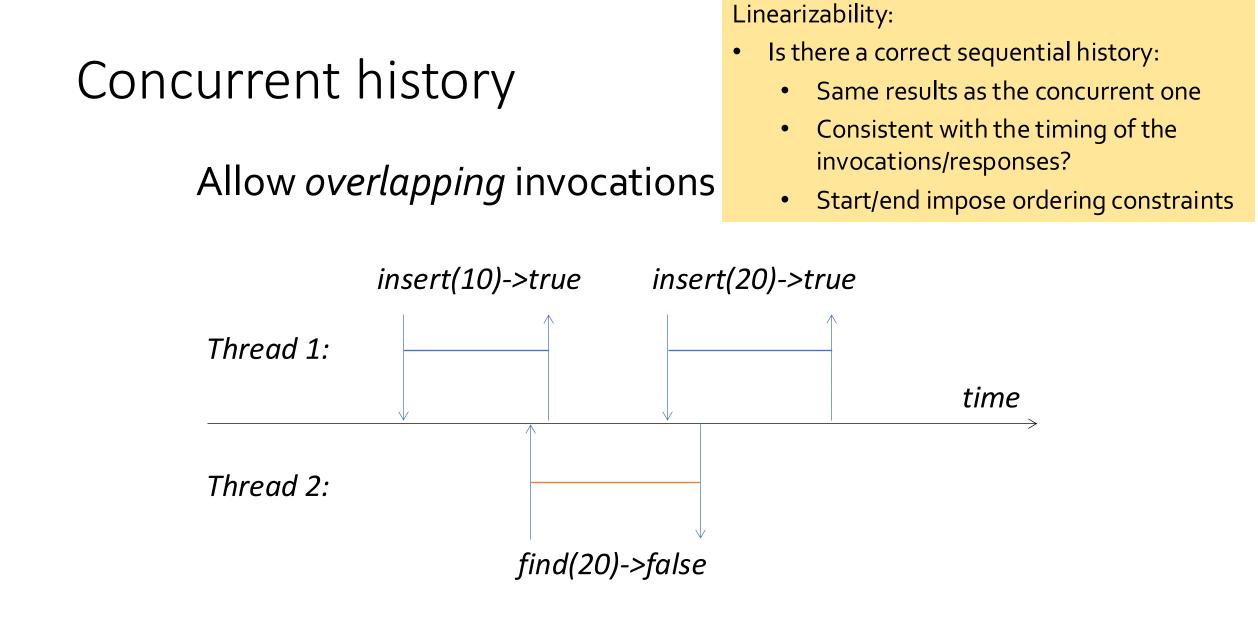
Linearizability: concurrent behaviour should be similar

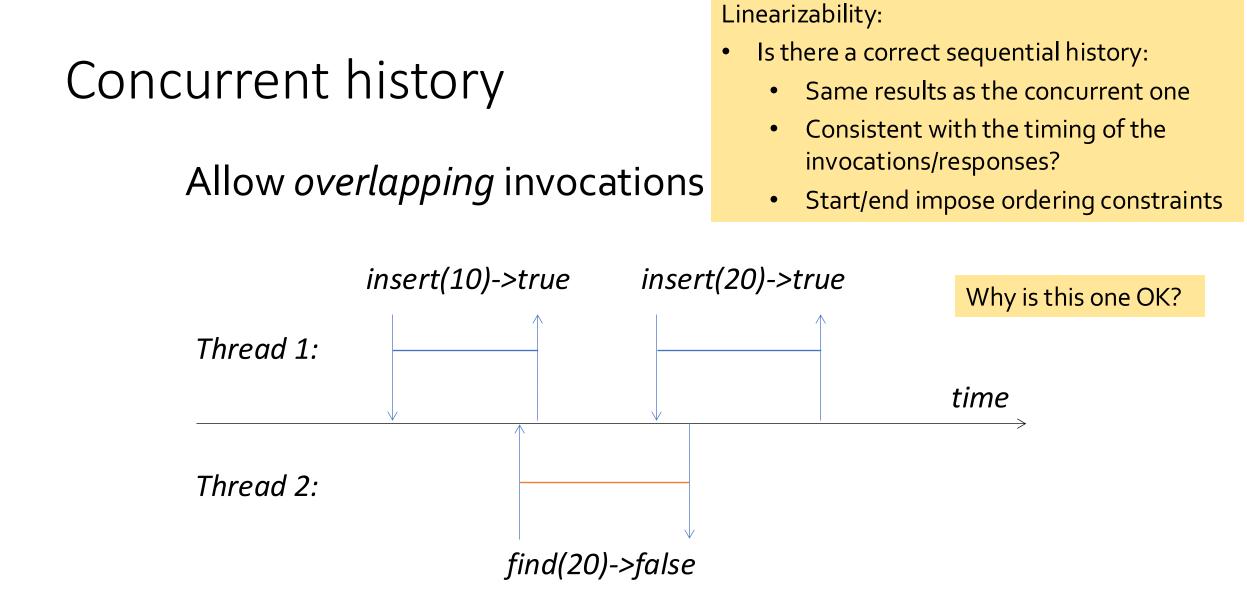
- even when threads can see intermediate state
- Recall: mutual exclusion precludes overlap 21

