

Synchronization + Cache Coherence

Chris Rossbach + Calvin Lin

CS380p

Today

- Reminder: Homework & Reading
- Foundations
 - Synchronization Implementation
 - Cache coherence



Review: Schedules/Interleavings

Model of concurrent execution

- Interleave statements from each thread into a single thread
- If **any** interleaving yields incorrect results, synchronization is needed

Thread 1

```
tmp1 = x;  
tmp1 = tmp1 + 1;  
x = tmp1;
```

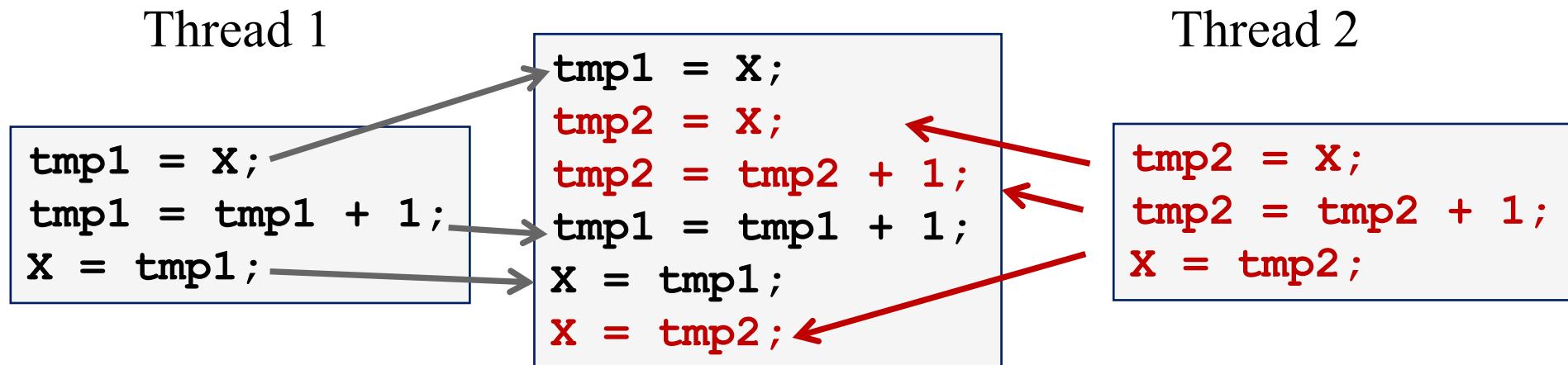
Thread 2

```
tmp2 = x;  
tmp2 = tmp2 + 1;  
x = tmp2;
```

Review: Schedules/Interleavings

Model of concurrent execution

- Interleave statements from each thread into a single thread
- If **any** interleaving yields incorrect results, synchronization is needed



If `X==0` initially, `X == 1` at the end. **WRONG** result!

Locks implement Mutual Exclusion

```
void increment() {  
    lock.acquire();  
    int temp = x;  
    temp = temp + 1;  
    x = temp;  
    lock.release();  
}
```

Mutual exclusion ensures only safe interleavings

- *But it limits concurrency, and hence scalability/performance*

Implementing Locks

```
int lock_value = 0;  
int* lock = &lock_value;
```

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int lock_value = 0;  
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```
lock::acquire() {  
    while (*lock == 1)  
        ; //spin  
    *lock = 1;  
}
```

Implementing Locks

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int lock_value = 0;  
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lock::acquire() {  
    while (*lock == 1)  
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}
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```
lock::release() {  
    *lock = 0;  
}
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Implementing Locks

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int lock_value = 0;  
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```
lock::acquire() {  
    while (*lock == 1)  
        ; //spin  
    *lock = 1;  
}
```

```
lock::release() {  
    *lock = 0;  
}
```

What are the problem(s) with this?

- A. CPU usage
- B. Memory usage
- C. lock::acquire() latency
- D. Memory bus usage
- E. Does not work

Multiprocessor Cache Coherence

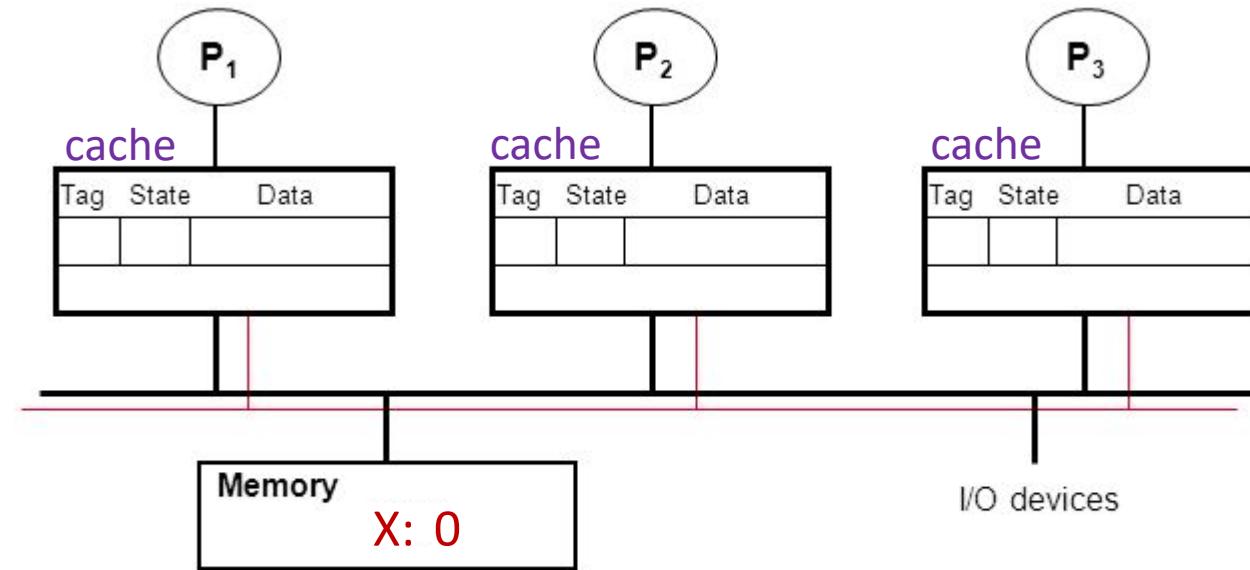
$$F = ma$$

Multiprocessor Cache Coherence

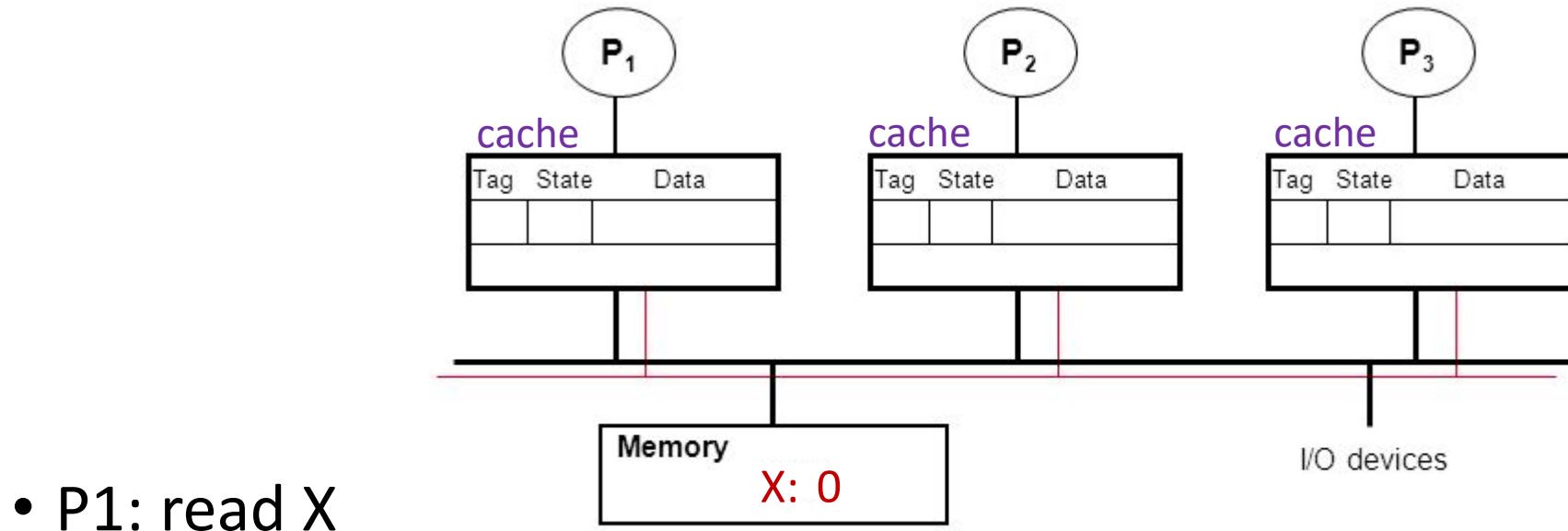
Physics | Concurrency

$F = ma \sim coherence$

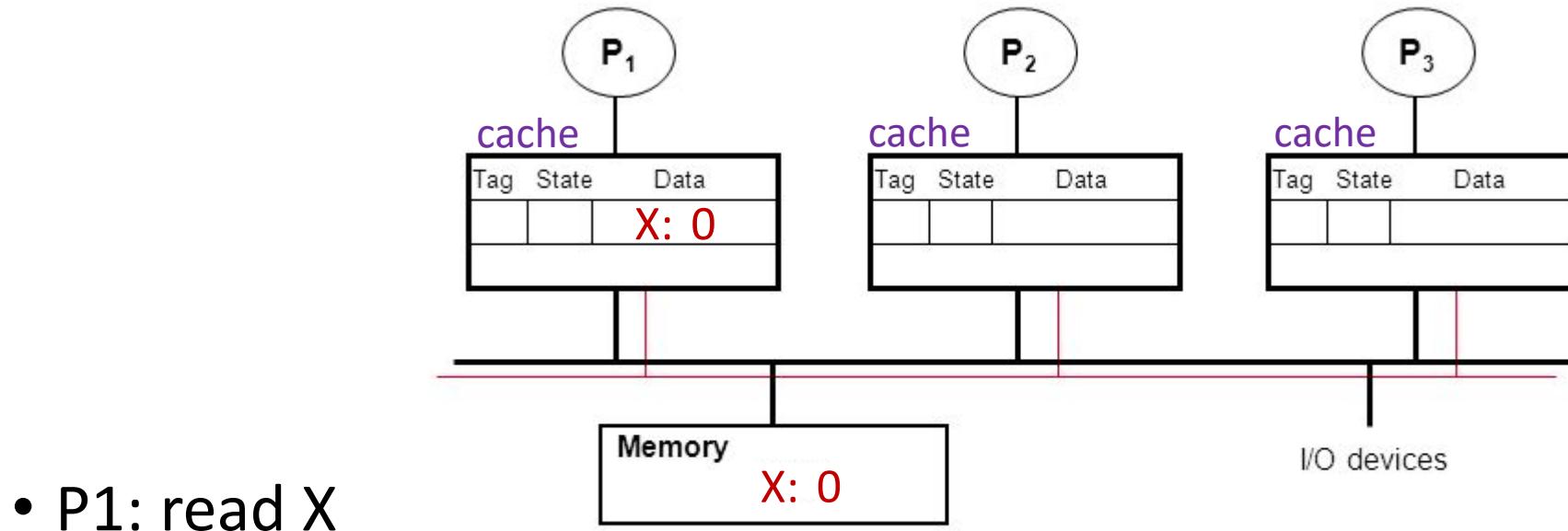
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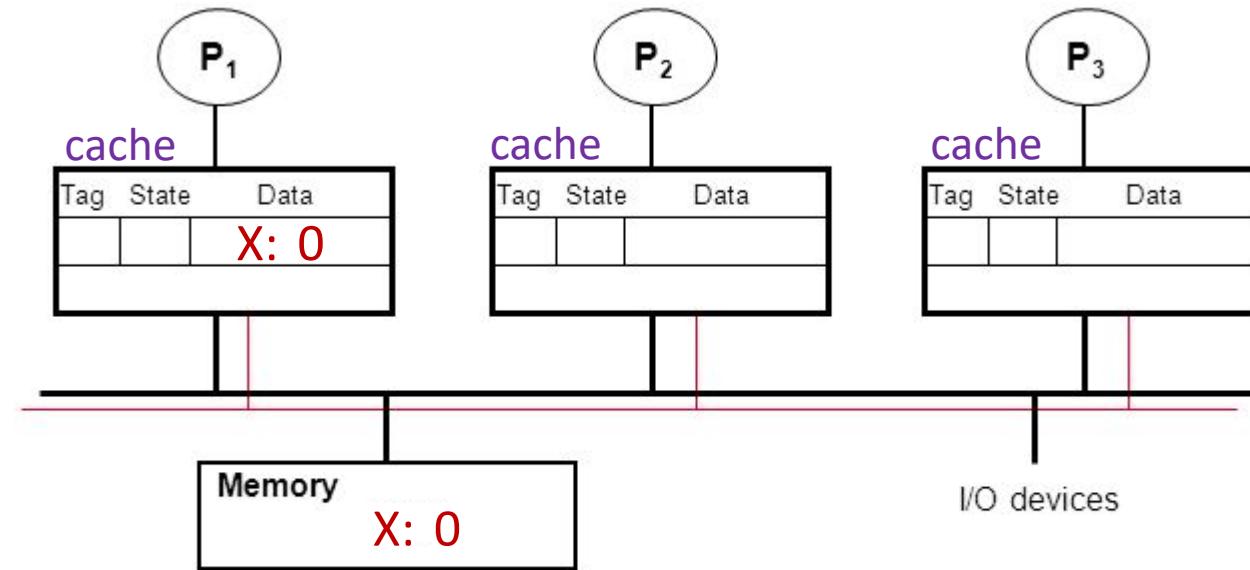
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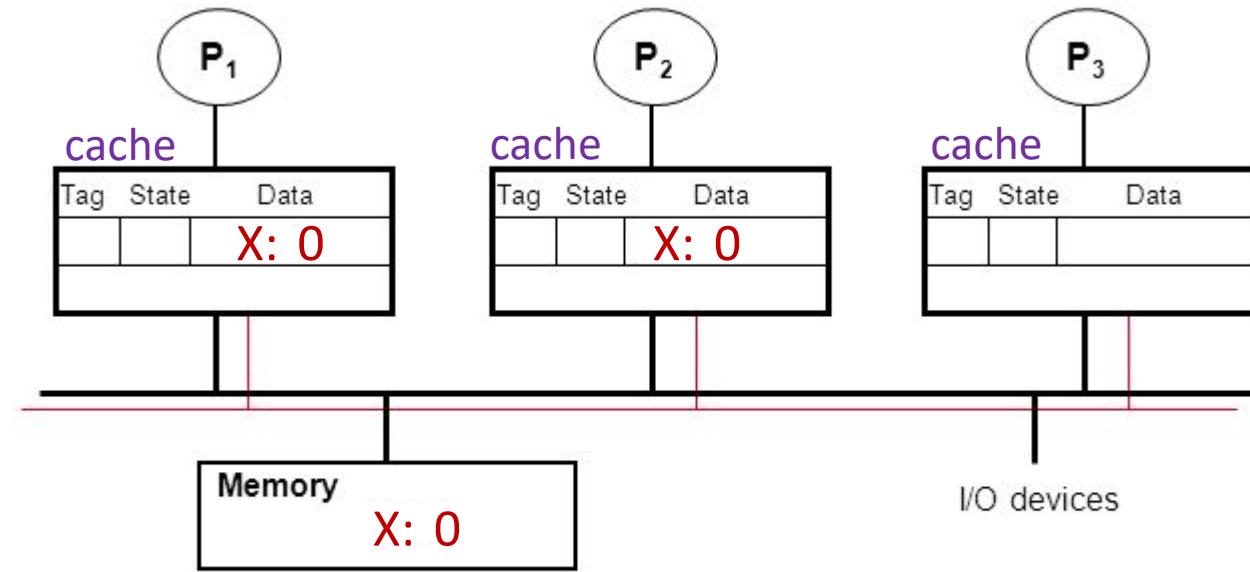