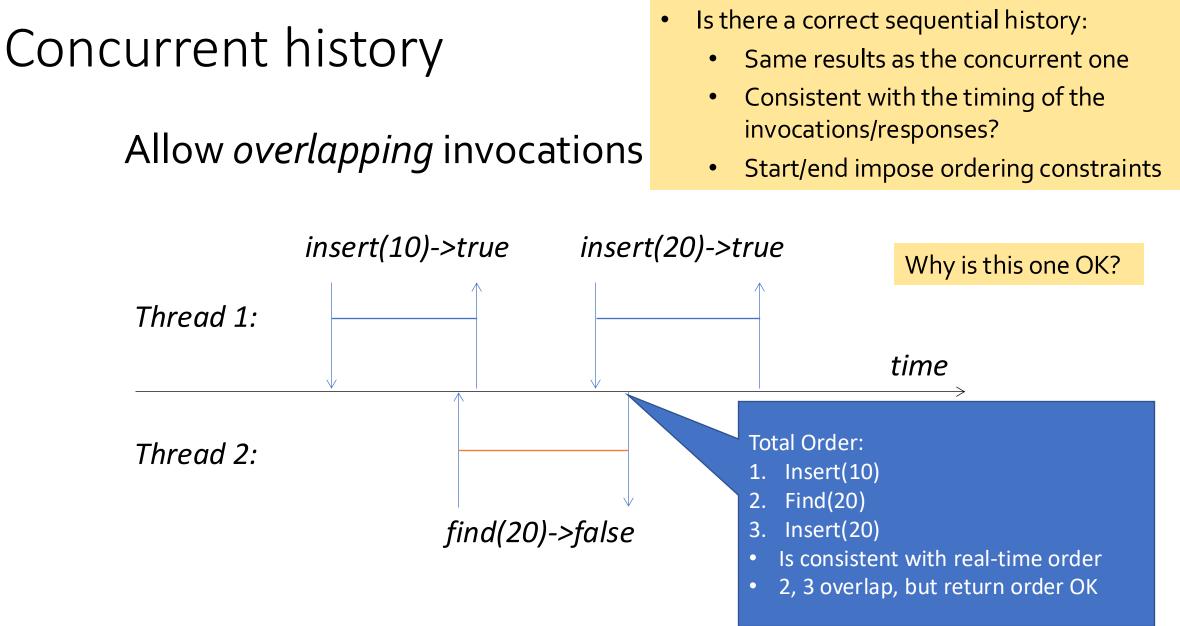
Concurrent history

Allow overlapping invocations

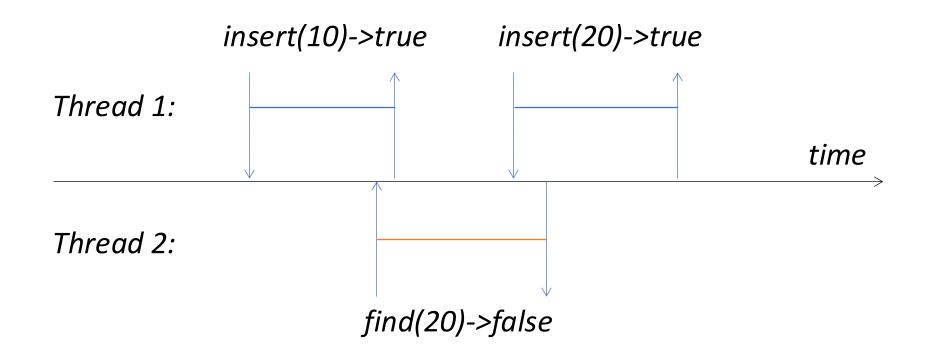


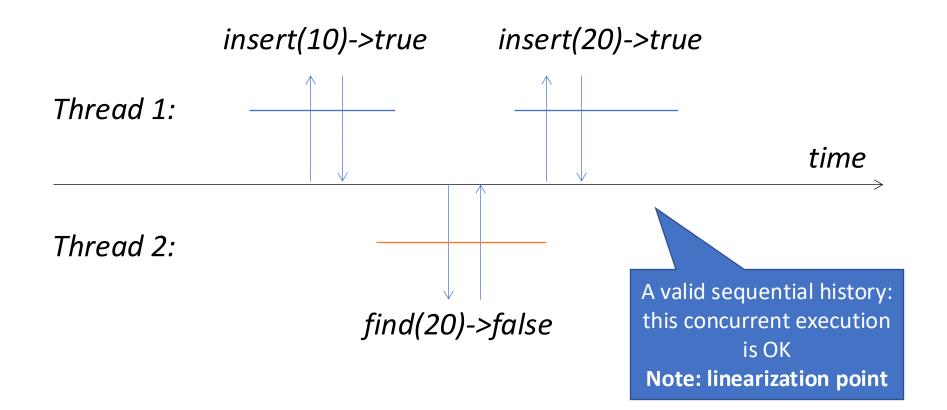


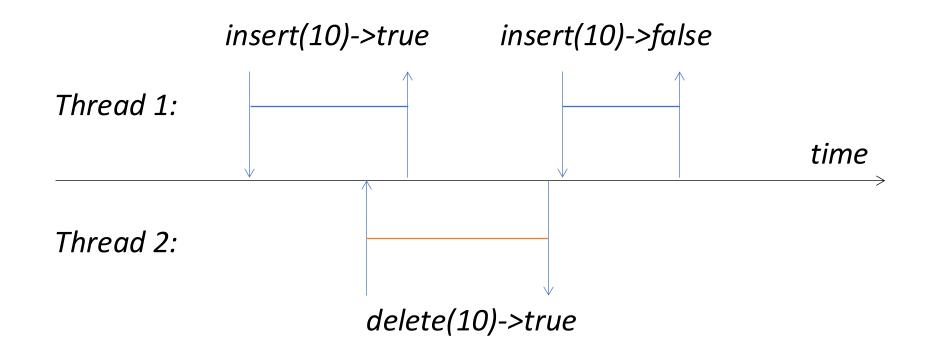


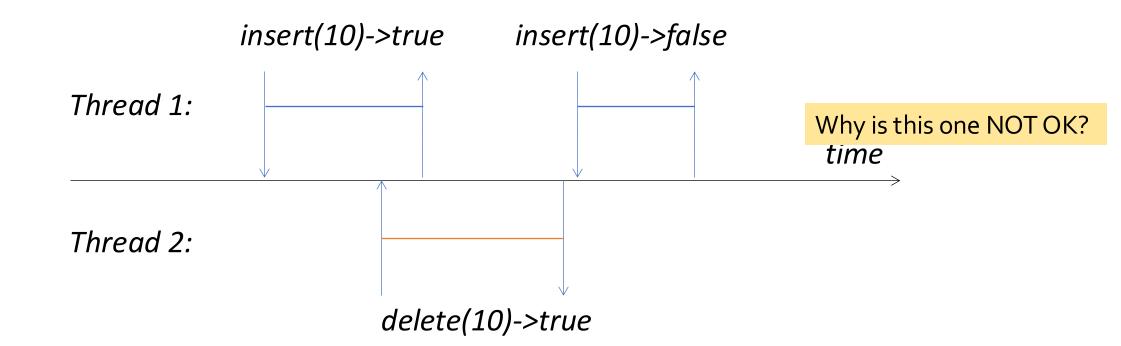


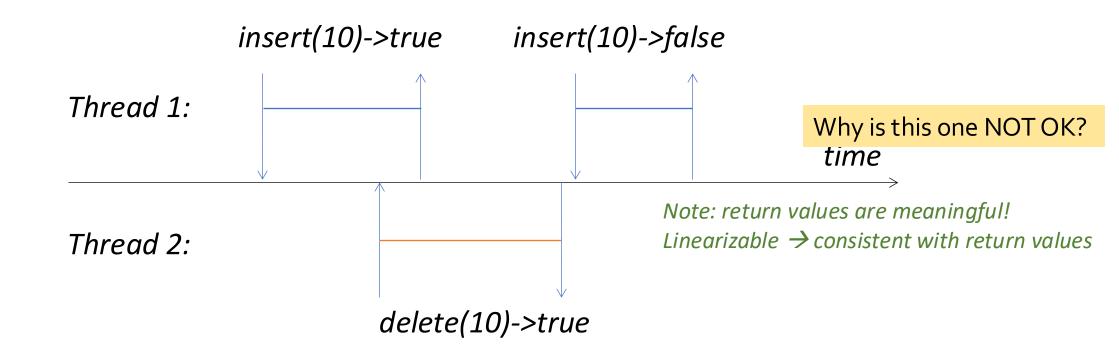
Linearizability:

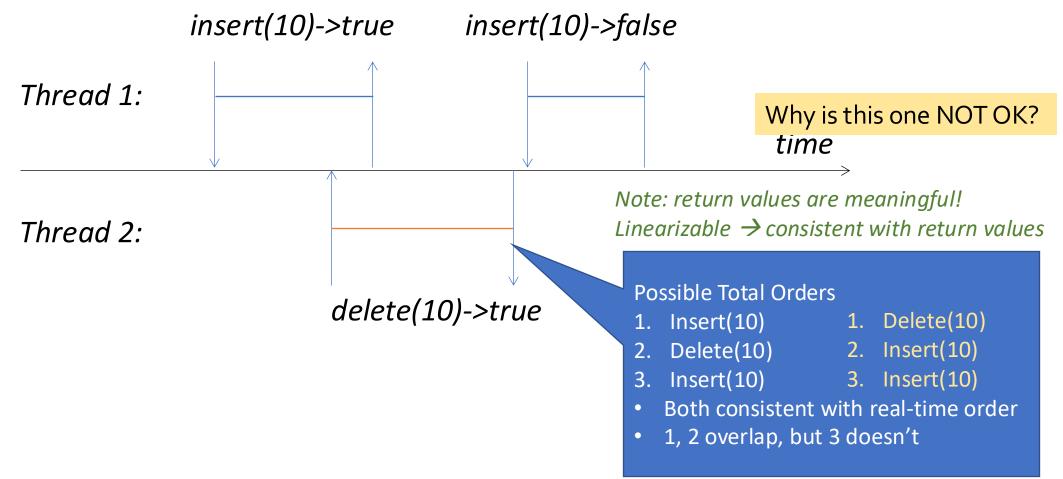


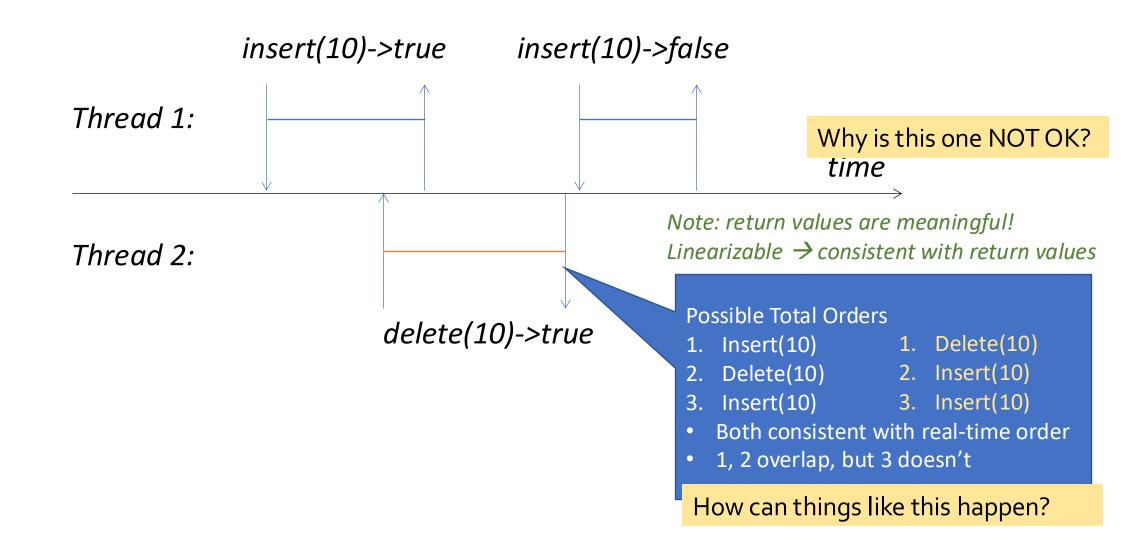












• find(20)