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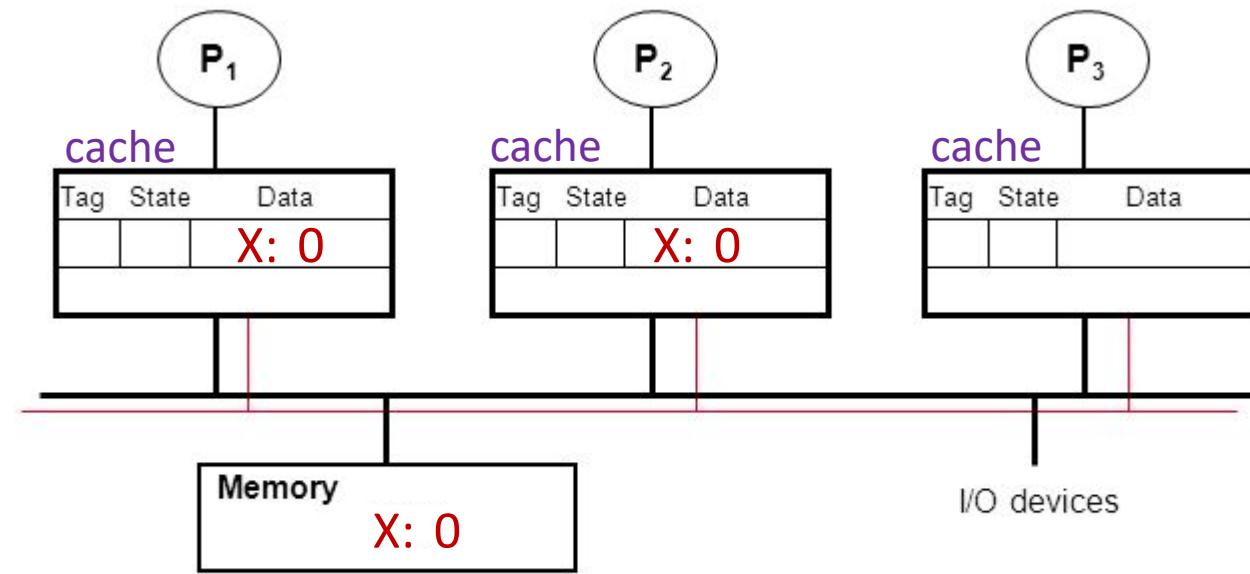
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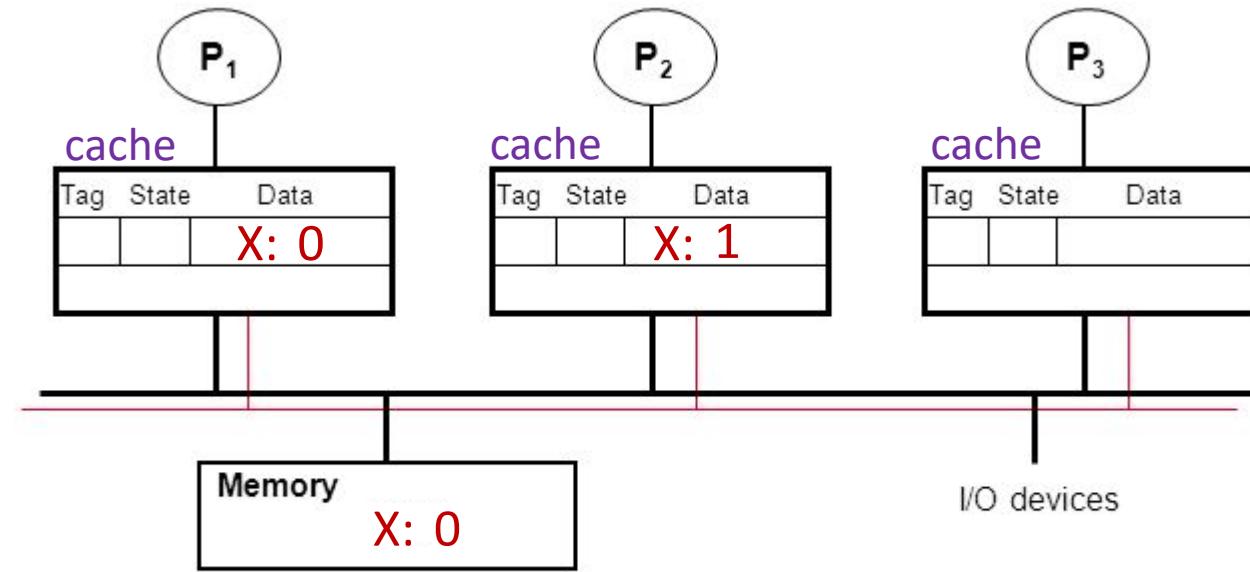
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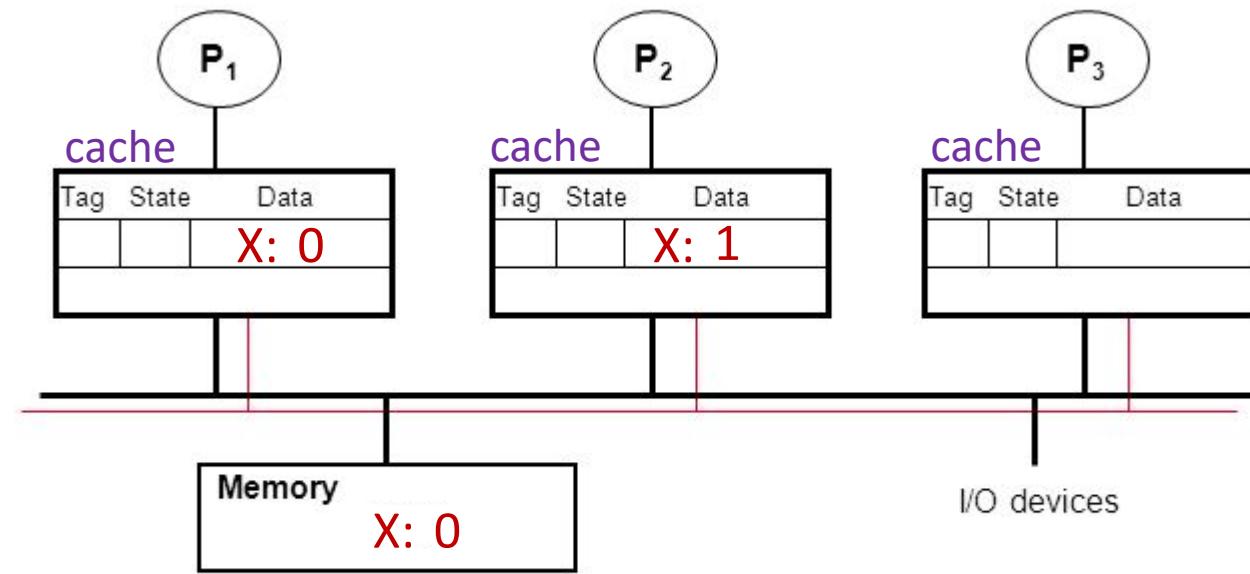
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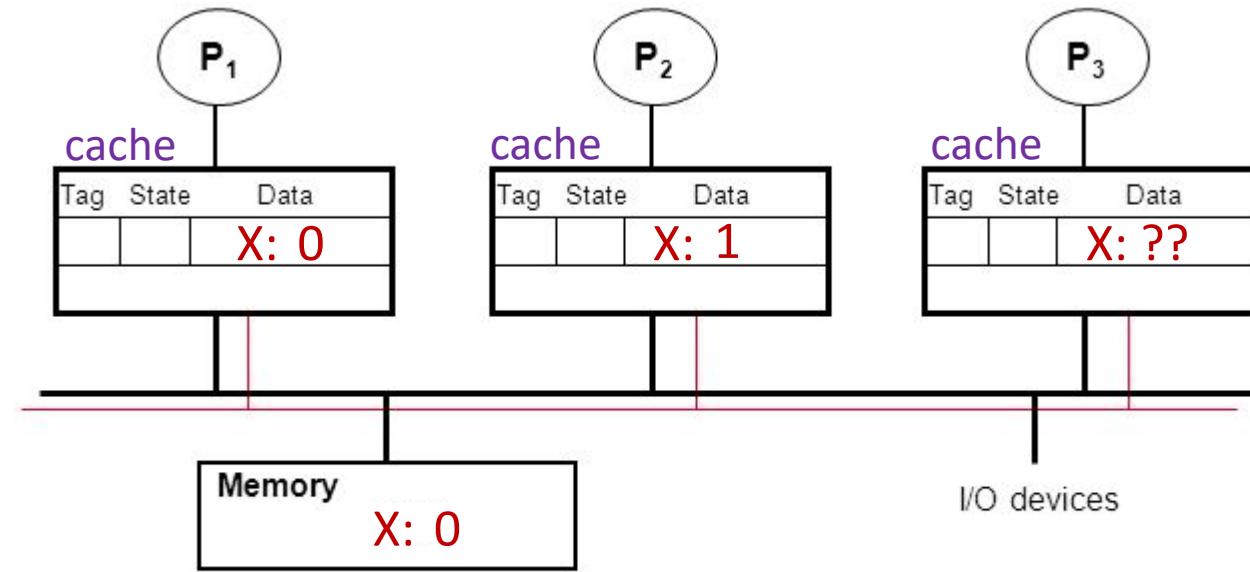
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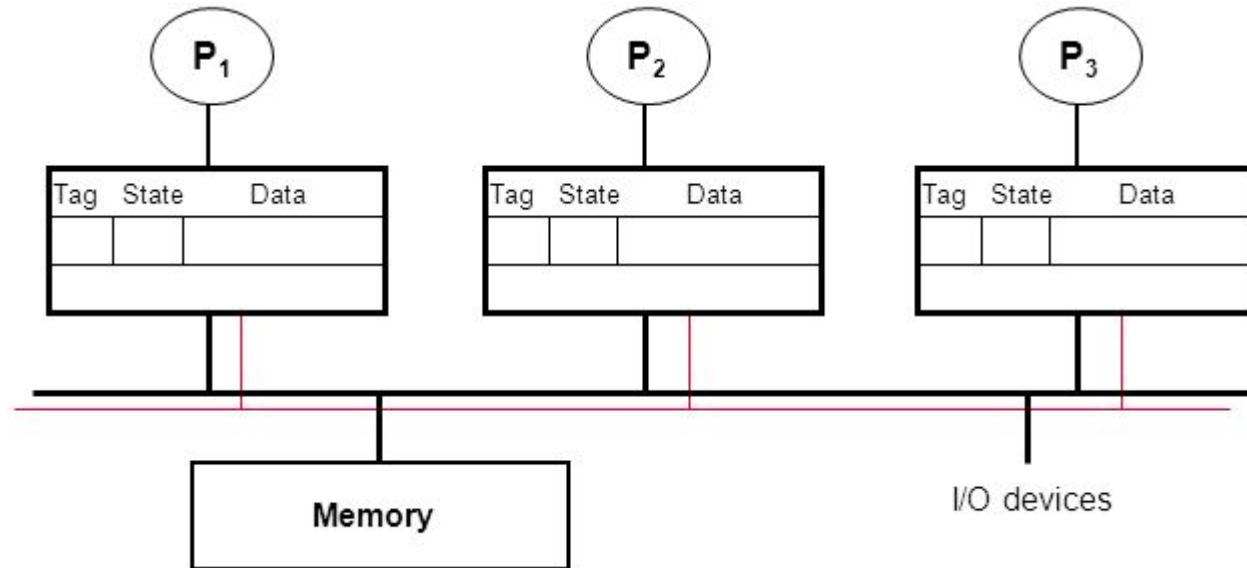
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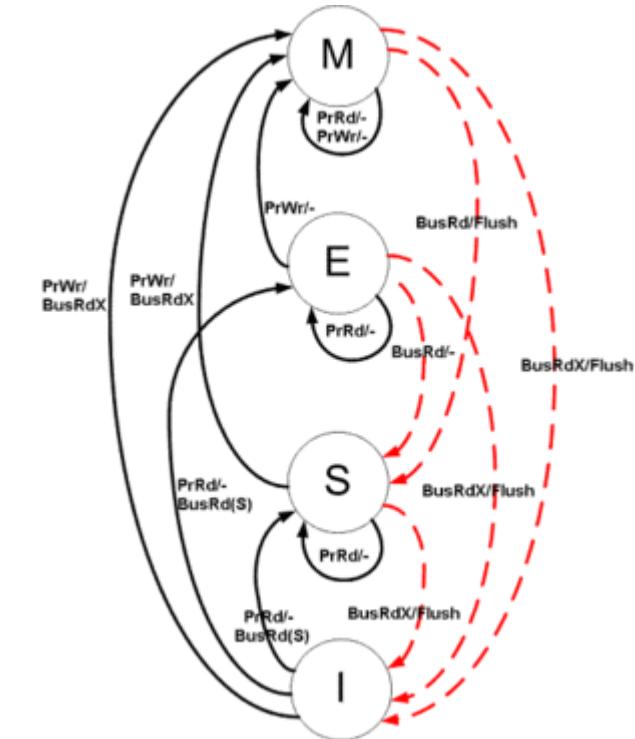
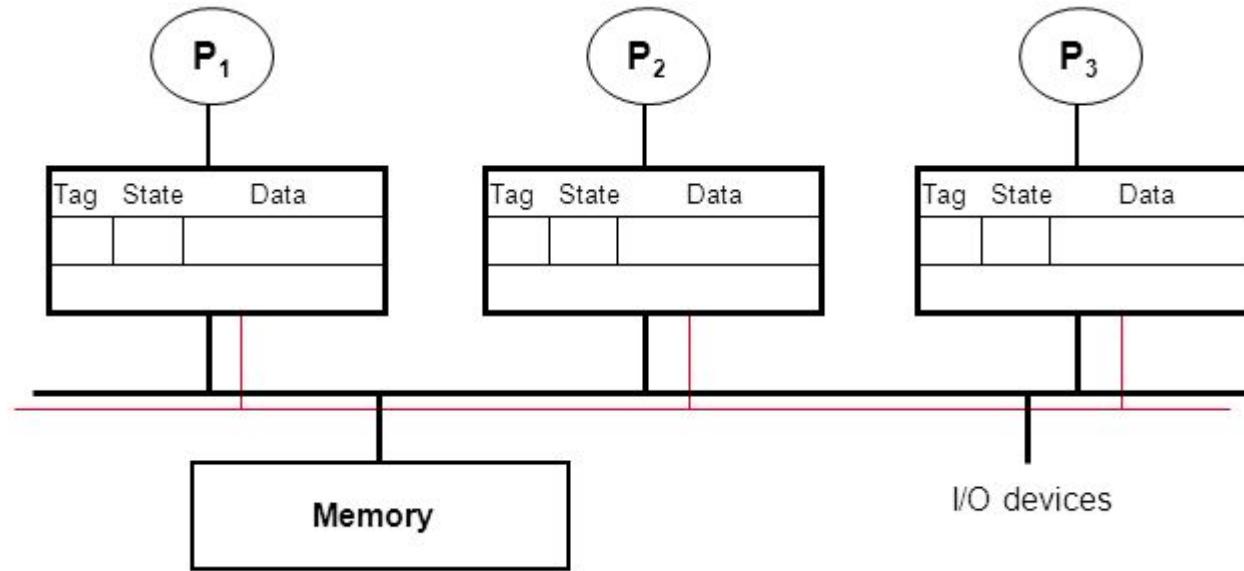


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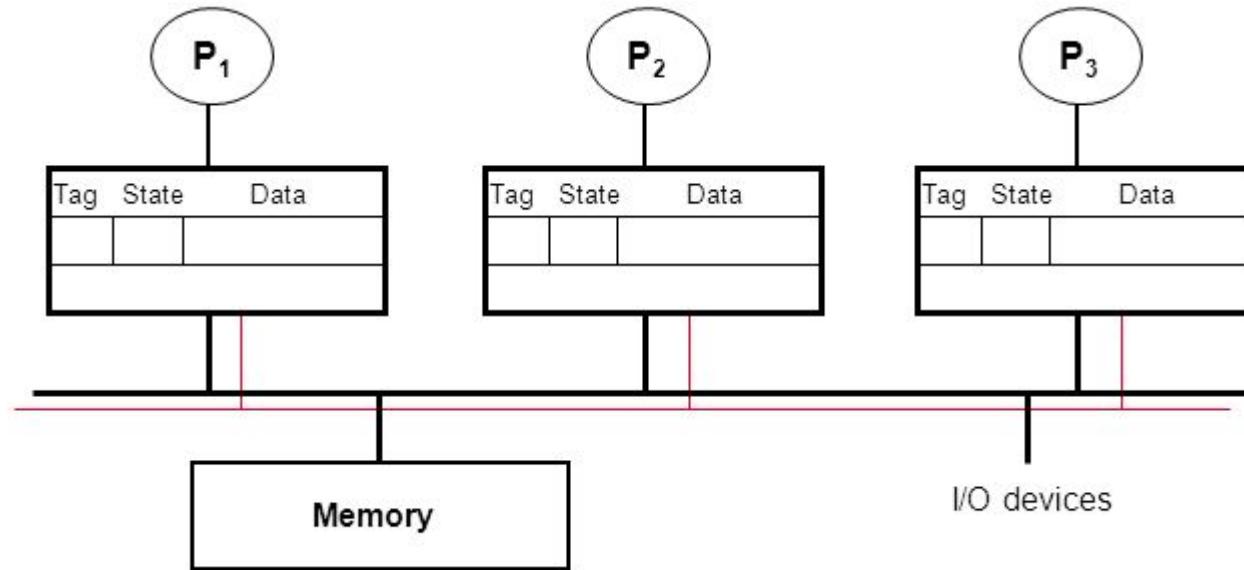
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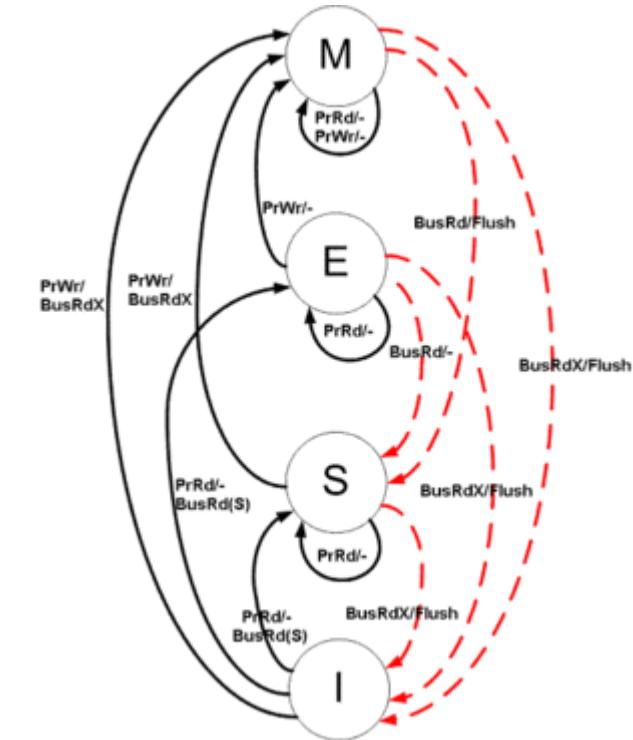
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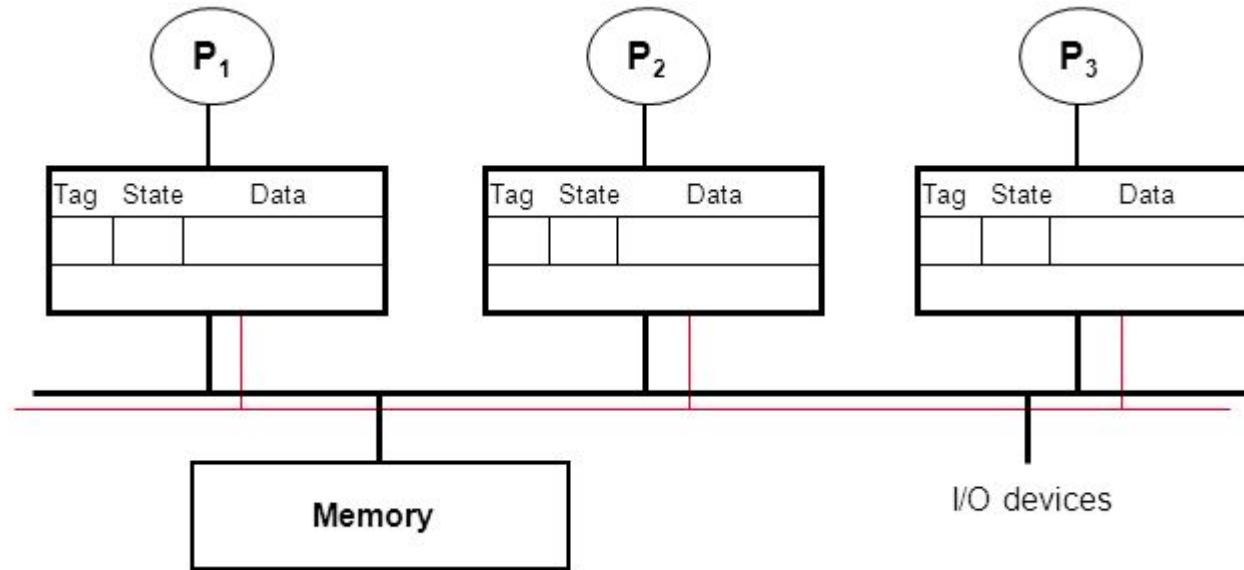
Multiprocessor Cache Coherence



Each cache line has a state (M, E, S, I)

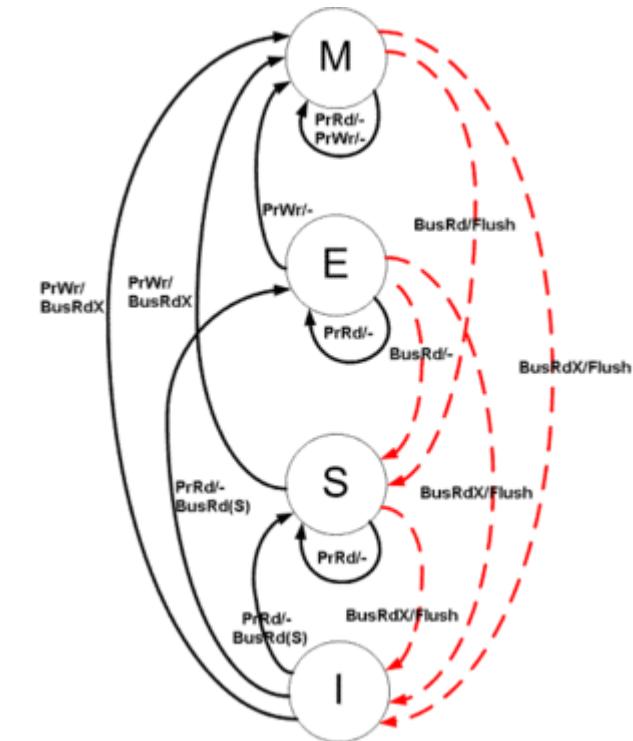


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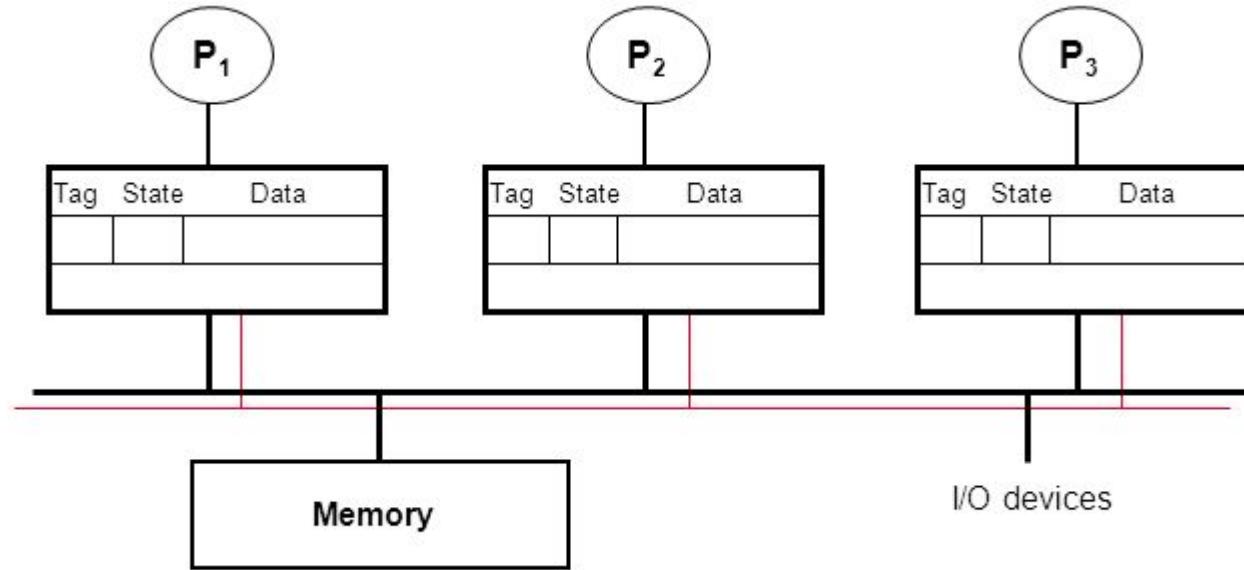


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- Processors “snoop” bus to maintain states

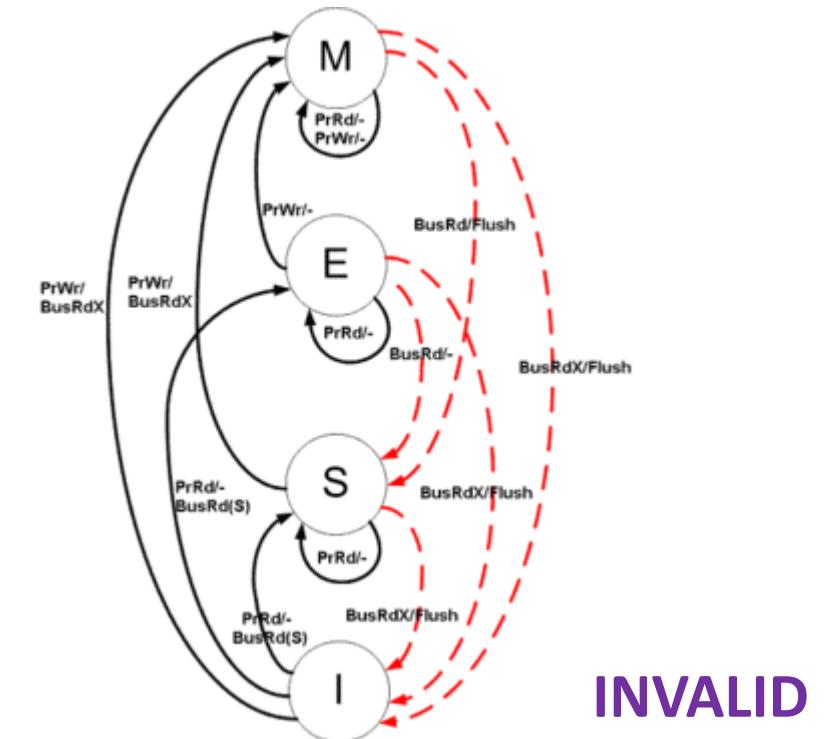


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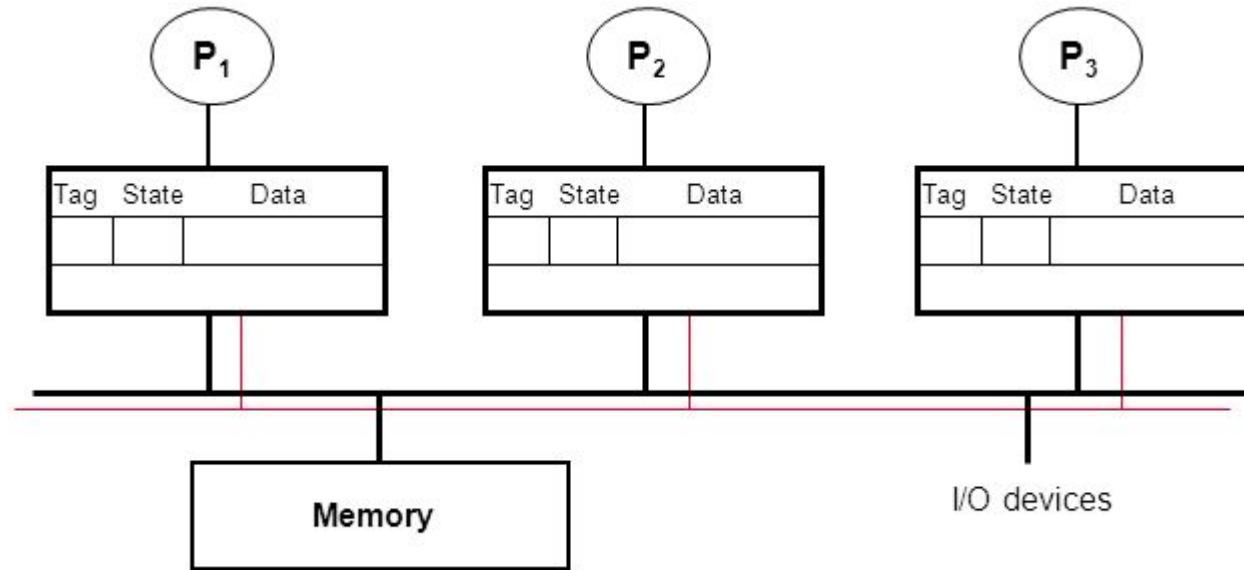