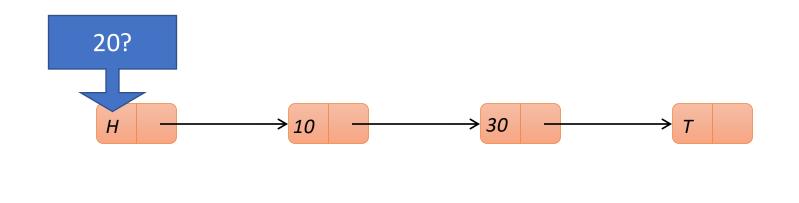


Thread 1:

Thread 2:

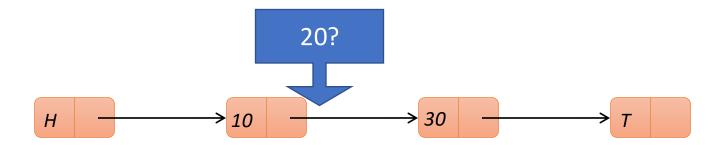
 \geq

• find(20)



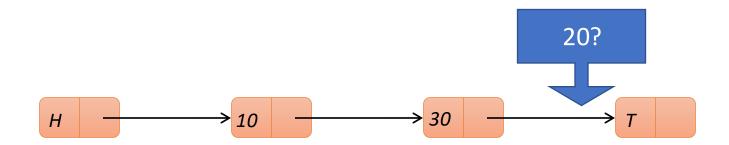


• find(20)



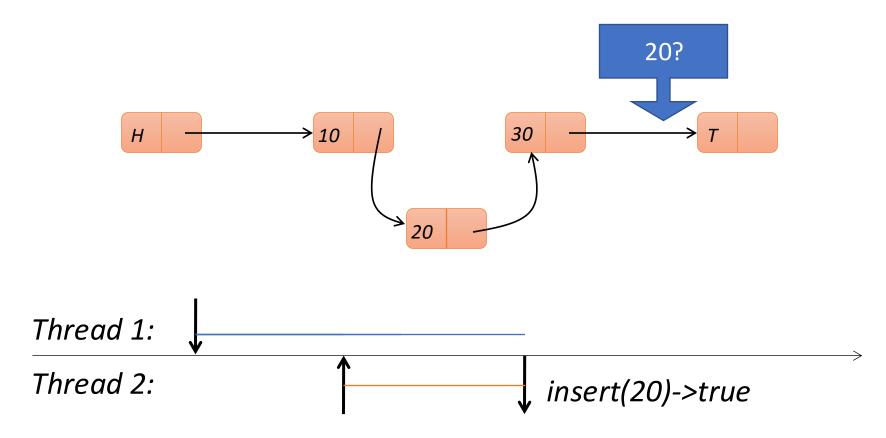


• find(20)

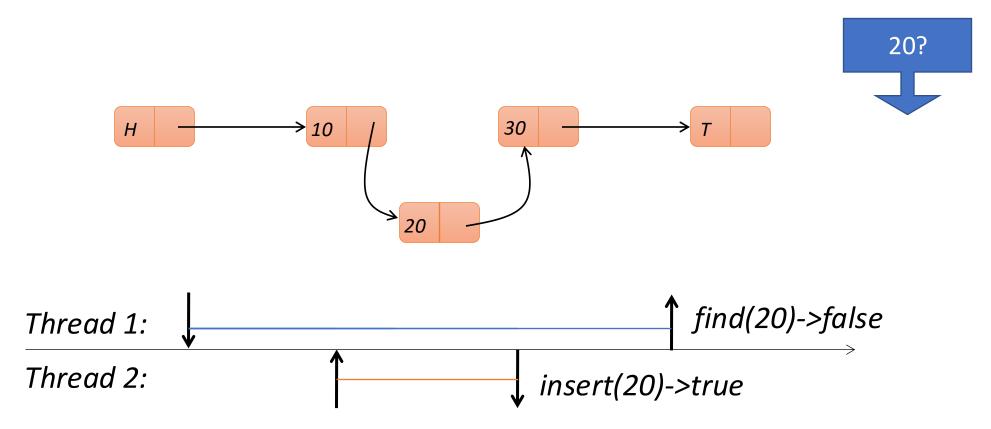




• find(20) • insert(20) -> true

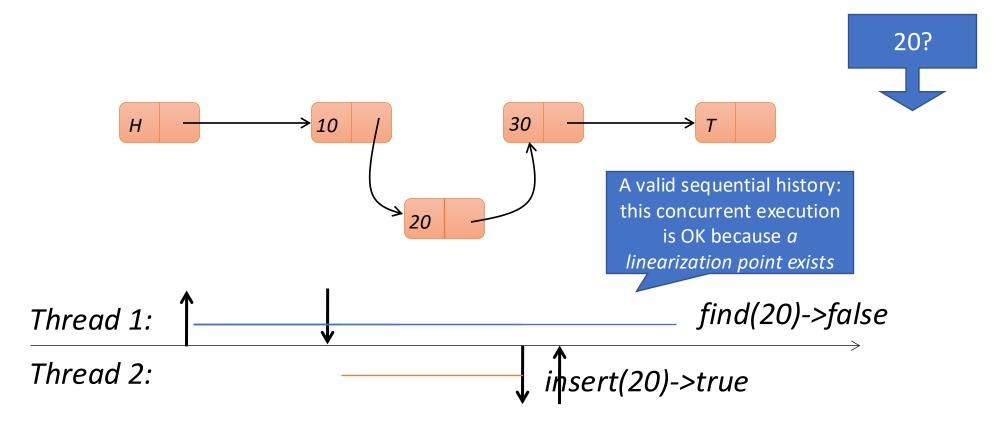


• find(20) -> false • insert(20) -> true



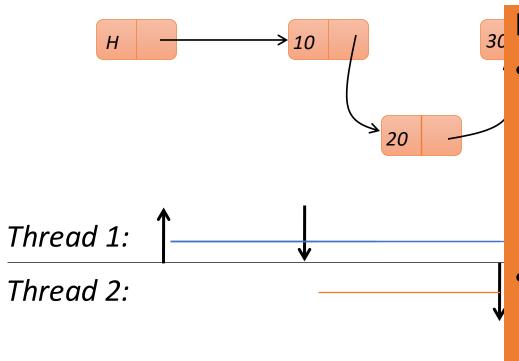
find(20) -> false

• insert(20) -> true



find(20) -> false

insert(20) -> true



Recurring Techniques:

- For updates
 - Perform an essential step of an operation by a single atomic instruction
 - E.g. CAS to insert an item into a list

20?

• This forms a "linearization point"

• For reads

- Identify a point during the operation's execution when the result is valid
- Not always a specific instruction

• Wait-free

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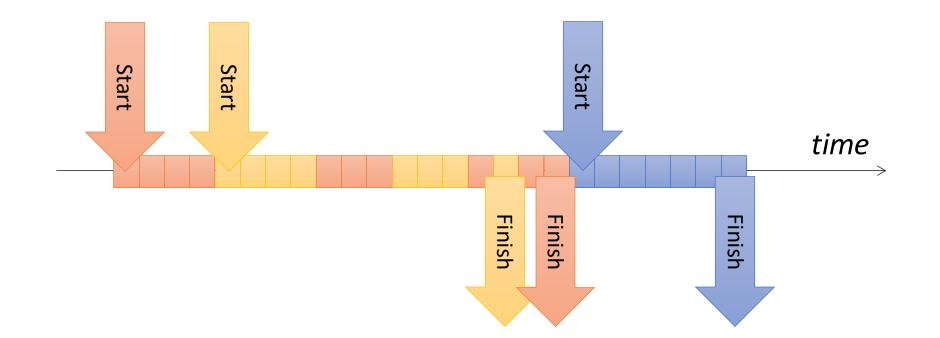
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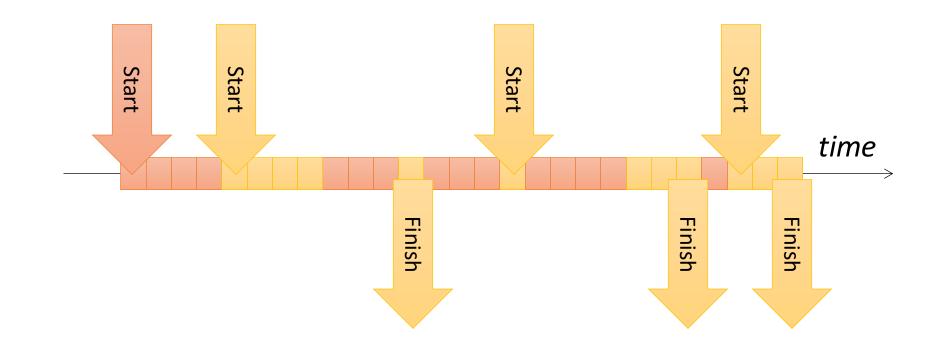