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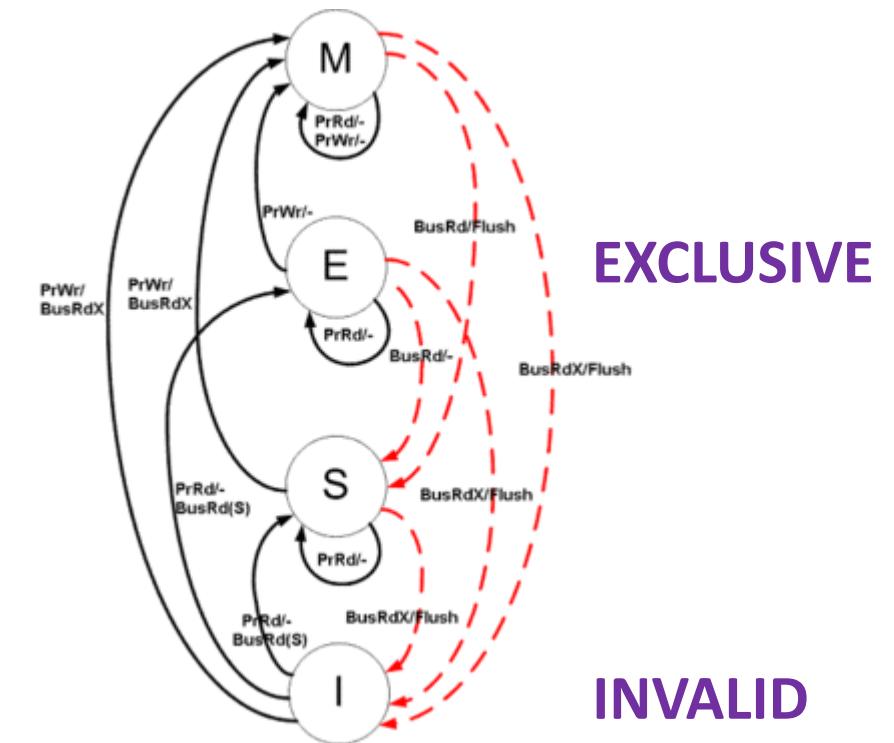


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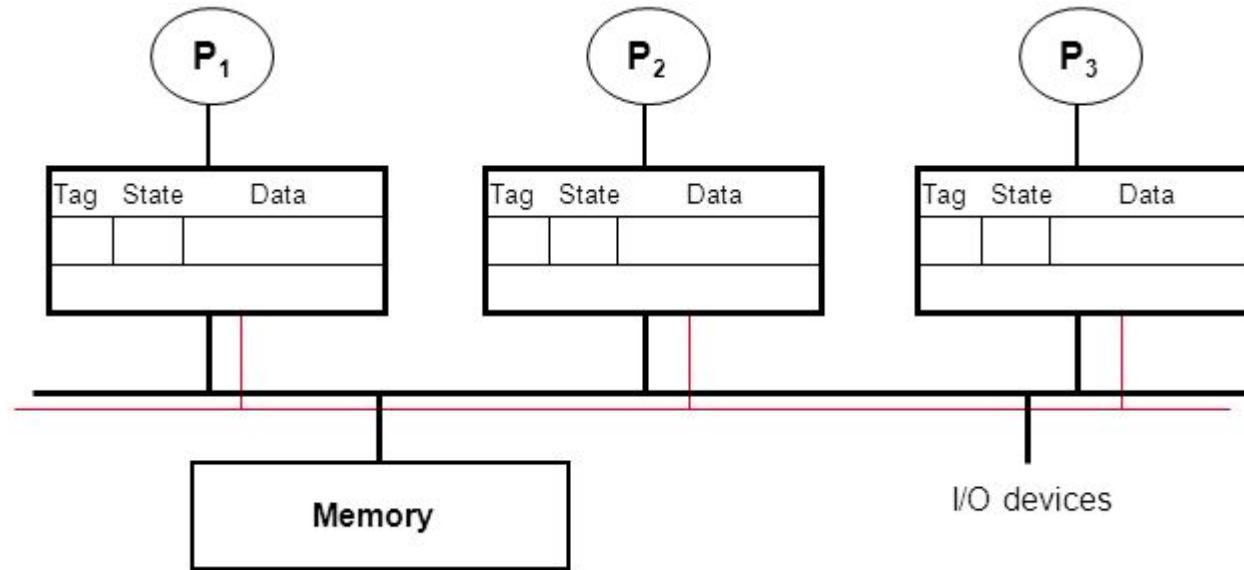


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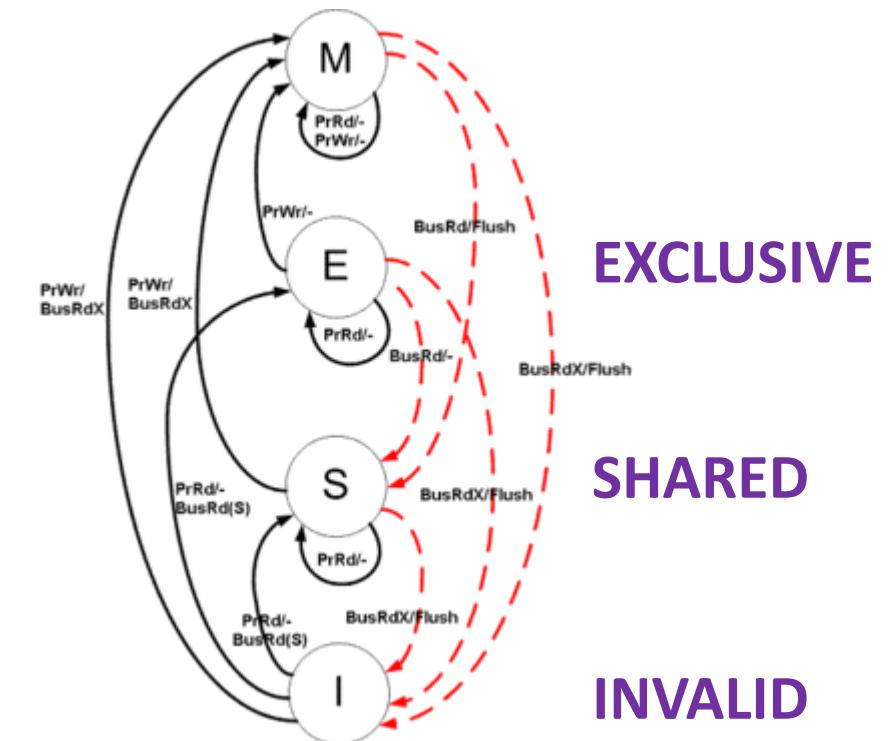


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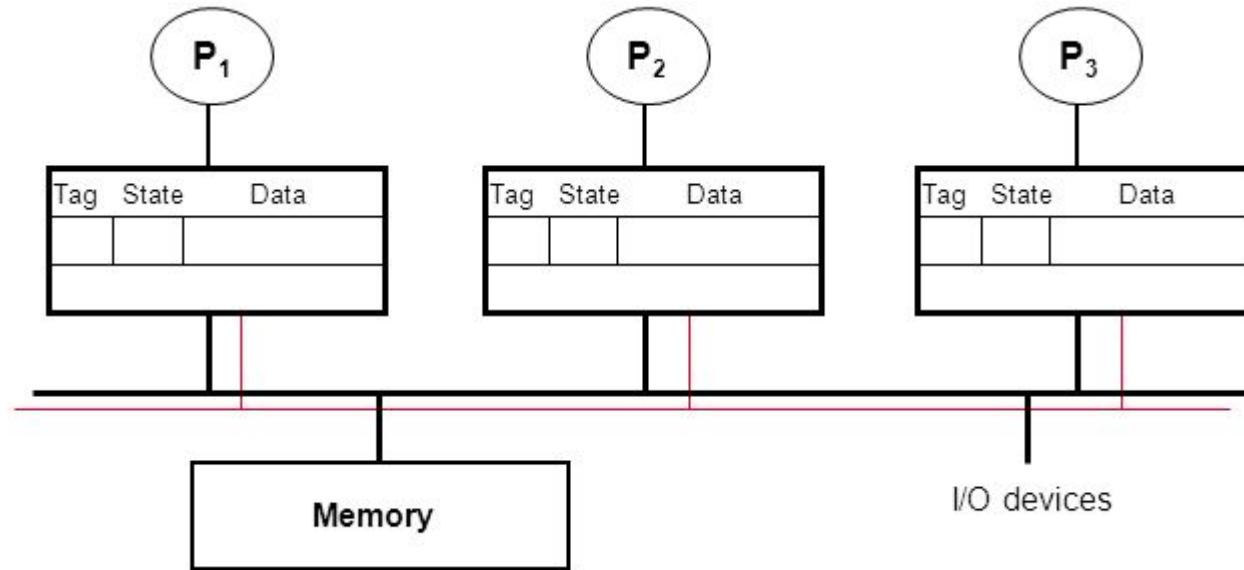


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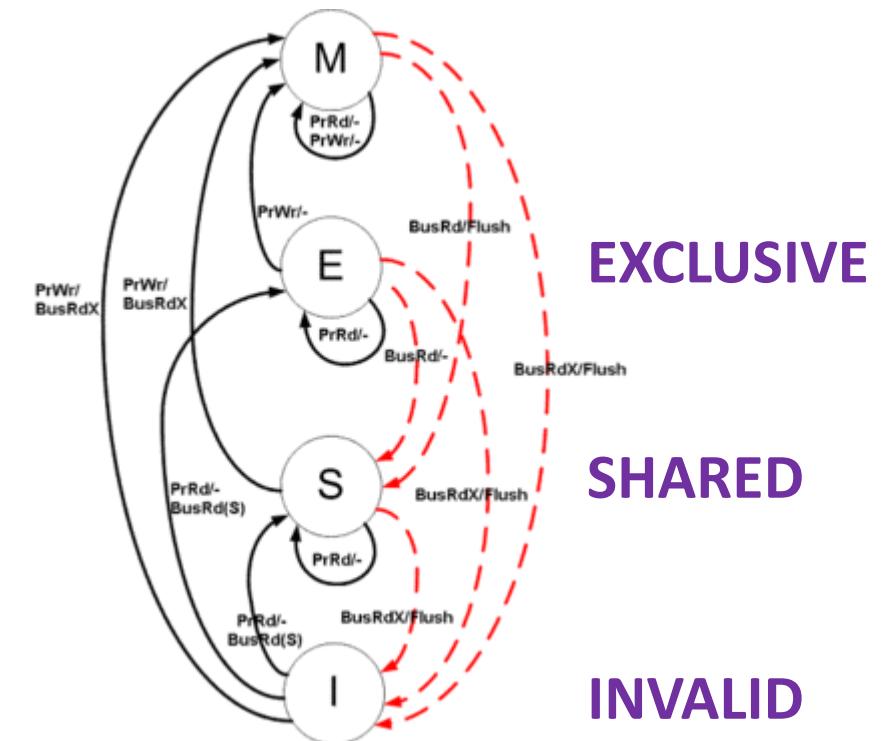


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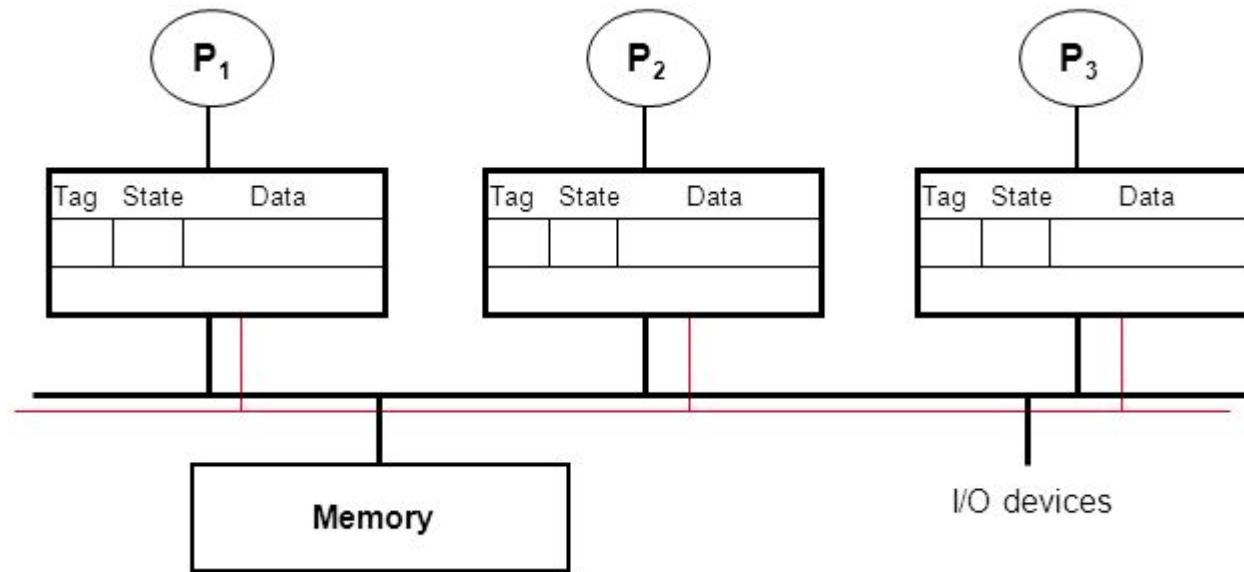


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- Write → ‘M’ → single copy → lots of cache coherence traffic

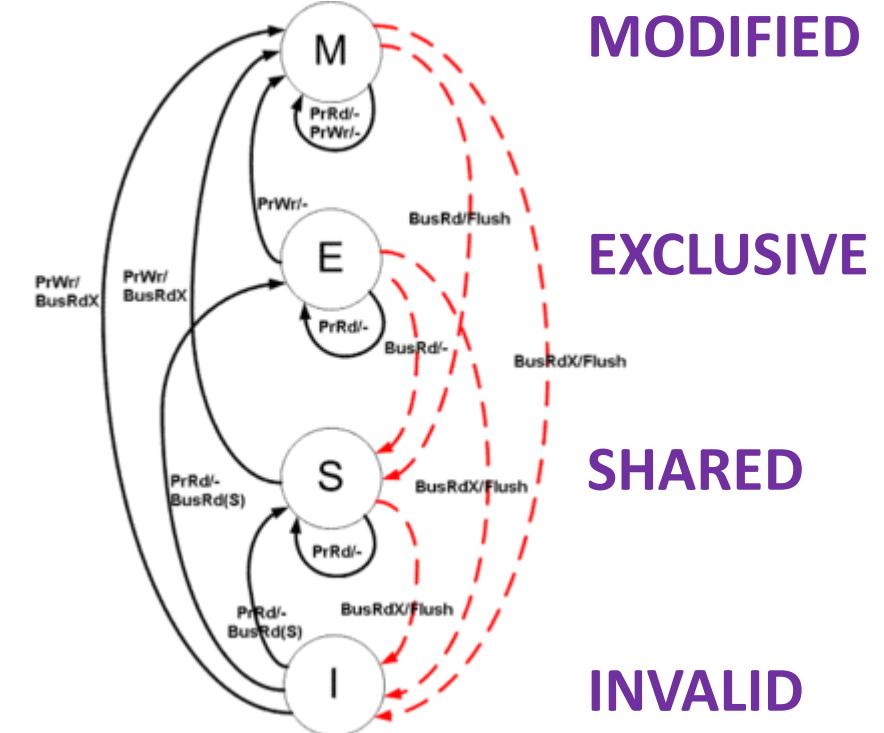


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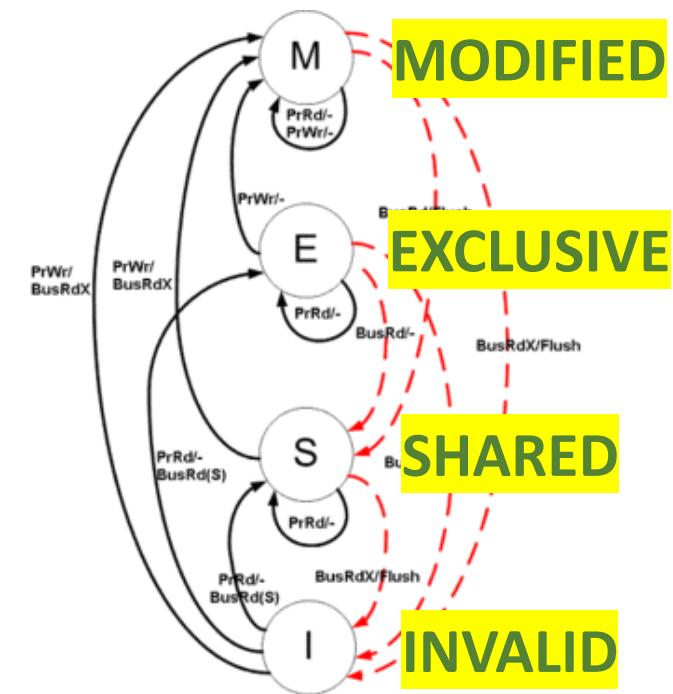
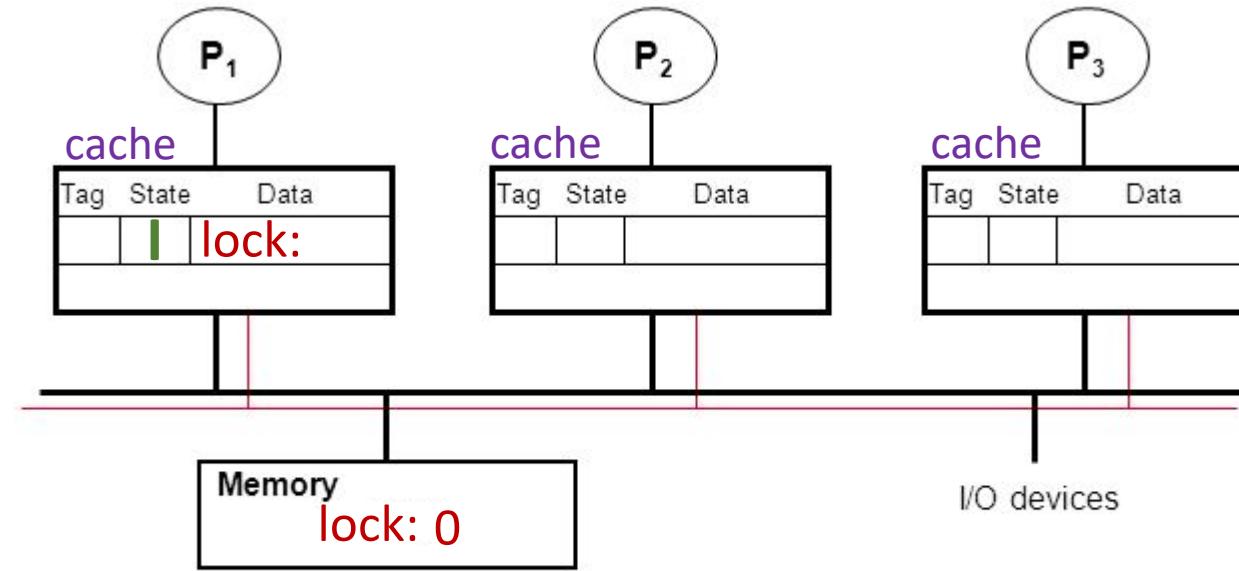


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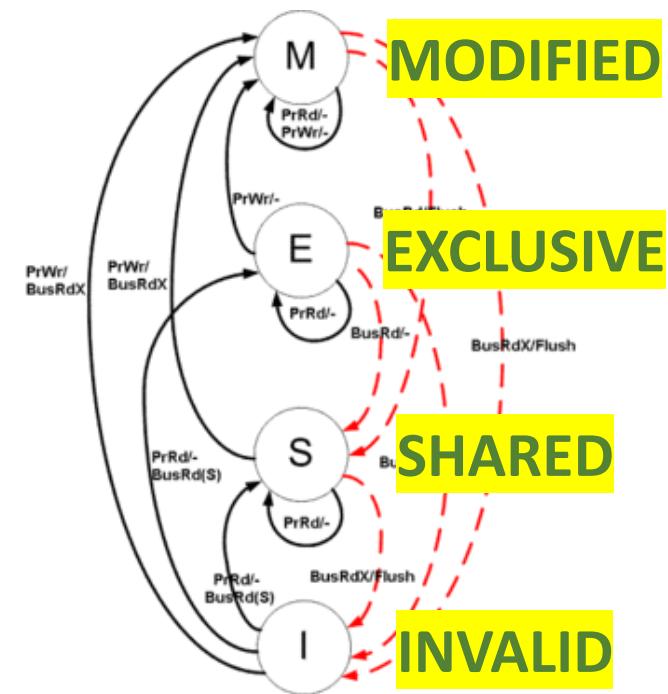
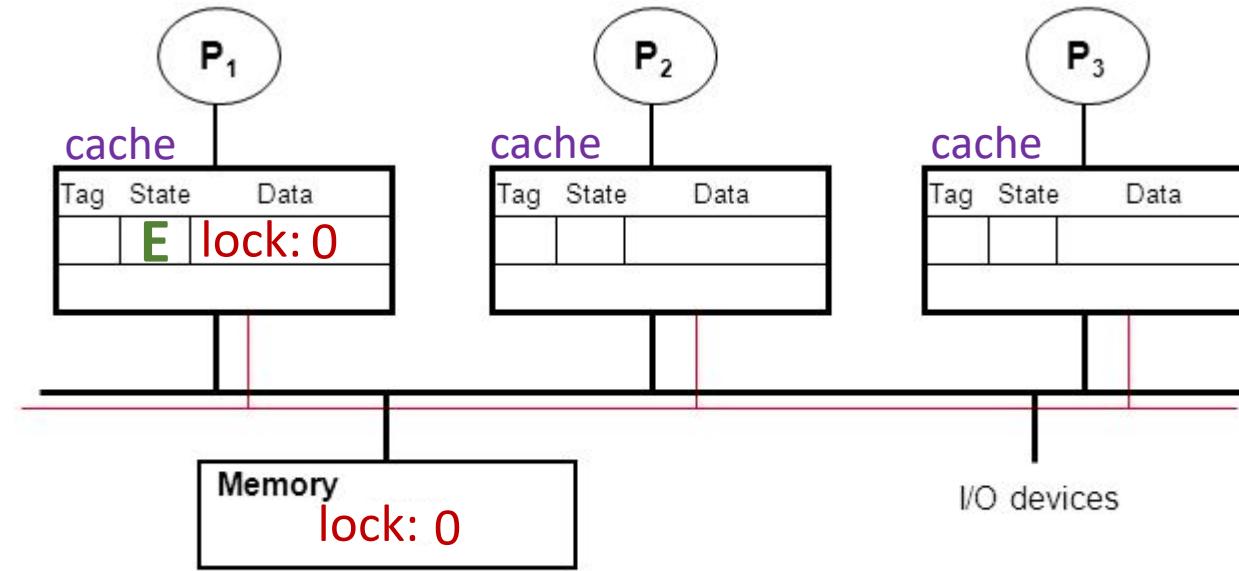
Cache Coherence: single-thread



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```
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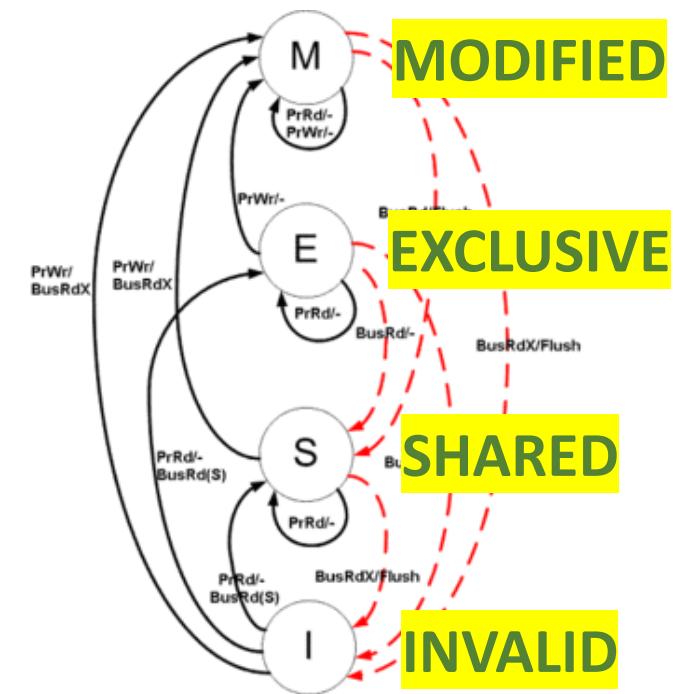
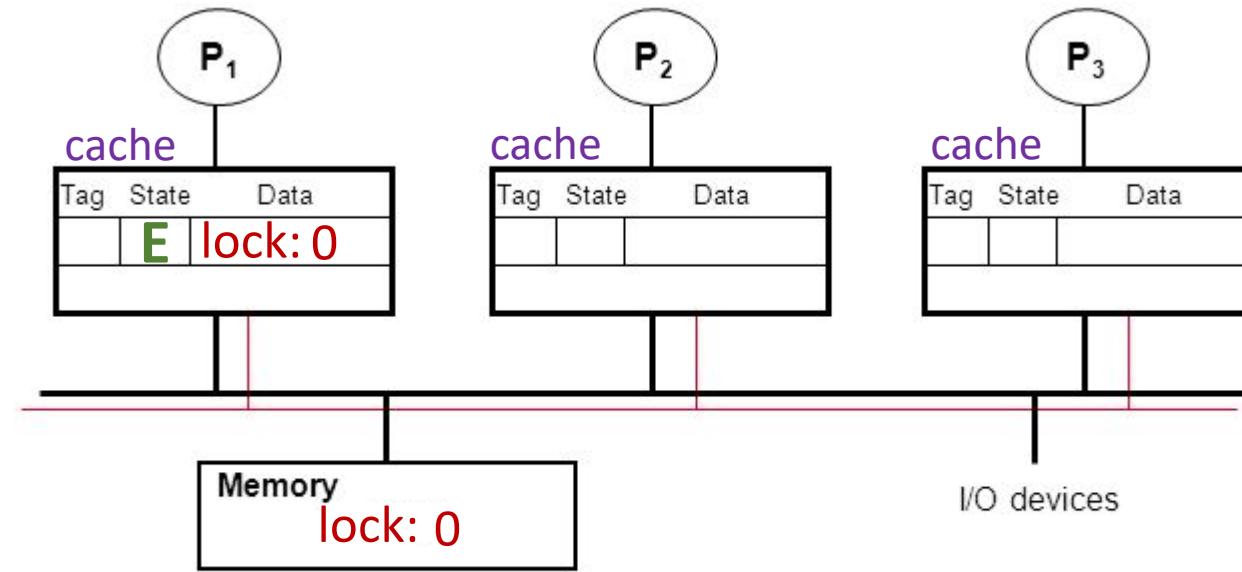
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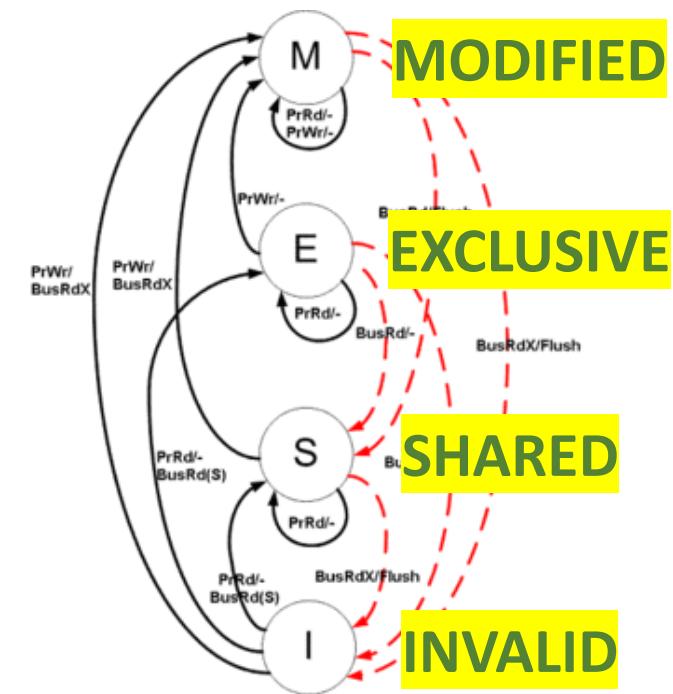
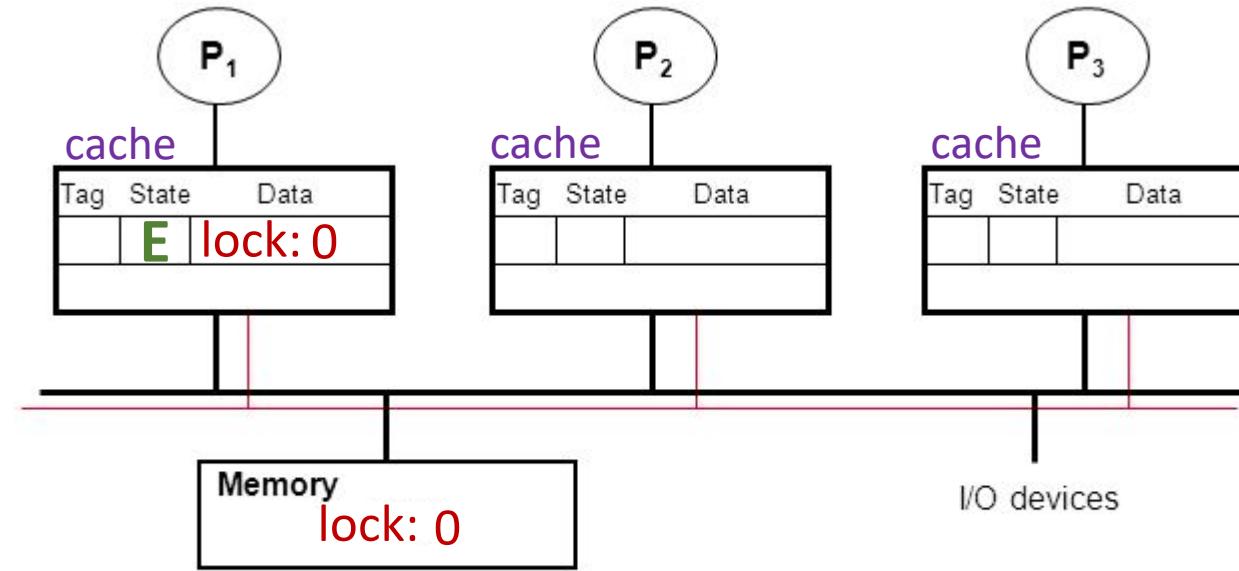


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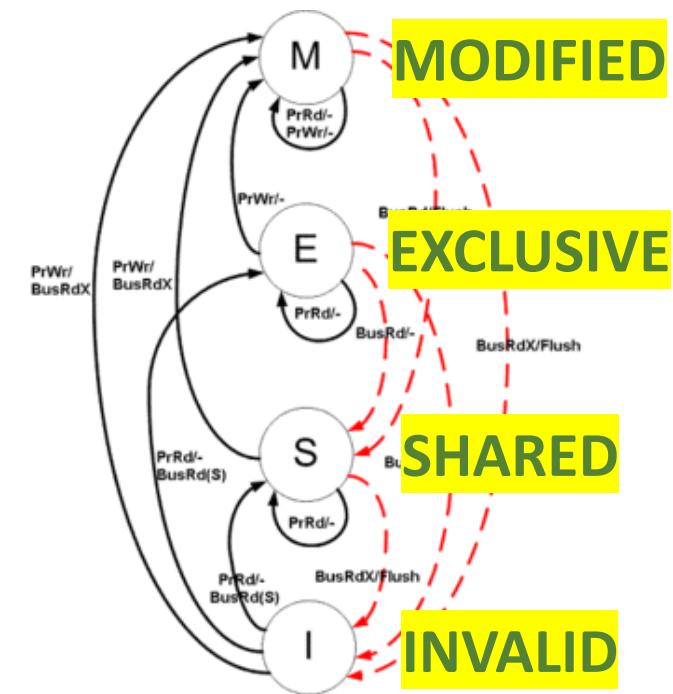
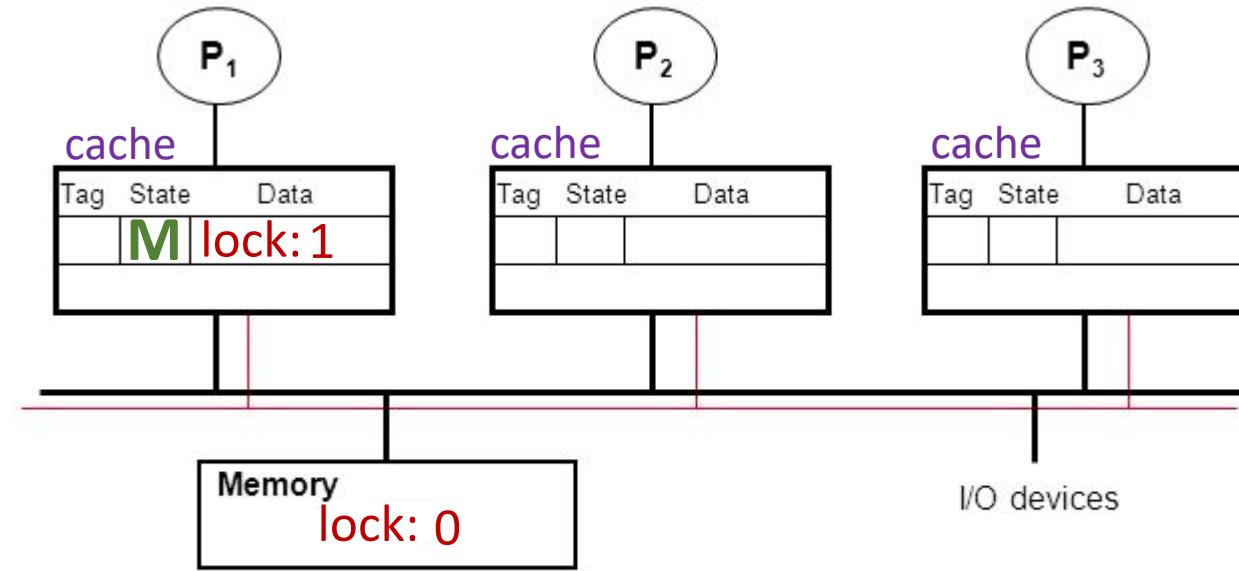


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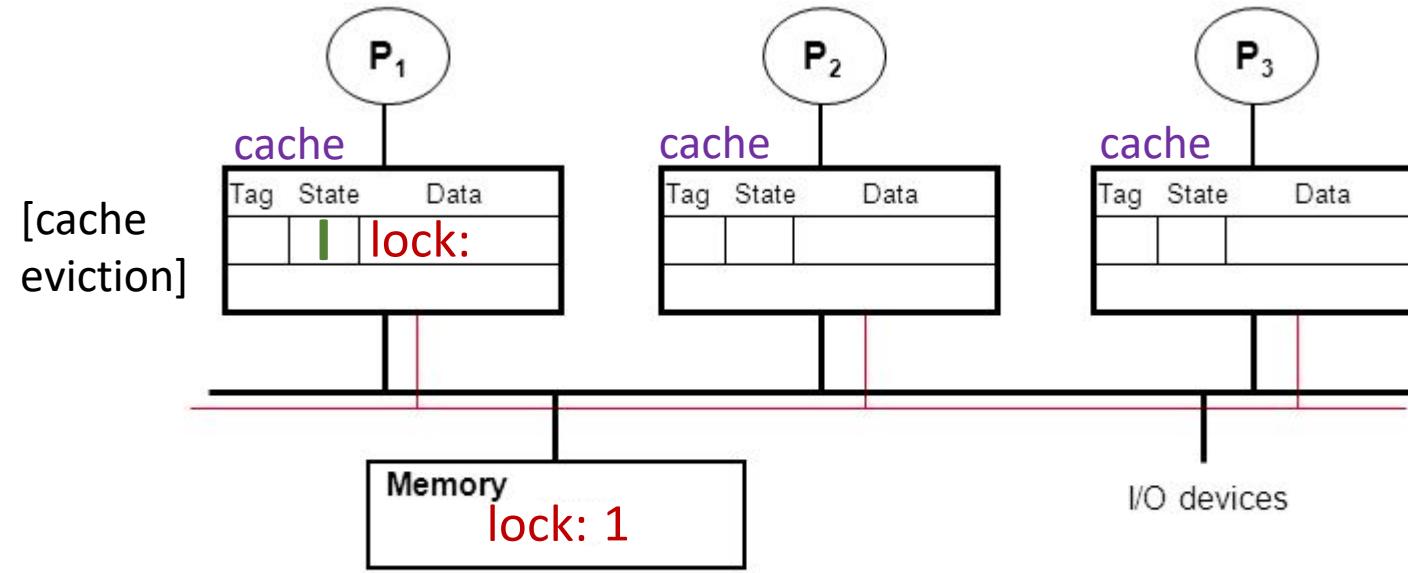


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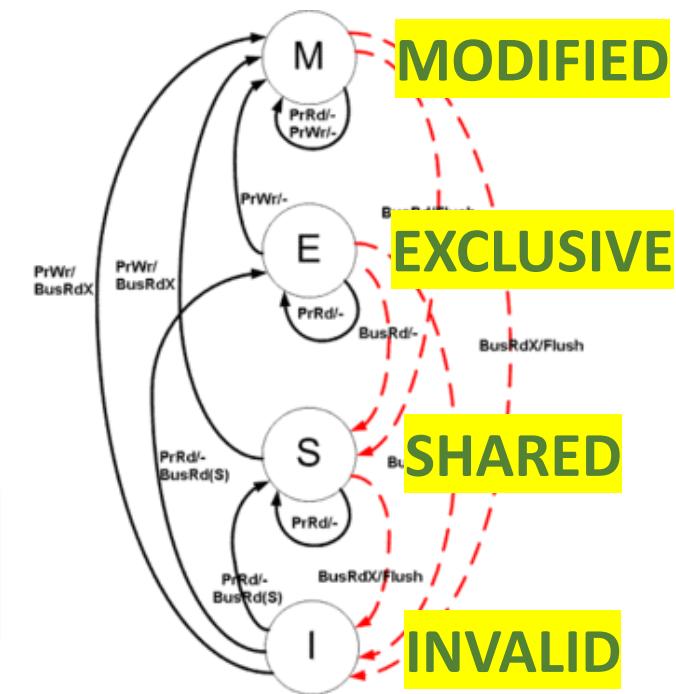
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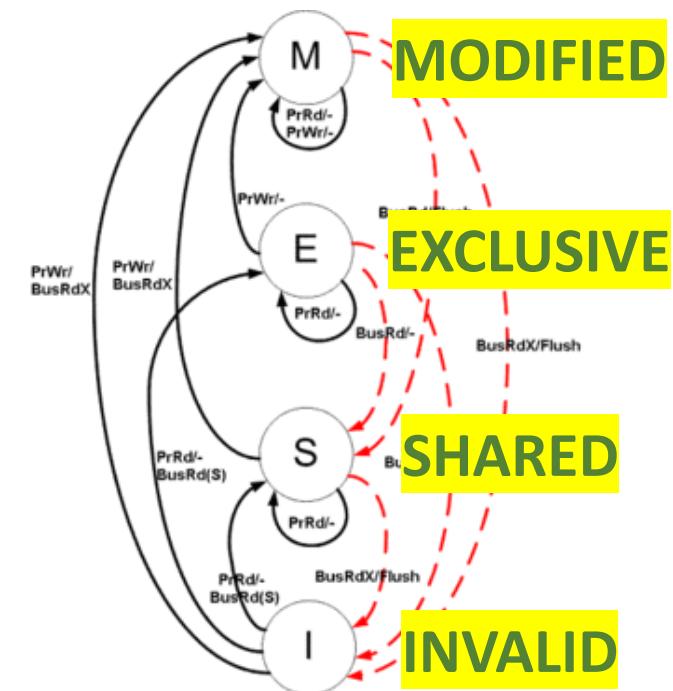
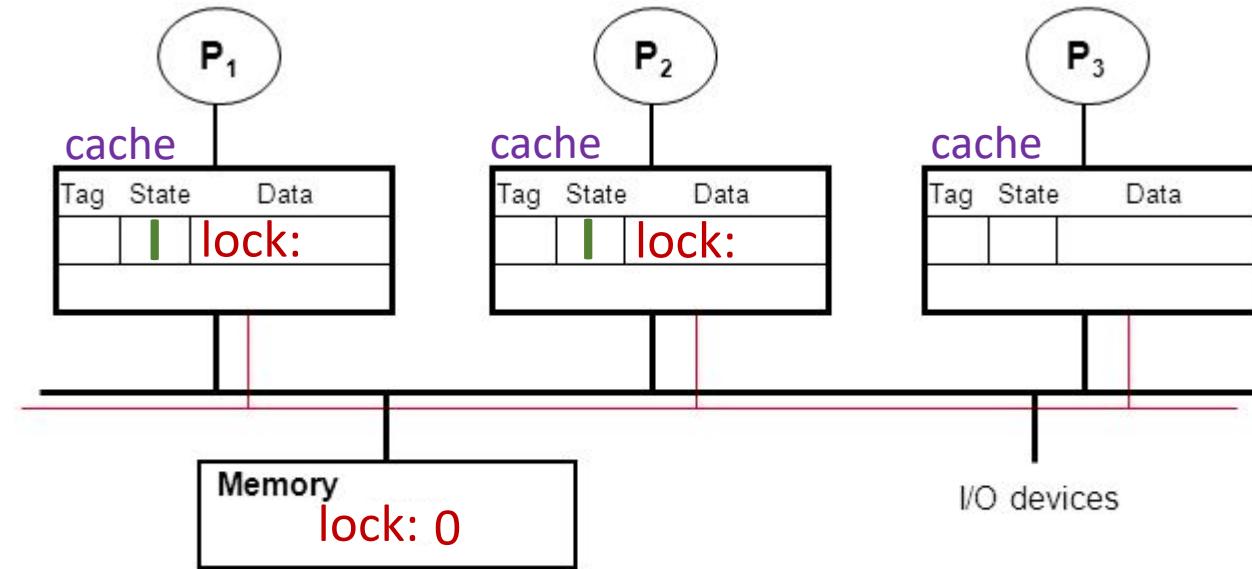
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Lock Implementation & Cache Coherence



Cache Coherence Action Zone



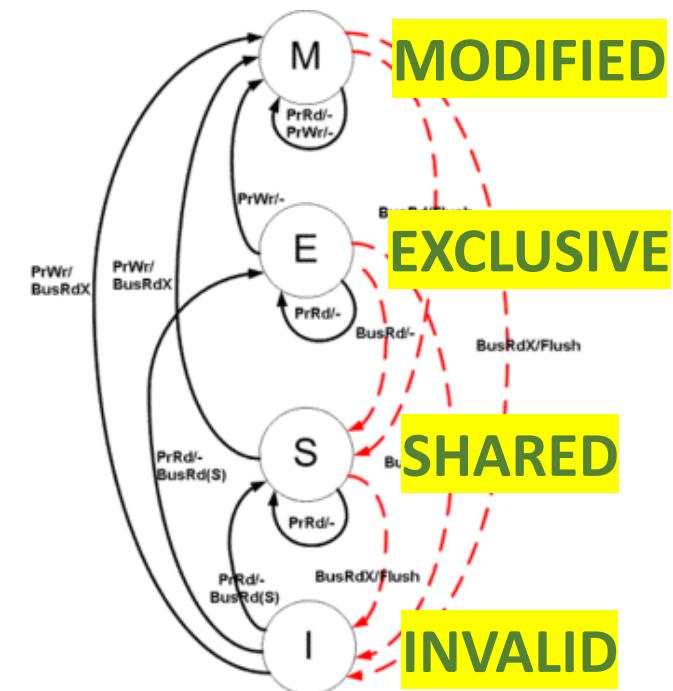
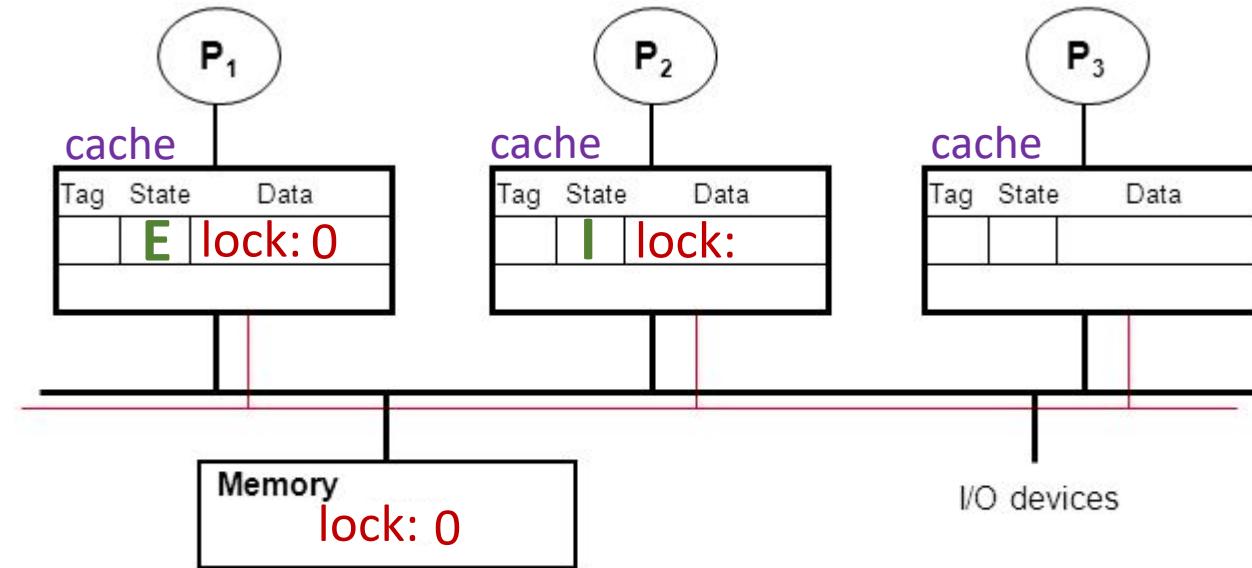
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Cache Coherence Action Zone