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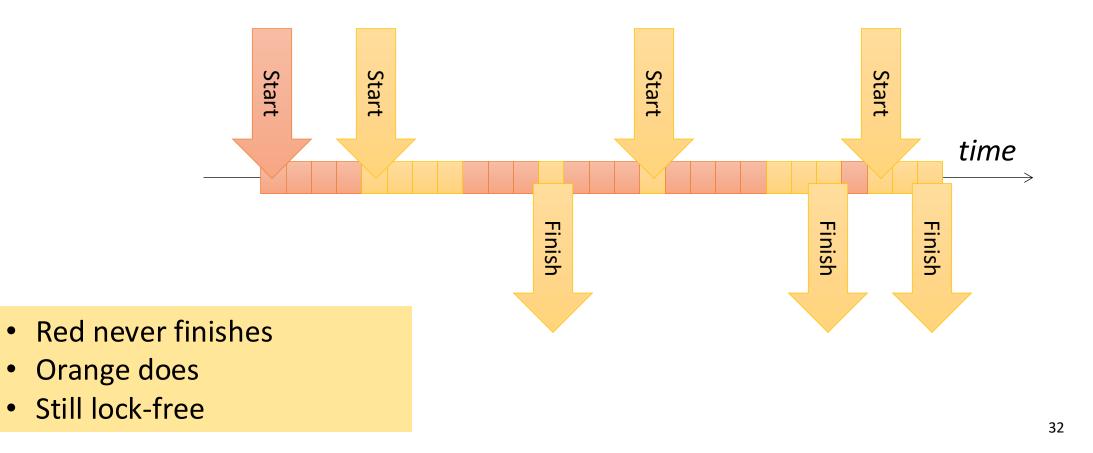
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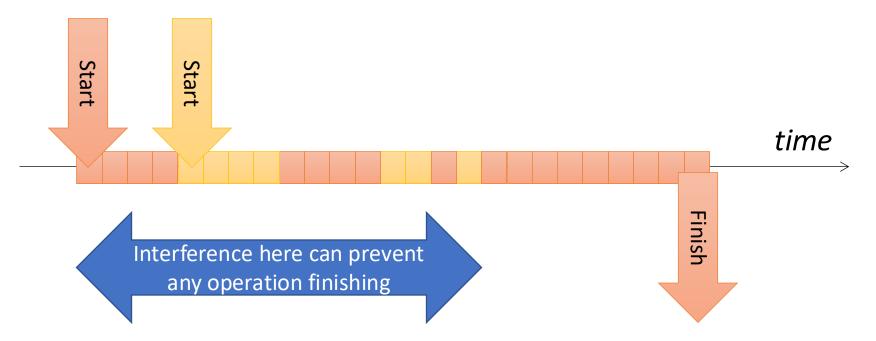
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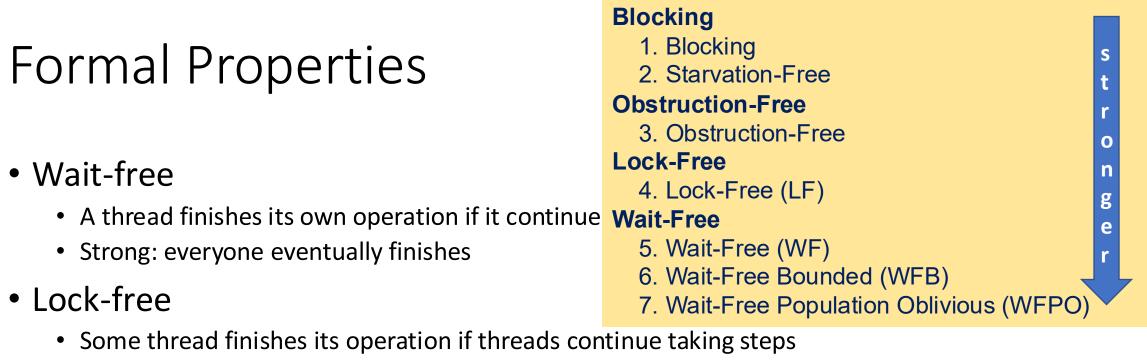


Formal Properties

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Blocking

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 - one method is never forced to wait to sync with another.

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T * list::remove(Obj key){
  LOCK(this);
  tmp = __do_remove(key);
  UNLOCK(this);
  return tmp;
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Thread-safe?

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Lock-based code doesn't compose

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Lock-based code doesn't compose

- Painting with a very broad brush Composition with linearizability is really about composed schedules
- If list were a linearizable concurrent data structure, composition OK?

}

- non-blocking
 - one method is never forced to wait to sync with another.
- applies to histories and objects and systems:
 - a history can be linearizable
 - an object is linearizable if all valid histories of its use are linearizable
- local property:
 - a system is linearizable iff each individual object is linearizable.
 - gives us **composability**.
- Why is it important?
 - Serializability is not composable.
 - Core hypotheses:
 - structuring all as concurrent objects buys composability
 - structuring all as concurrent objects is tractable/possible

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 - Can you compose codes that provide property P
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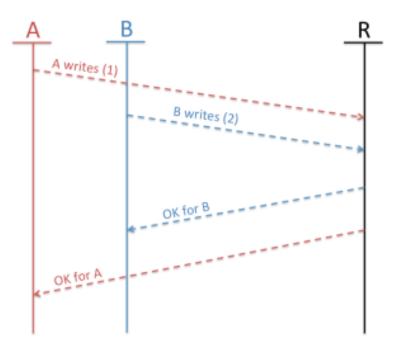
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- These are related but differ in subtle ways
- Non-composability of serializability is really about composing schedules

• Threads A, B write integers to a register R

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- Because it is concurrent, method invocations overlap

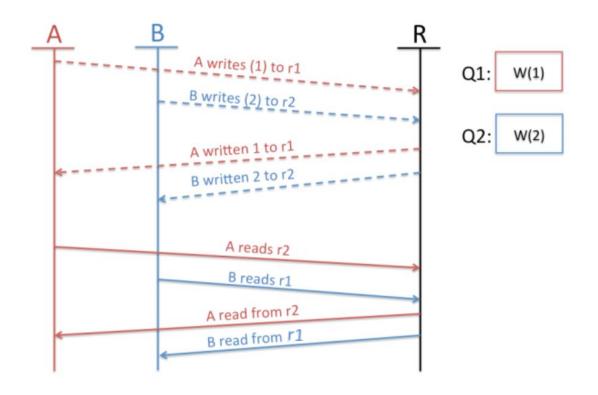
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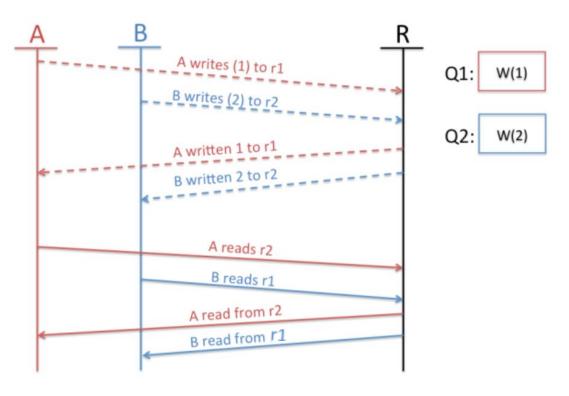
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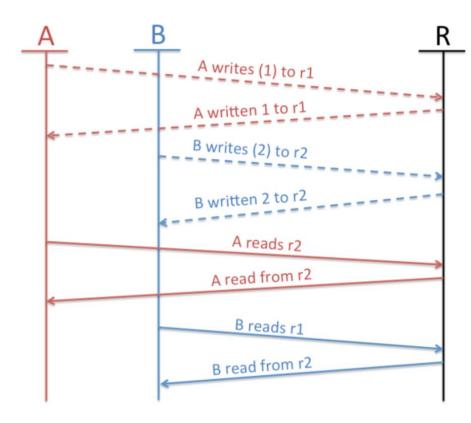