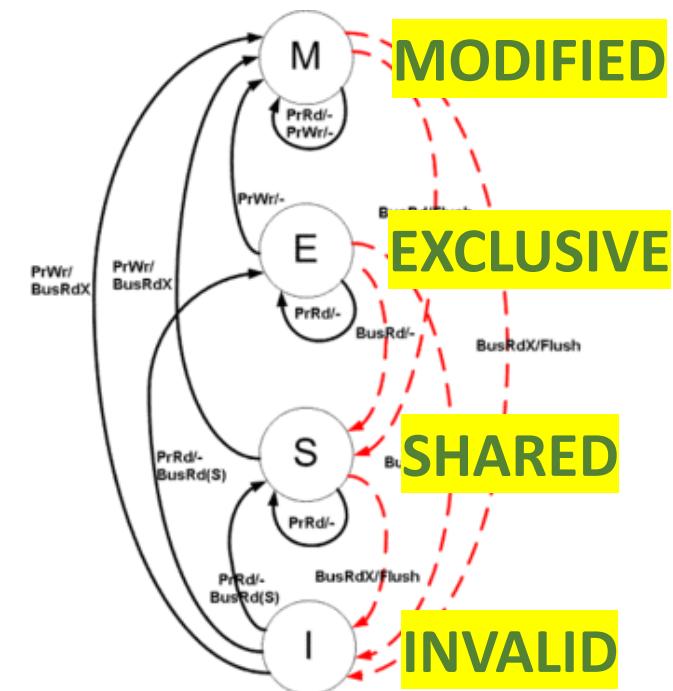
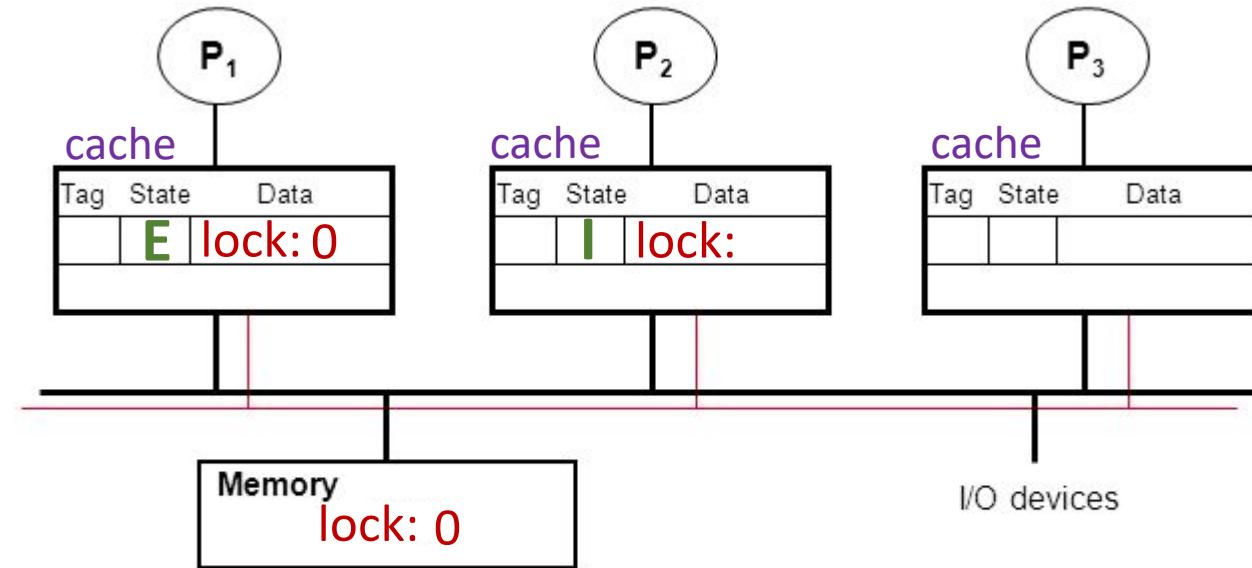
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Cache Coherence Action Zone



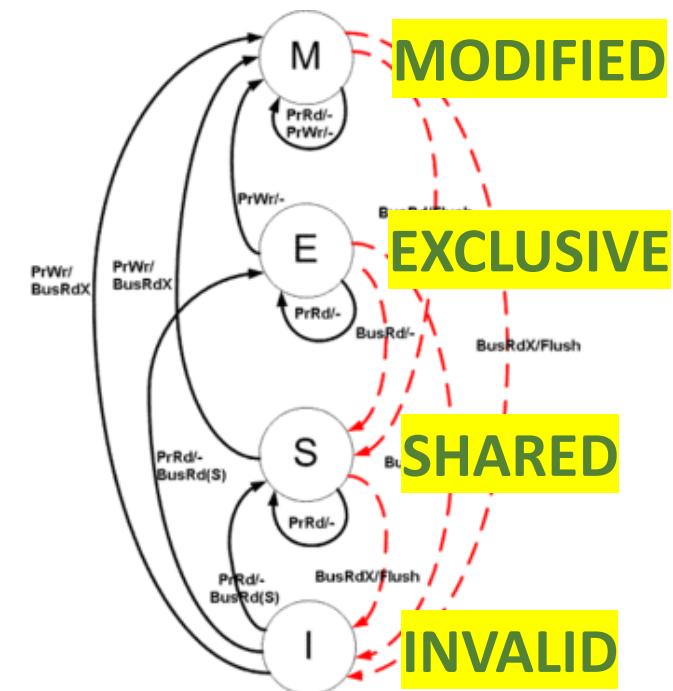
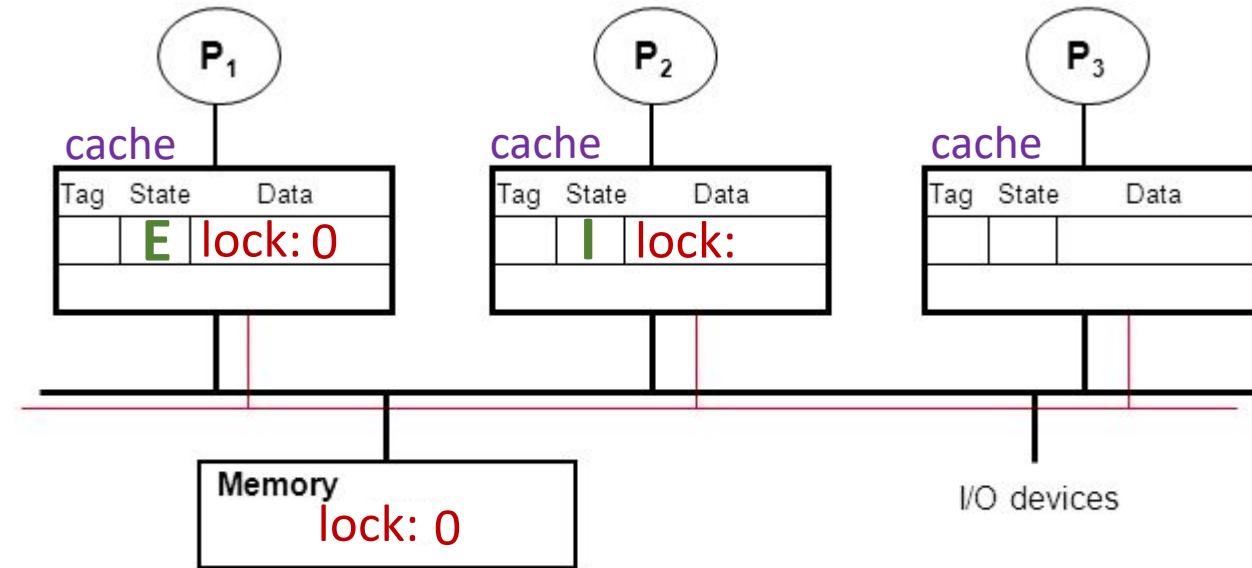
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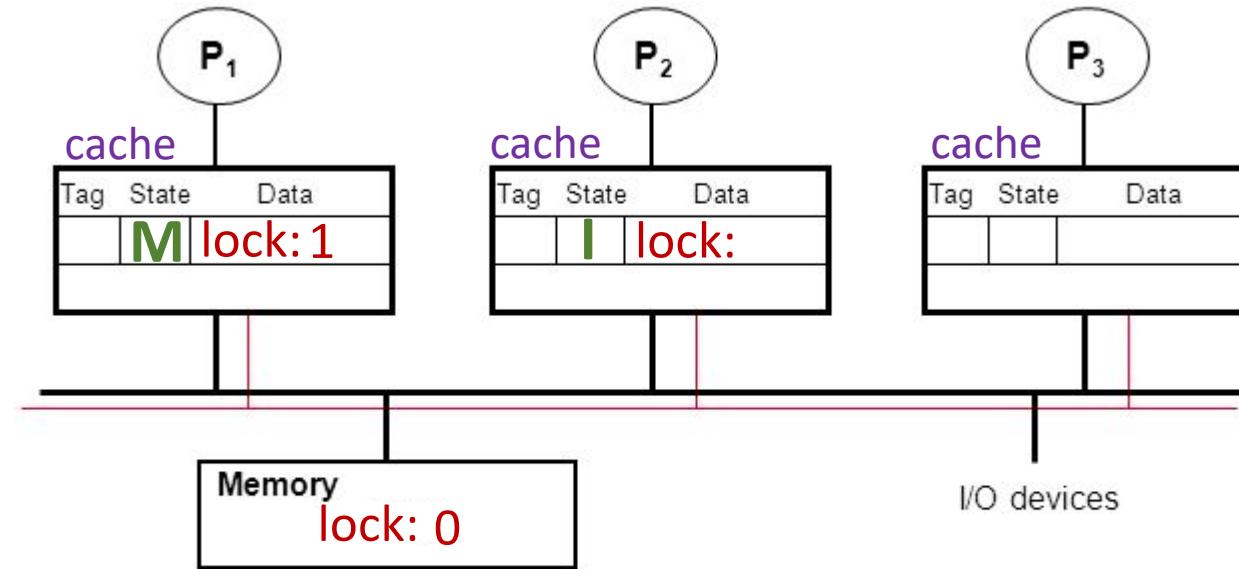
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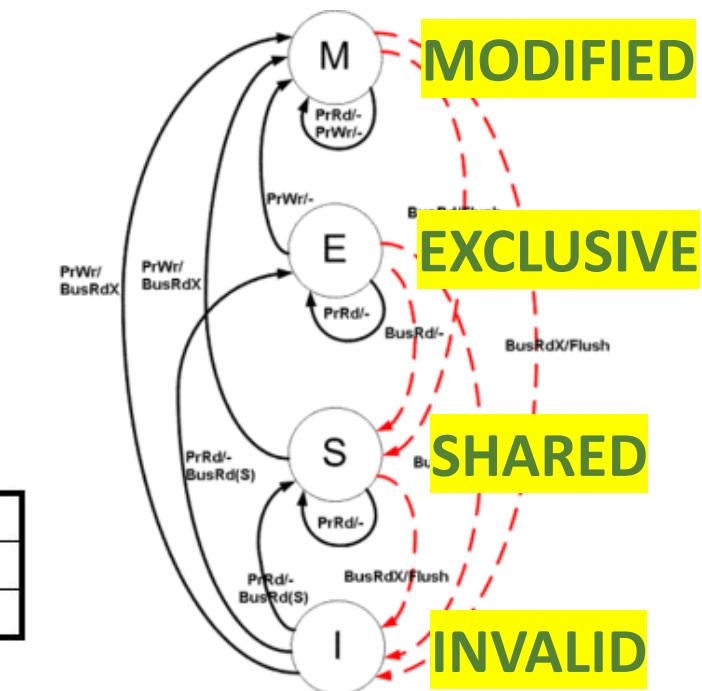
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Lock Implementation & Cache Coherence

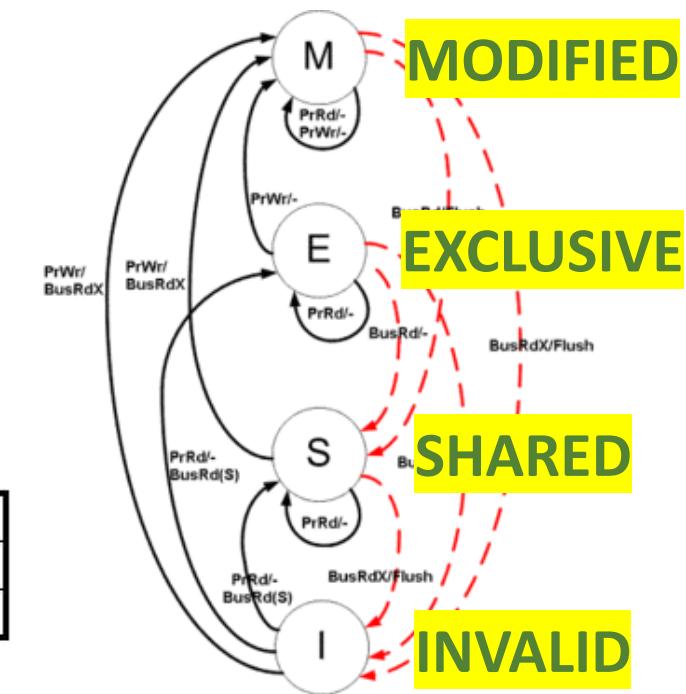
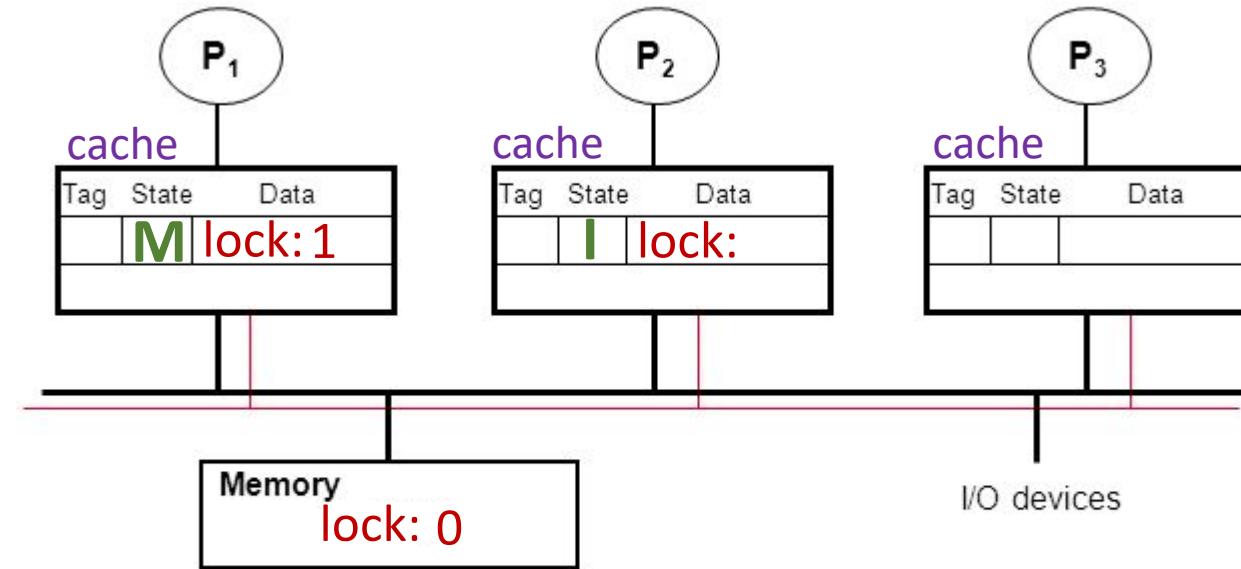


Cache Coherence Action Zone



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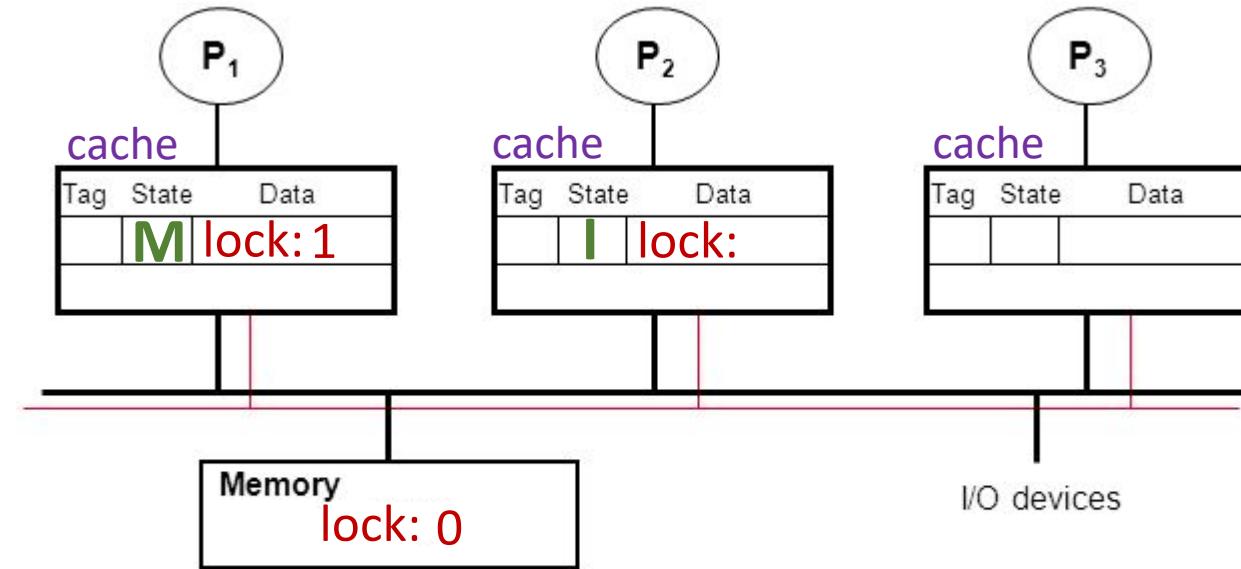
Lock Implementation & Cache Coherence

Cache Coherence Action Zone



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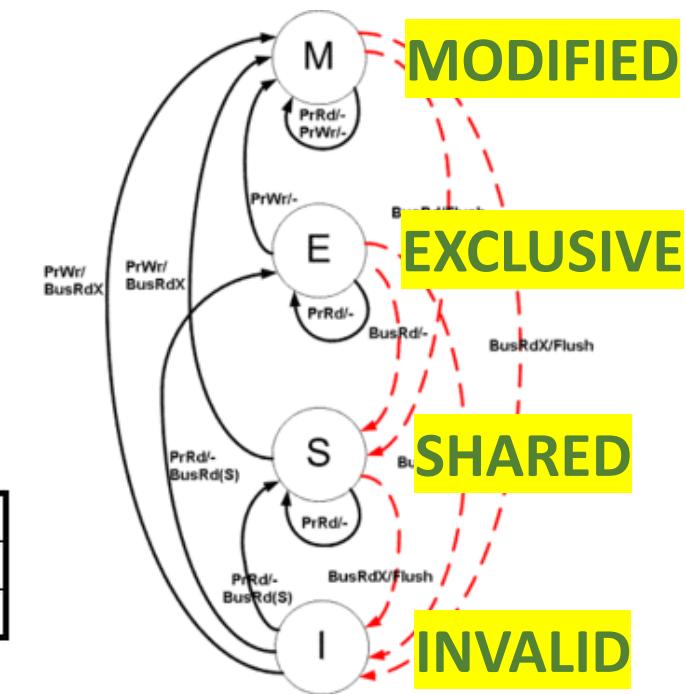
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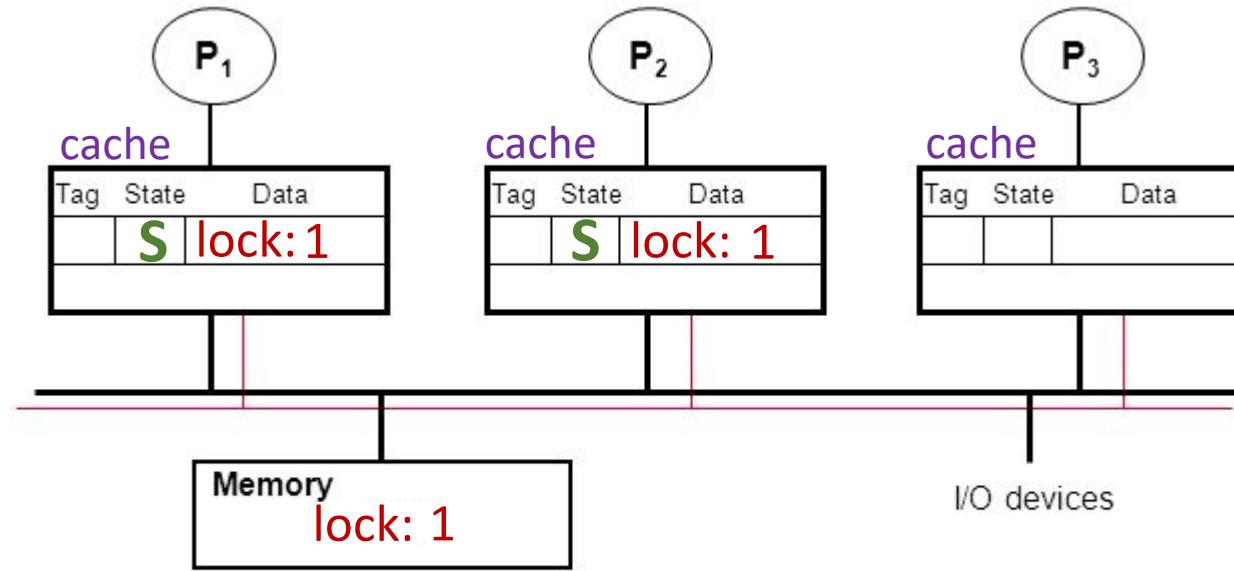


Cache Coherence Action Zone



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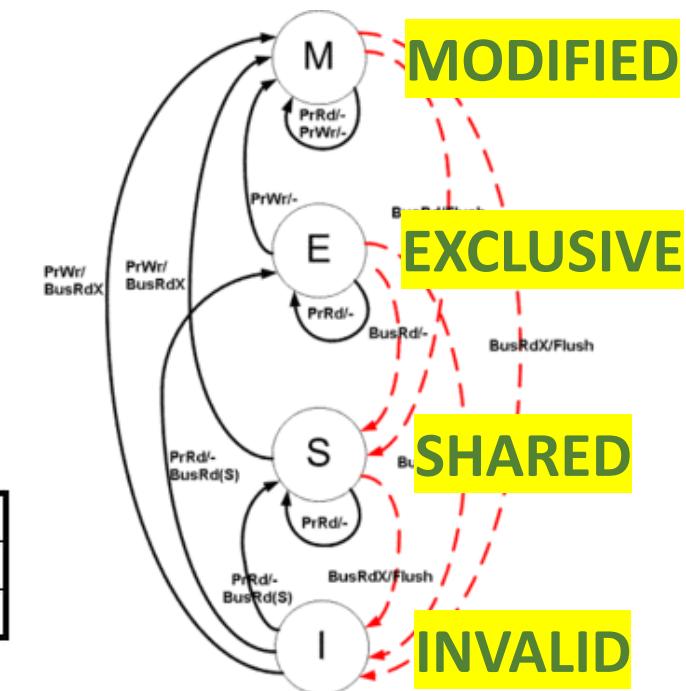
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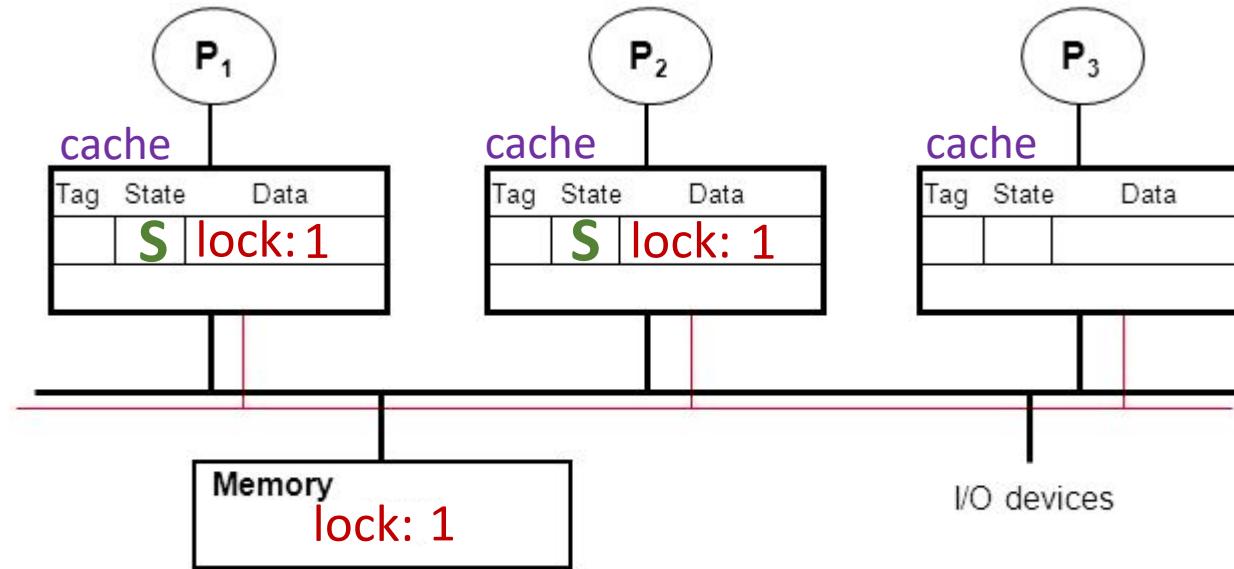


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try: load lock, R0
    test R0
    bnz try
    store lock, 1
}
```

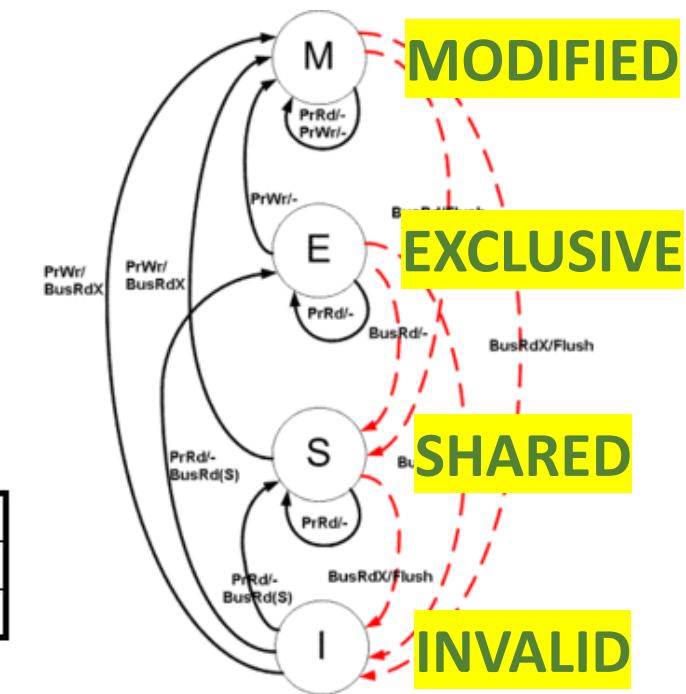


Lock Implementation & Cache Coherence



```
// (straw-person lock impl)
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lock() {
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    bnz try
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}
```

10

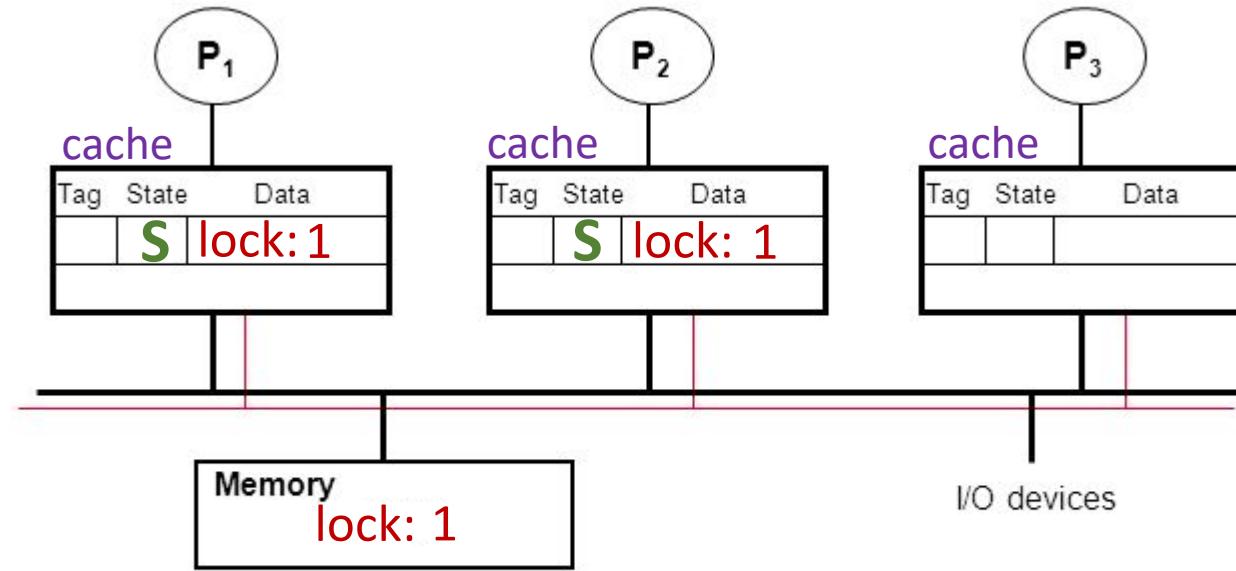


Cache Coherence Action Zone



P1

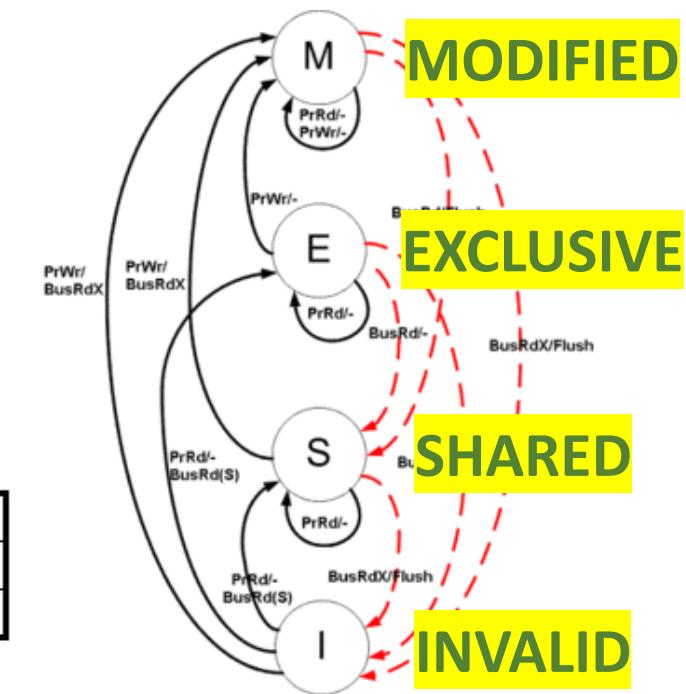
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    store lock, 1
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Lock Implementation & Cache Coherence

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```

10

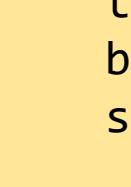
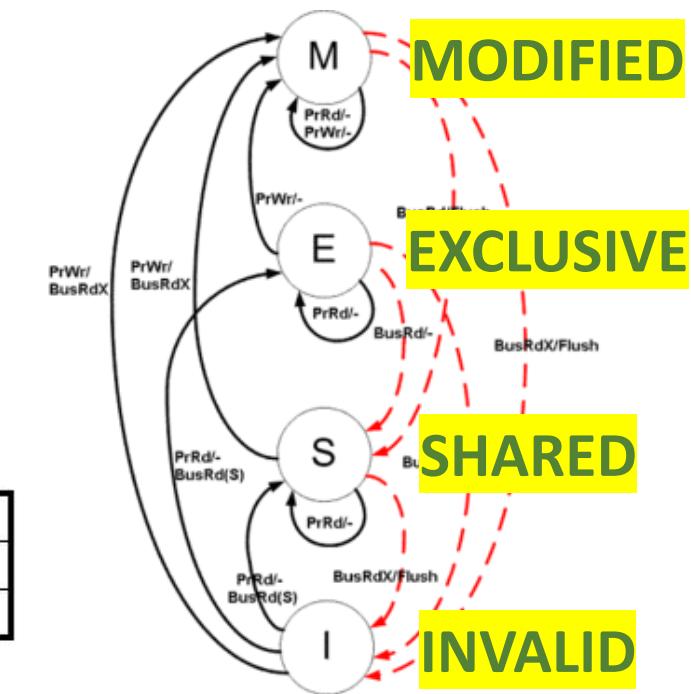
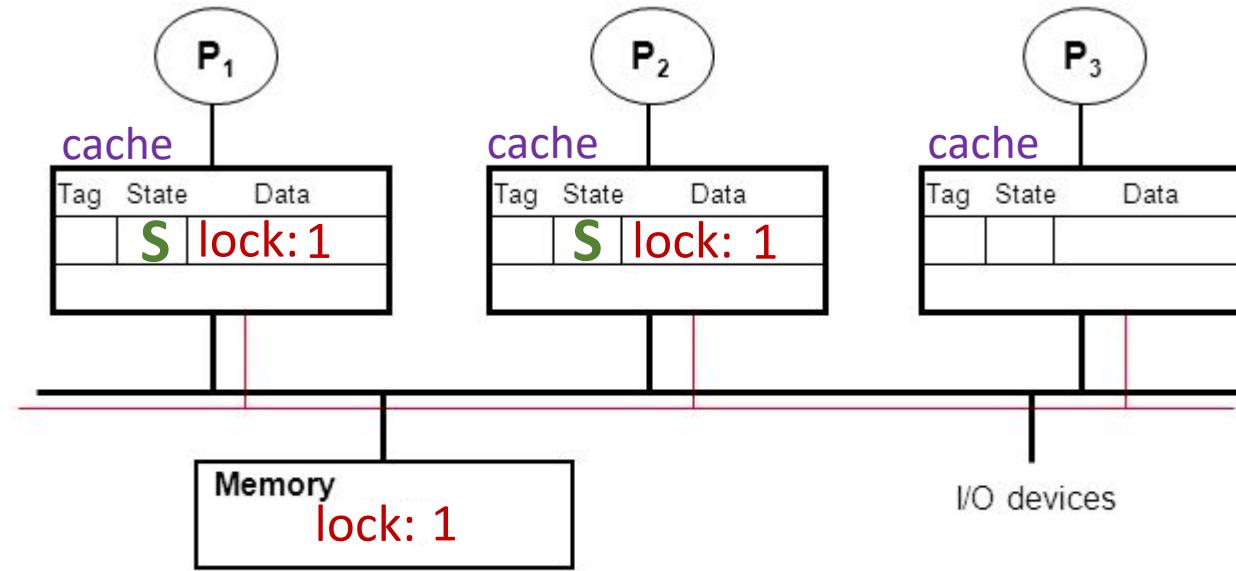


Cache Coherence Action Zone



P1

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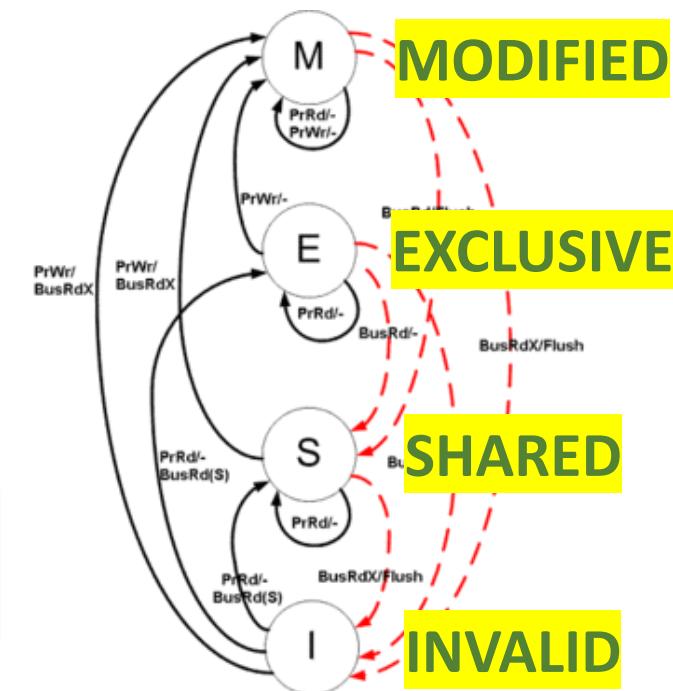
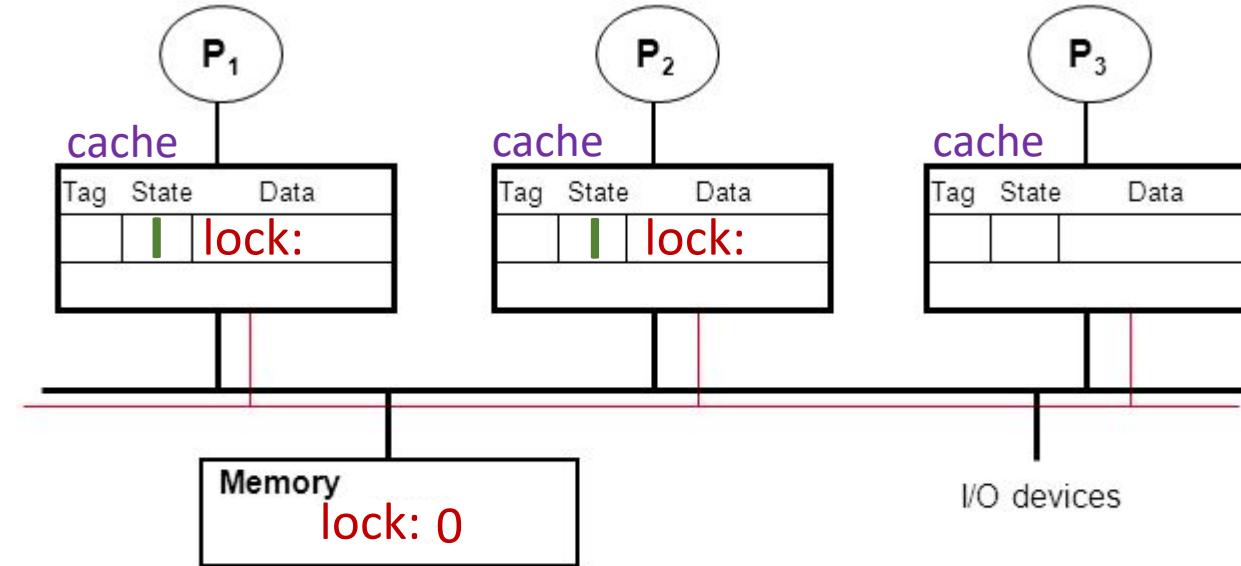
Lock Implementation & Cache Coherence

SAFE!

10

```
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    store lock, 1
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```

Cache Coherence Action Zone II



P1

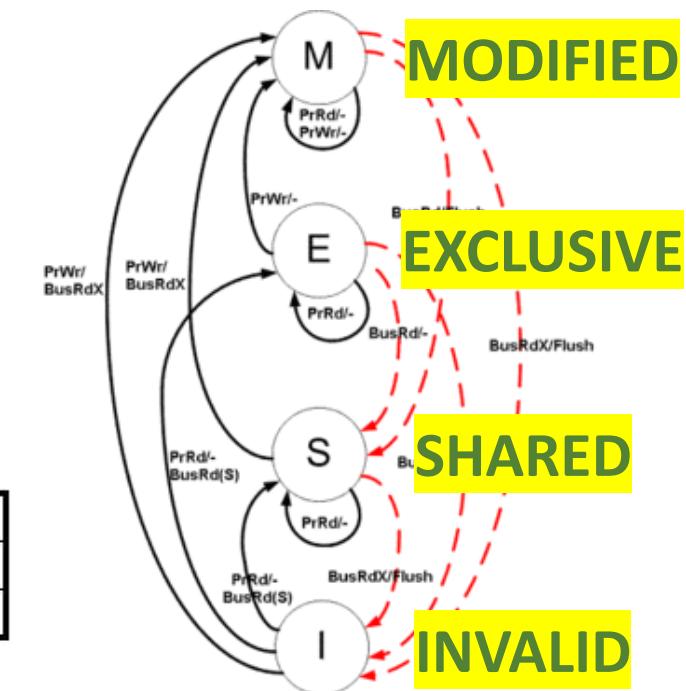
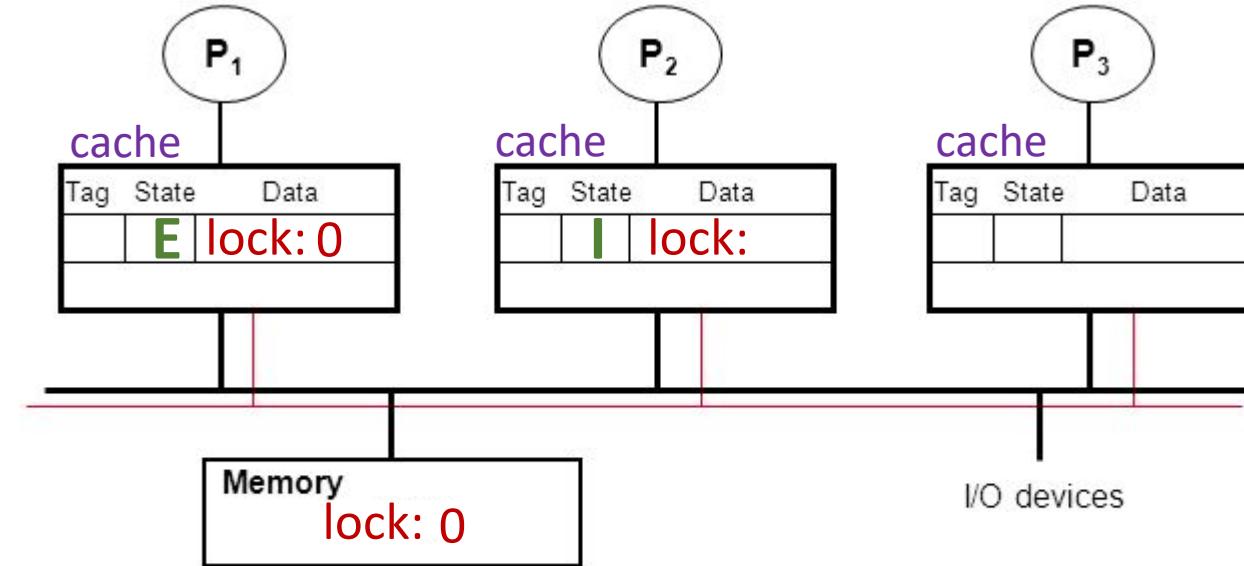
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    bnz try
    store lock, 1
}
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P2

```
// (straw-person lock impl)
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try: load lock, R0
    test R0
    bnz try
    store lock, 1
}
```

Cache Coherence Action Zone II



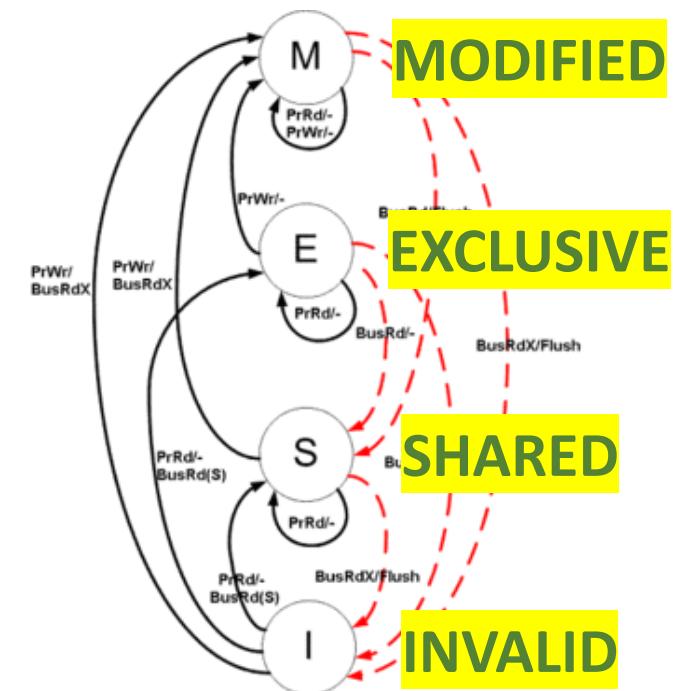
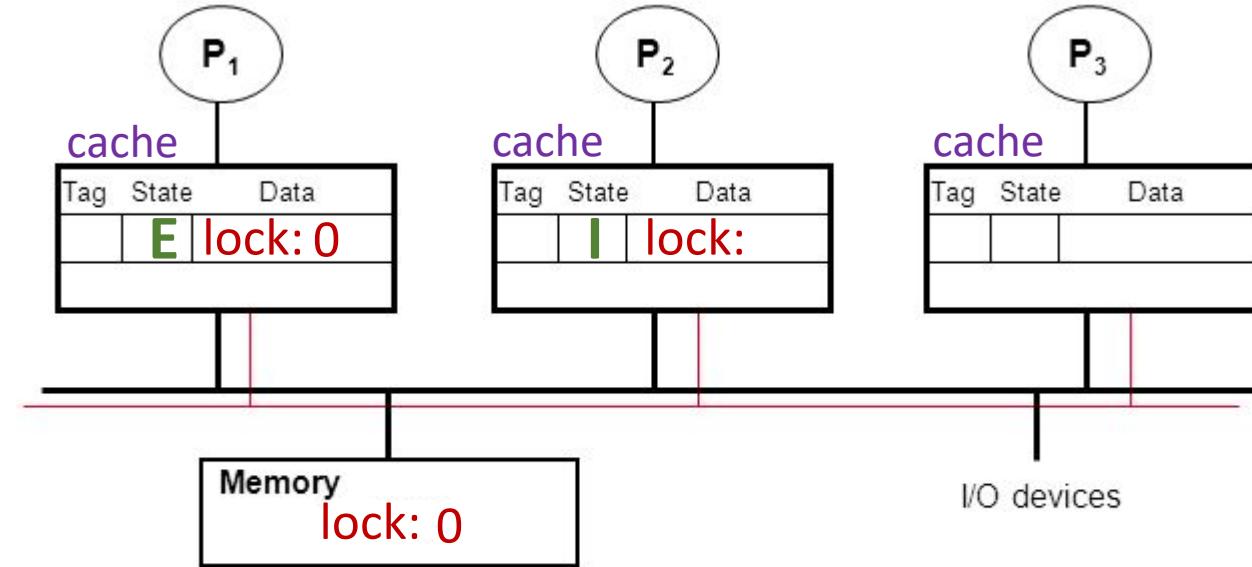
P1