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- Serializability:
 - Execution equivalent to some serial order
 - All see same order

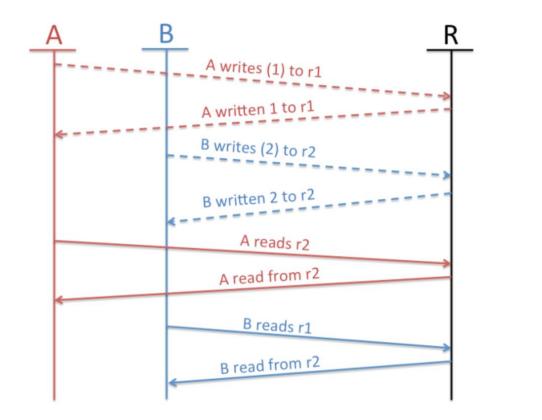


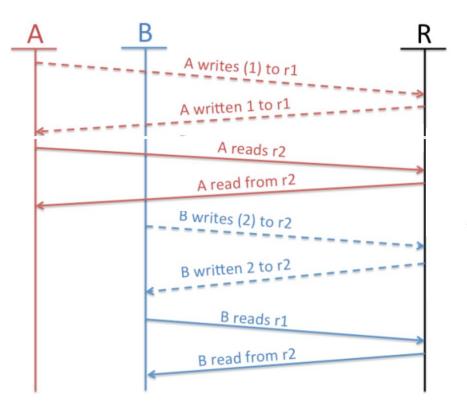
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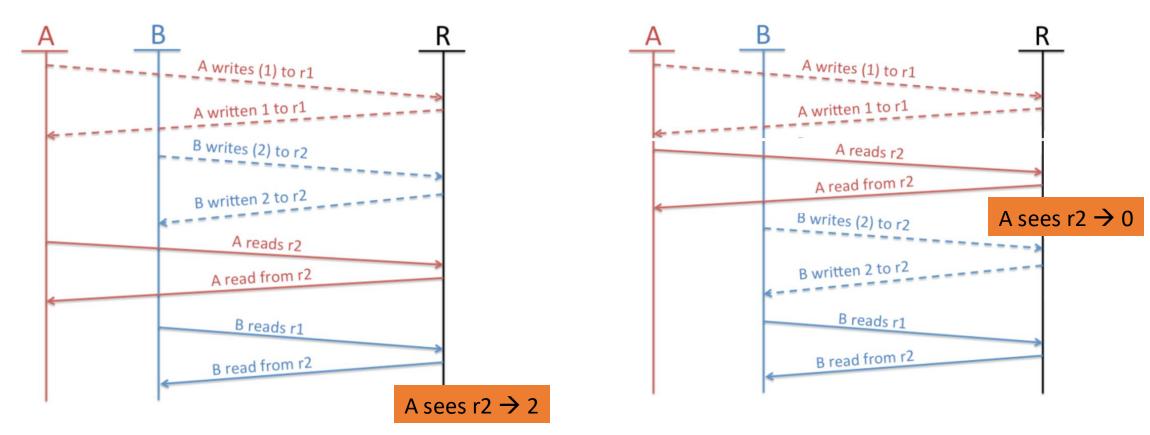


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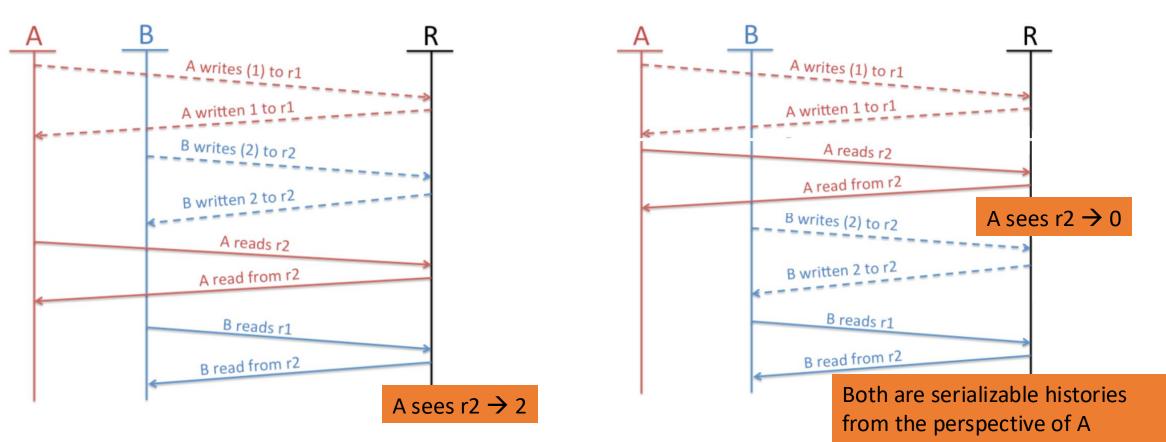




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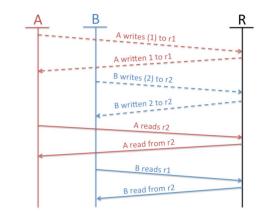


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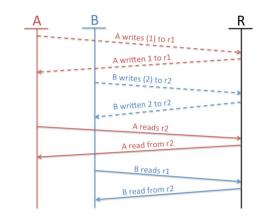