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P2

```
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try: load lock, R0
    test R0
    bnz try
    store lock, 1
}
```

Cache Coherence Action Zone II



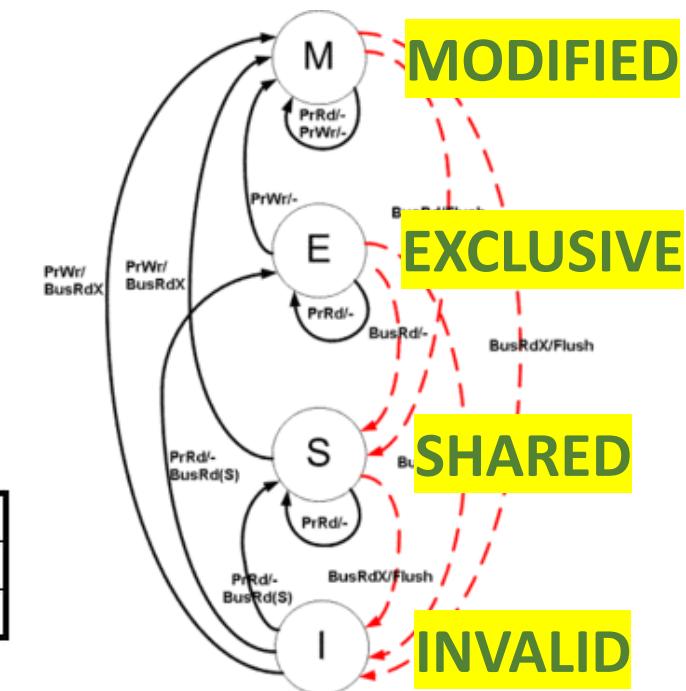
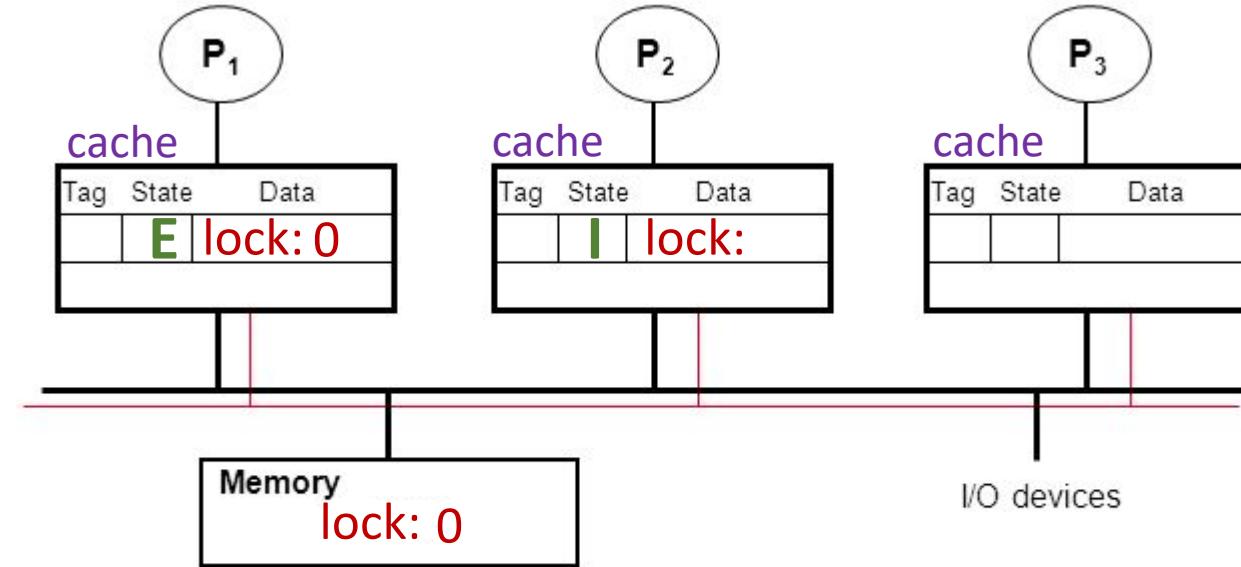
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P2

```
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}
```

Cache Coherence Action Zone II



P1

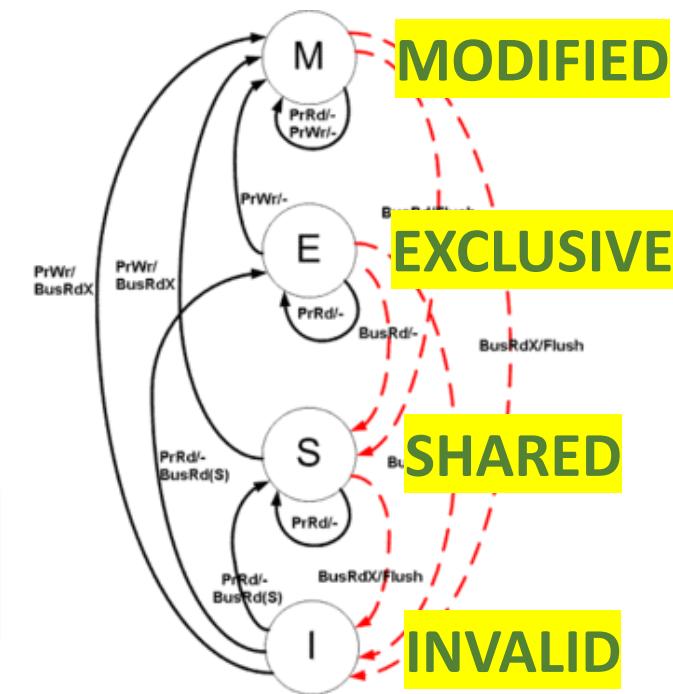
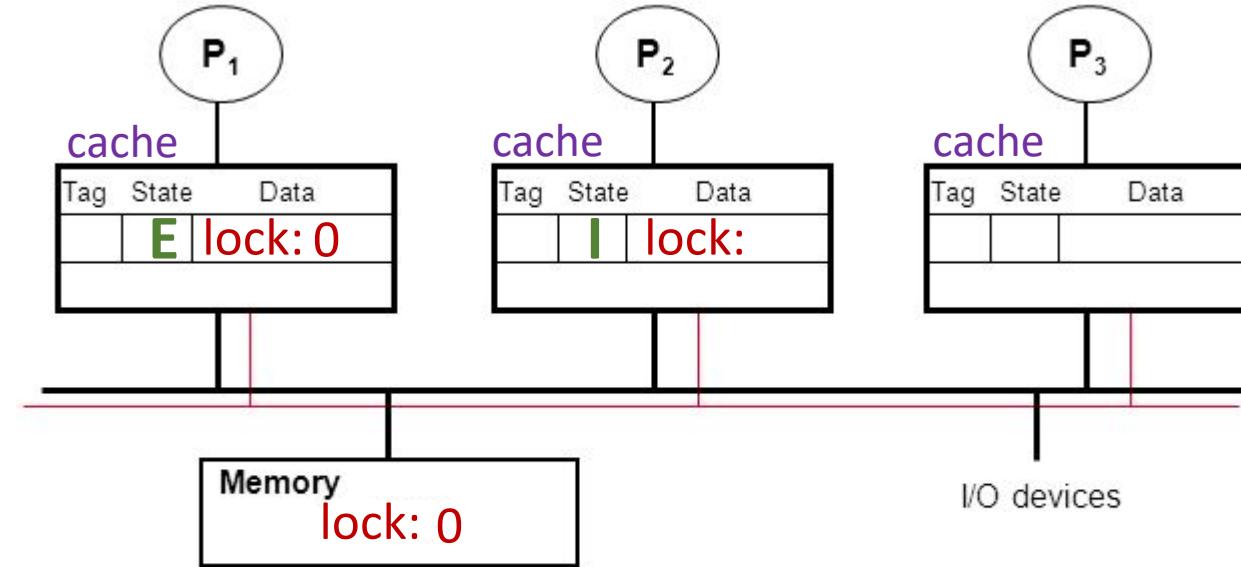
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Cache Coherence Action Zone II



P1

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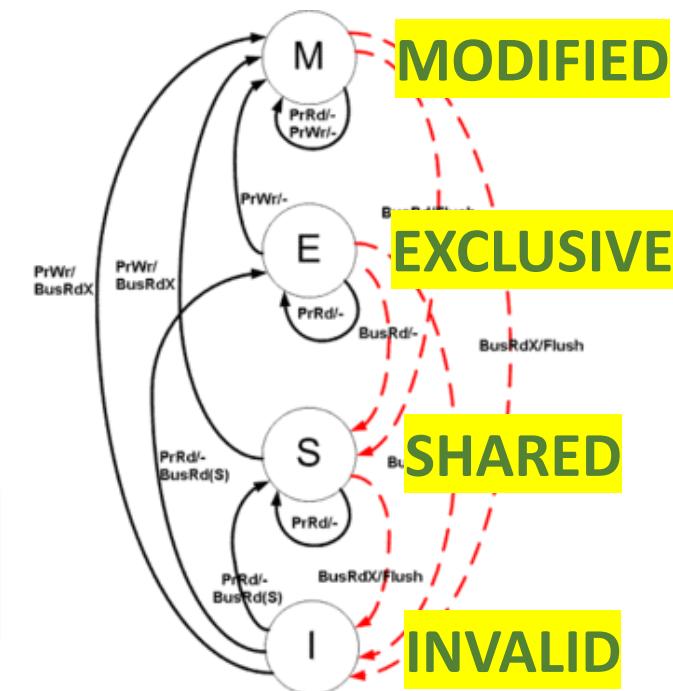
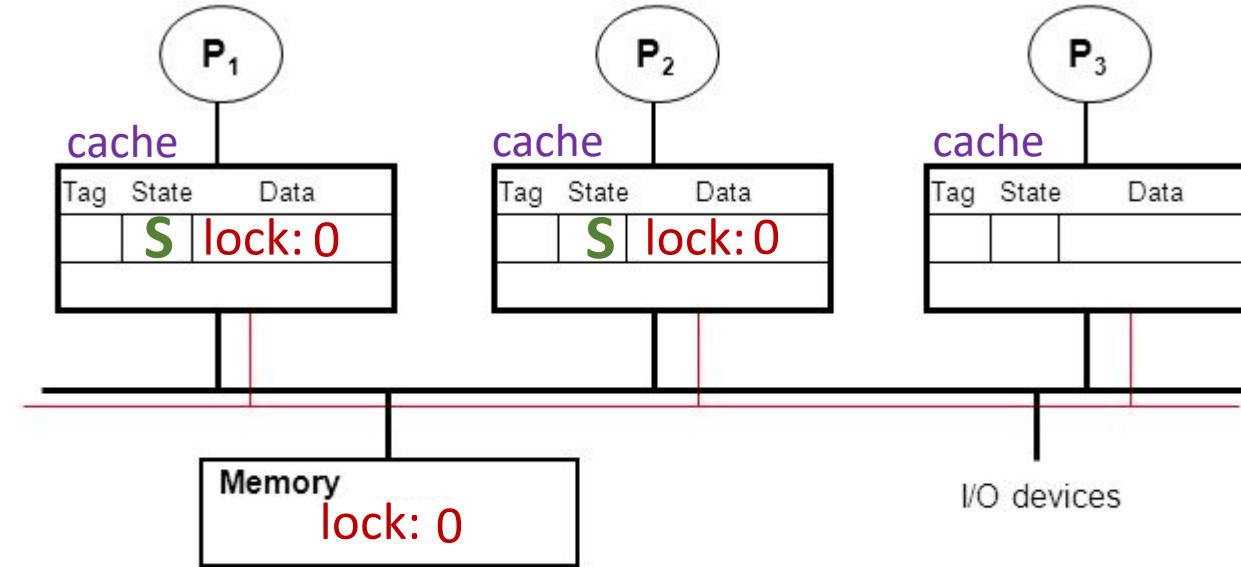
P2



Lock Implementation & Cache Coherence

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Cache Coherence Action Zone II

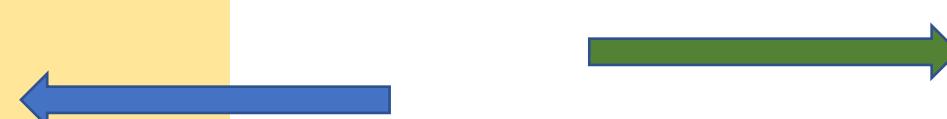


P1

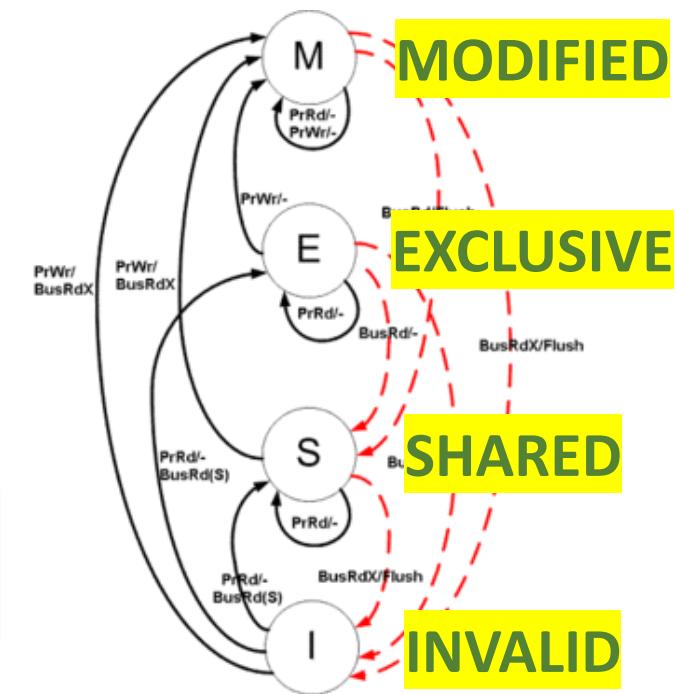
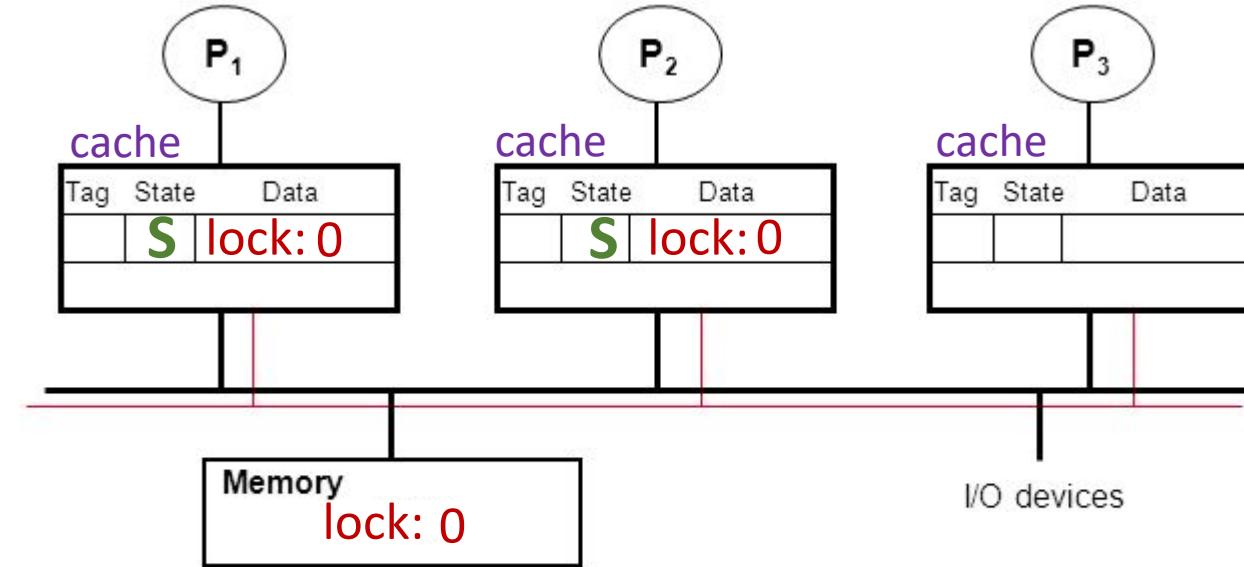
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P2

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Cache Coherence Action Zone II



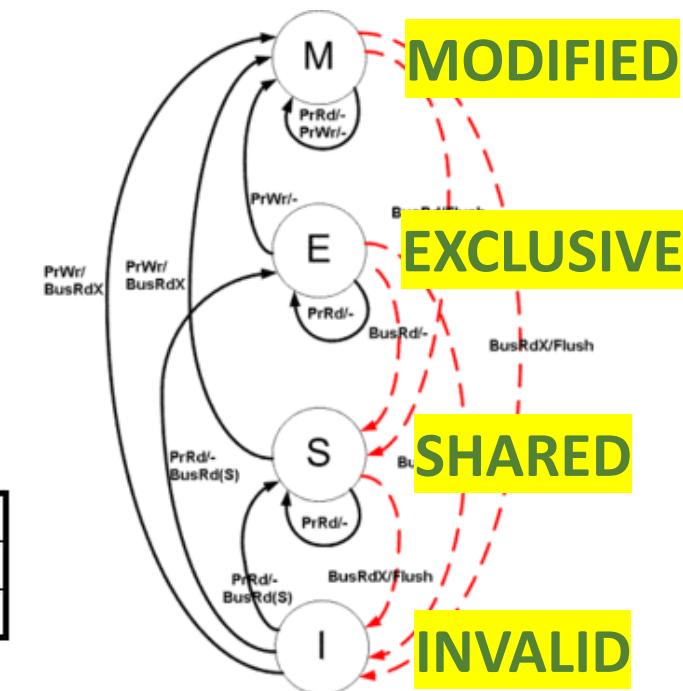
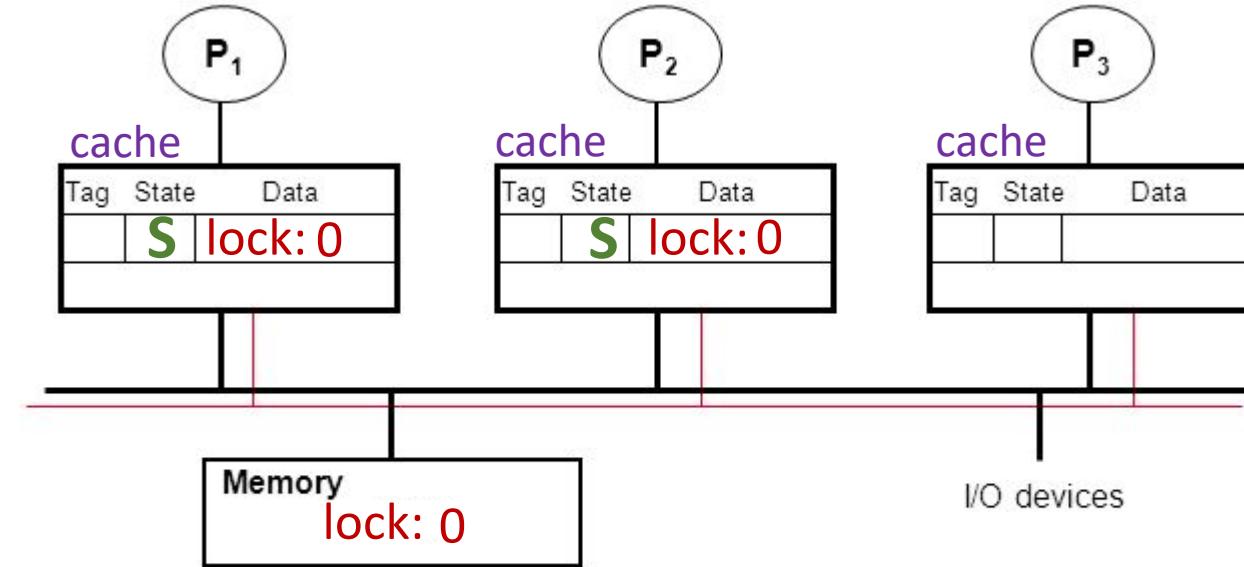
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P2

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Cache Coherence Action Zone II