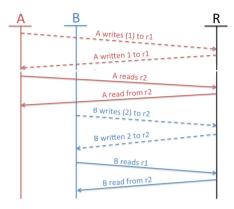
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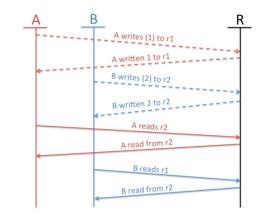


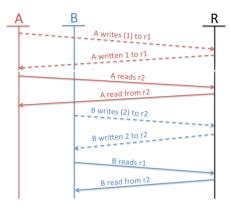
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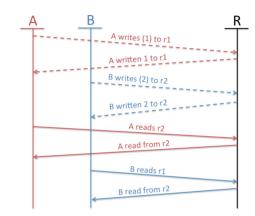
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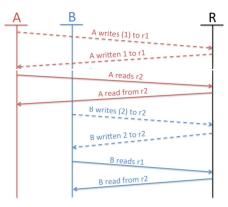




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Sub-History	Outcome
H1a	A writes r1=1, reads r2 \rightarrow 0
H2a	A writes r1=1, reads r2 \rightarrow 2
H1b	B writes r2=2, reads r1 \rightarrow 0
H2b	B writes r2=2, reads r1 \rightarrow 1



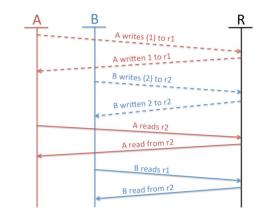


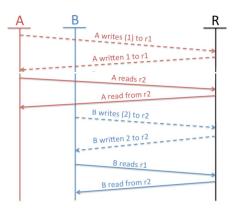
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From the perspective of threads A, B, all sub-histories are serializable

- They respect program order for each of A, B
- And are equivalent to *some* serial execution
- If we "compose" these histories, some composed histories not serializable





• Compose sub-histories to form all possible histories

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History	Effect
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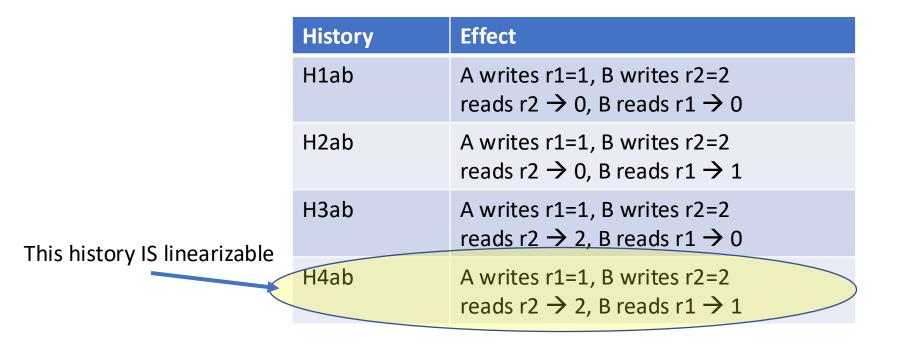
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H1b	B writes r2=2, reads r1 \rightarrow 0	H2ab	A writes r1=1, B writes r2=2 A reads r2 \rightarrow 0, B reads r1 \rightarrow 1
H2b	B writes r2=2, reads r1 \rightarrow 1	H3ab	A writes r1=1, B writes r2=2 A reads r2 \rightarrow 2, B reads r1 \rightarrow 0
	4 serializable sub-histories composed To form 4 complete histories, Only H4ab is actually serializable	H4ab	A writes r1=1, B writes r2=2 A reads r2 \rightarrow 2, B reads r1 \rightarrow 1

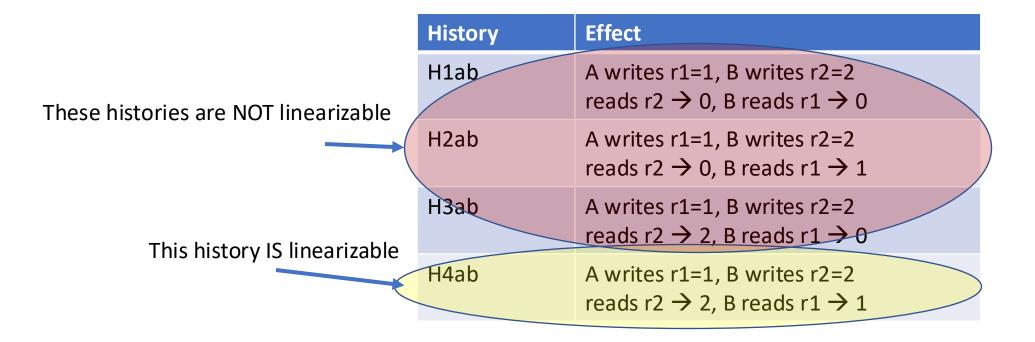
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 - Equivalent to adding constraint that operations respect real time order of operations

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Another Perspective

Serializability

invocations and responses can be reordered to yield a sequential history

the sequential history is correct according to the sequential definition of the object

Linearizability

invocations and responses can be reordered to yield a sequential history

the sequential history is correct according to the sequential definition of the/each object

if a response preceded an invocation in the original history, it must still precede it in the sequential reordering

Linearizability Redux

- non-blocking
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- applies to histories and objects and systems:
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- Population count
- Iteration
- Resizing the bucket array

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Options to consider when implementing a "difficult" operation:

Relax the semantics (e.g., non-exact count, or non-linearizable count)

Fall back to a simple implementation if permitted (e.g., lock the whole table for resize)

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Design a clever implementation (e.g., split-ordered lists)

Use a different data structure (e.g., skip lists)