P1

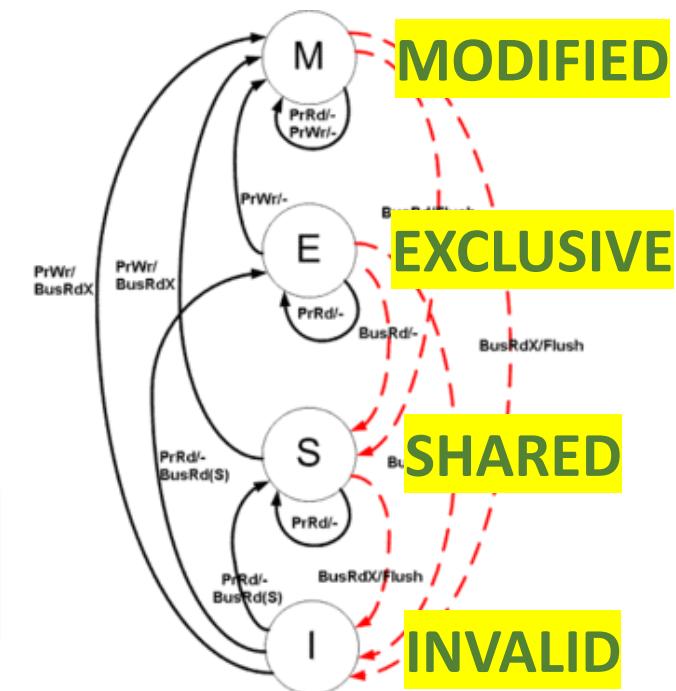
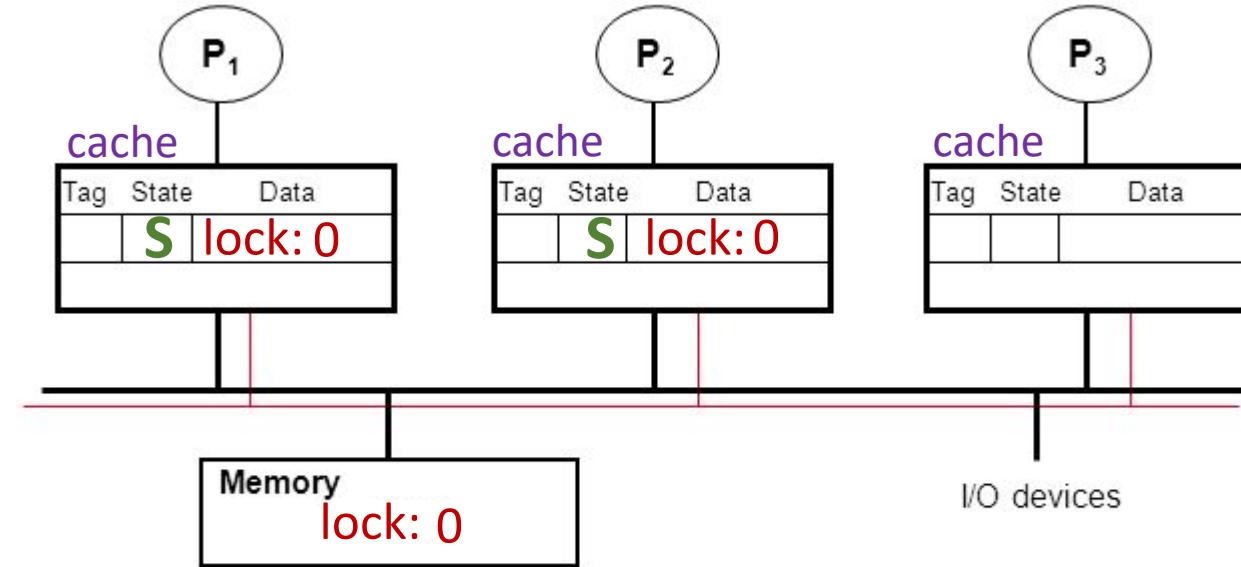
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P2

Lock Implementation & Cache Coherence

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```

Cache Coherence Action Zone II



P1

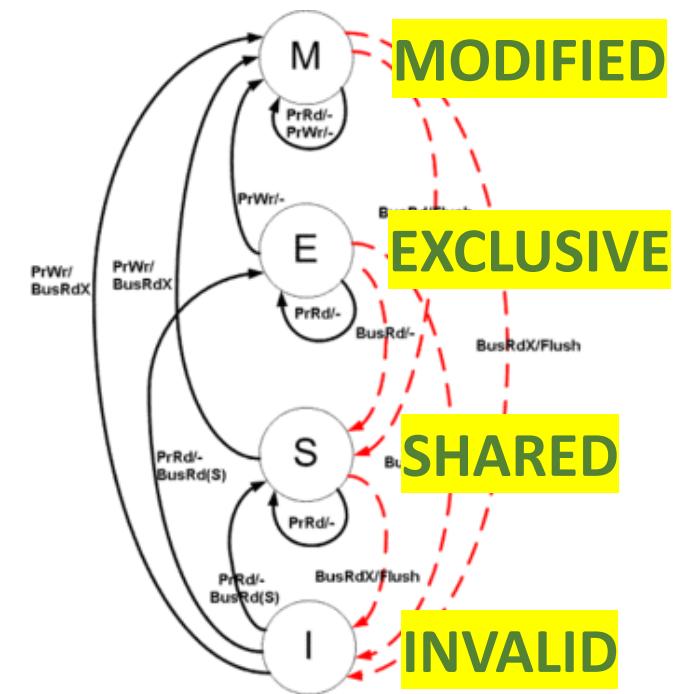
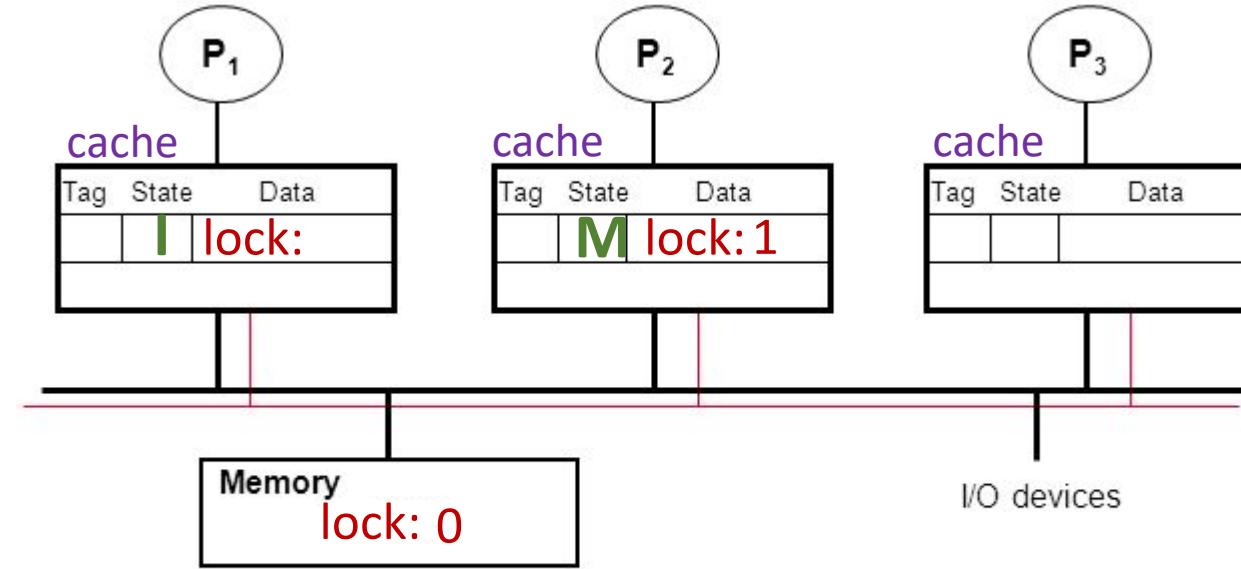
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    bnz try
    store lock, 1
}
```

Lock Implementation & Cache Coherence

Cache Coherence Action Zone II



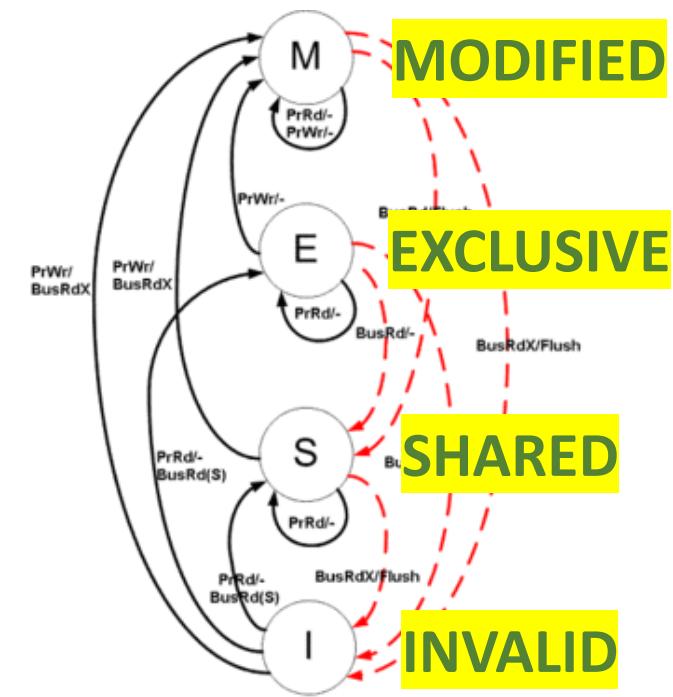
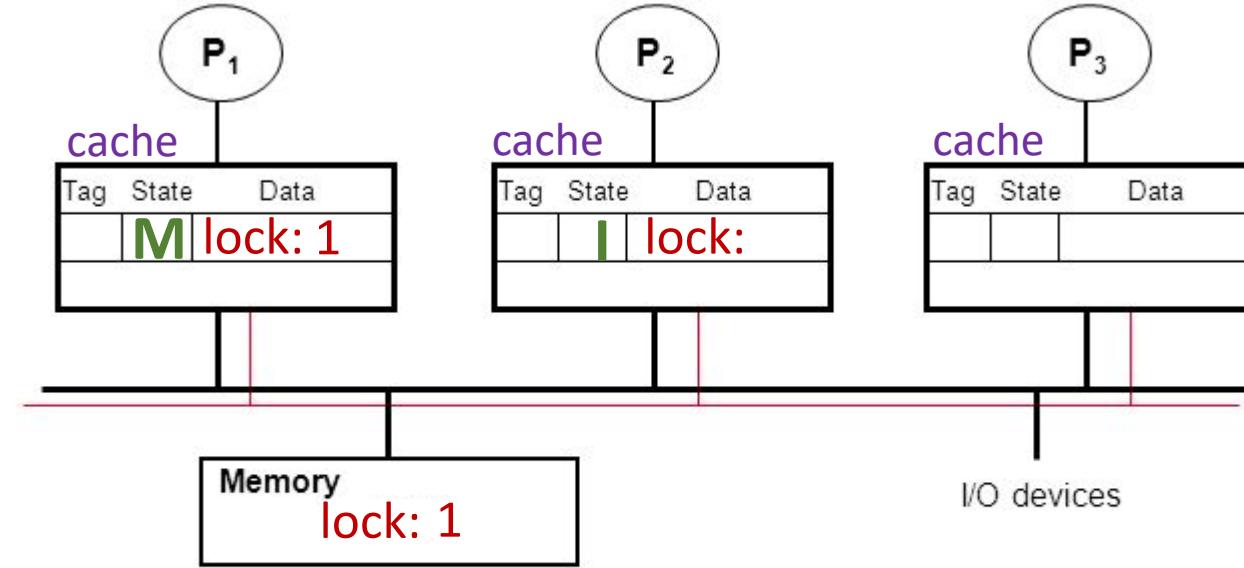
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Lock Implementation & Cache Coherence

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Cache Coherence Action Zone II

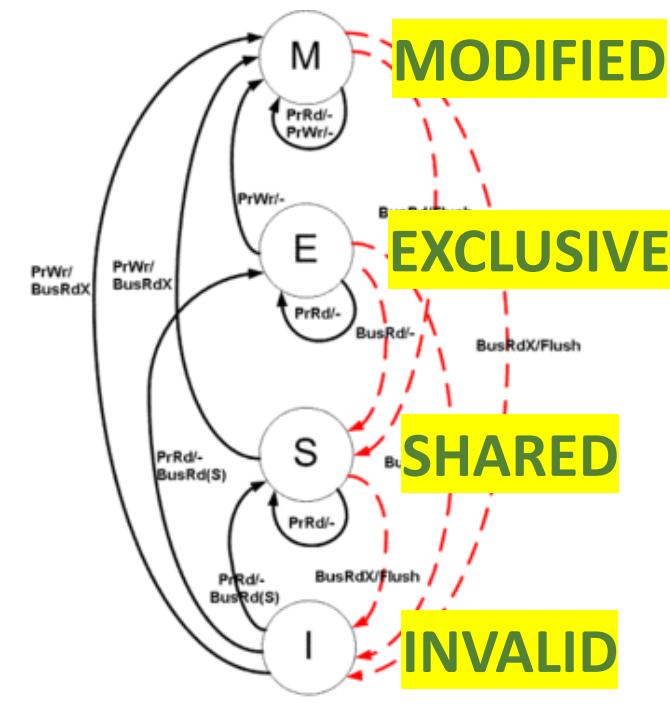
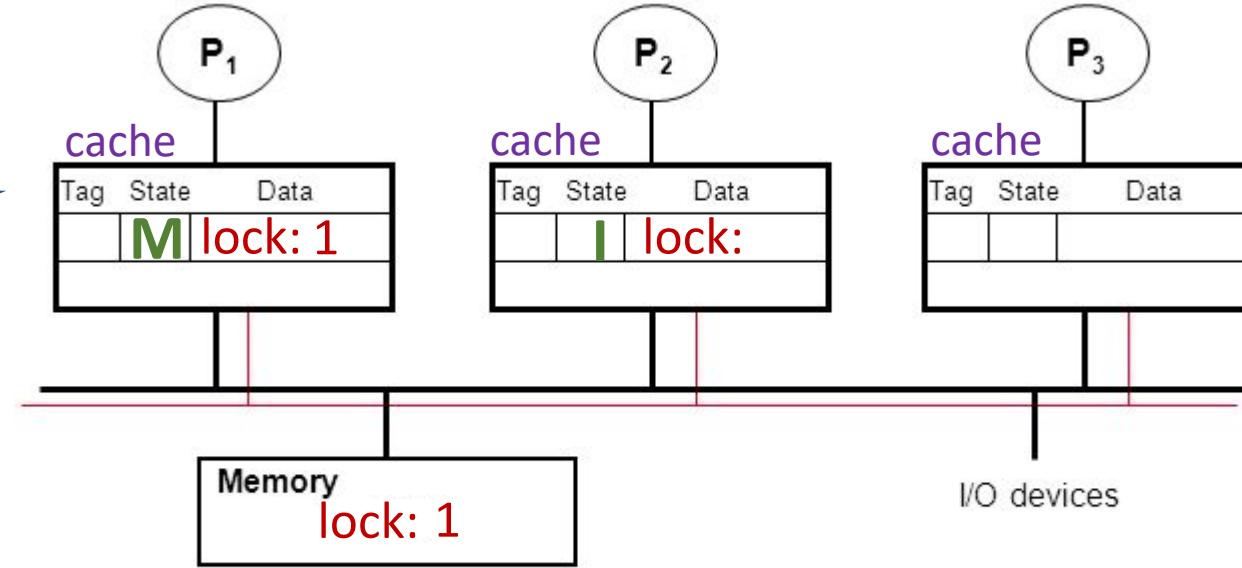


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Lock Implementation & Cache Coherence

Cache Coherence Action Zone II



P1

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Lock Implementation & Cache Coherence

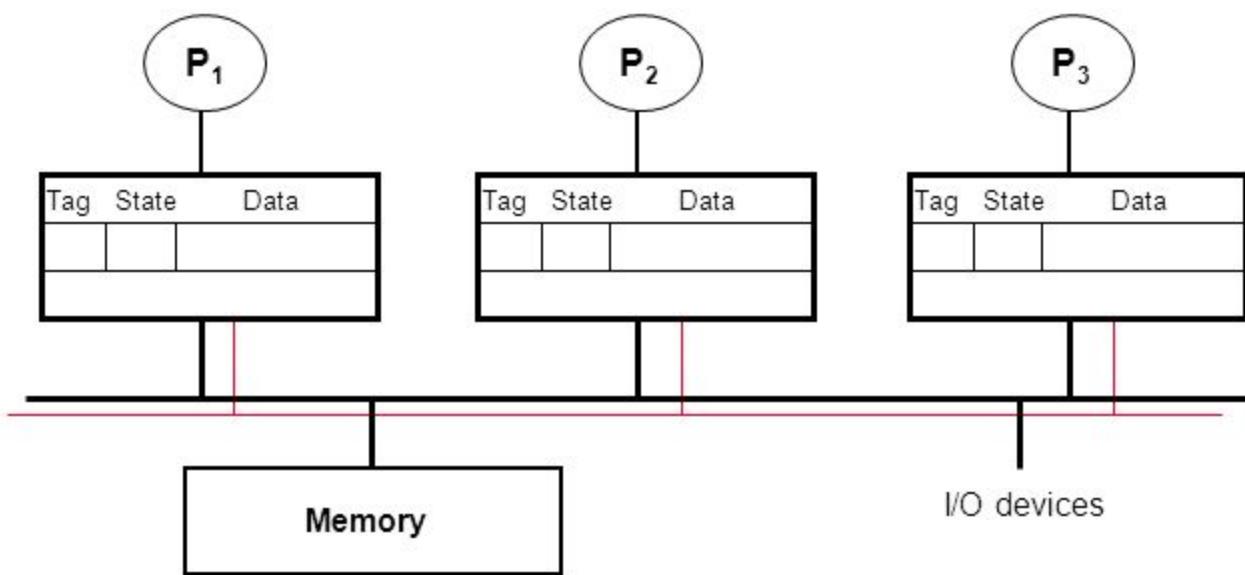
P2

```
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try: load lock, R0
    test R0
    bnz try
    store lock, 1
}
```

Read-Modify-Write (RMW)

- ◆ Implementing locks requires read-modify-write operations
- ◆ Required effect is:
 - An atomic and isolated action
 1. read memory location **AND**
 2. write a new value to the location
 - RMW is *very tricky* in multi-processors
 - Cache coherence alone doesn't solve it

```
// (straw-person lock impl)
// Initially, lock == 0 (unheld)
lock() {
try: load lock, R0
    test R0
    bnz try
    store lock, 1
}
```



Essence of HW-supported RMW

```
// (straw-person lock impl)
// Initially, lock == 0 (unheld)
lock() {
try:    load lock, R0
        test R0
        bnz try
        store lock, 1
}
```

Make this into a single
(atomic hardware instruction)

HW Support for Read-Modify-Write (RMW)

Test & Set	CAS	Exchange, locked increment/decrement,	LLSC: load-linked store-conditional
Most architectures	Many architectures	x86	PPC, Alpha, MIPS
<pre>int TST(addr) { atomic { ret = *addr; if(!*addr) *addr = 1; return ret; } }</pre>	<pre>bool cas(addr, old, new) { atomic { if(*addr == old) { *addr = new; return true; } return false; } }</pre>	<pre>int XCHG(addr, val) { atomic { ret = *addr; *addr = val; return ret; } }</pre>	<pre>bool LLSC(addr, val) { ret = *addr; atomic { if(*addr == ret) { *addr = val; return true; } return false; } }</pre>

HW Support for Read-Modify-Write (RMW)

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	<pre>void CAS_lock(lock) { while(CAS(&lock, 0, 1) != true); }</pre>		

HW Support for Read-Modify-Write (RMW)

Test & Set	CAS	Exchange, locked increment/decrement,	LLSC: load-linked store-conditional
Most architectures	Many architectures	x86	PPC, Alpha, MIPS
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HW Support for RMW: LL-SC

LLSC: load-linked store-conditional

PPC, Alpha, MIPS

```
bool LLSC(addr, val) {
    ret = *addr;
    atomic {
        if(*addr == ret) {
            *addr = val;
            return true;
        }
        return false;
    }
```

- load-linked is a load that is “linked” to a subsequent store-conditional
- Store-conditional only succeeds if value from linked-load is unchanged

HW Support for RMW: LL-SC

LLSC: load-linked store-conditional

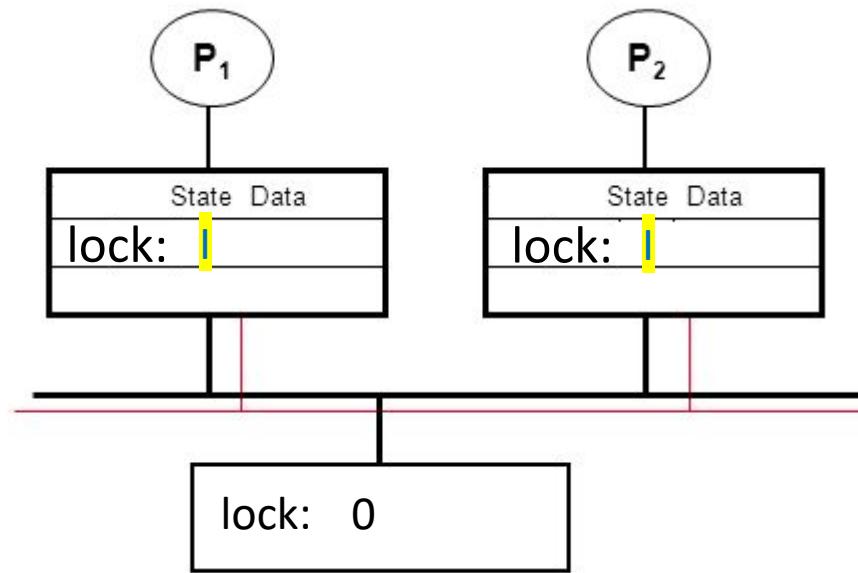
PPC, Alpha, MIPS

```
bool LLSC(addr, val) {
    ret = *addr;
    atomic {
        if(*addr == ret) {
            *addr = val;
            return true;
        }
    }
    return false;
}
```

```
void LLSC_lock(lock) {
    while(1) {
        old = load-linked(lock);
        if(old == 0 && store-cond(lock, 1))
            return;
    }
}
```

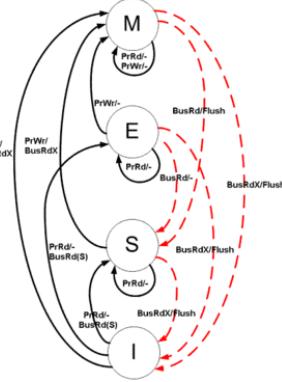
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LLSC Lock Action Zone

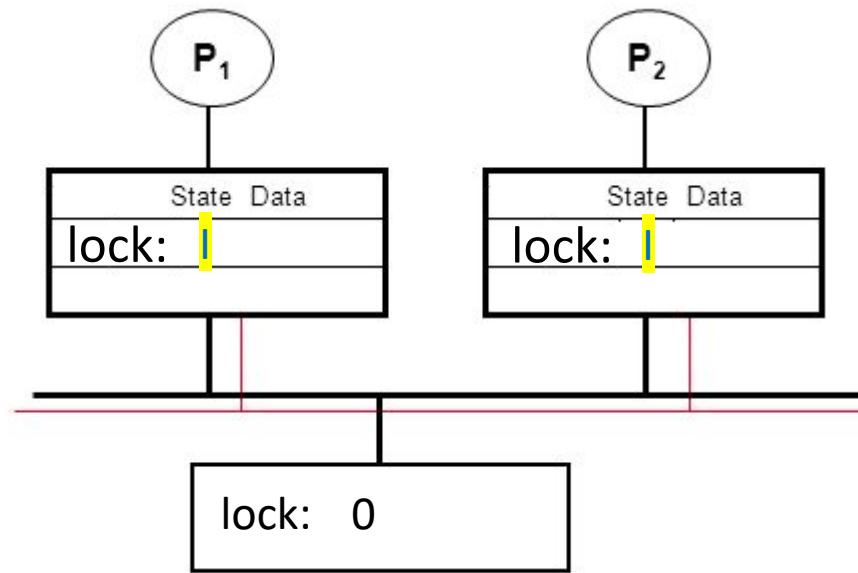


```
P1
lock(lock) {
    while(1) {
        old = ll(lock);
        if(old == 0)
            if(sc(lock, 1))
                return;
    }
}
```

```
P2
lock(lock) {
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        old = ll(lock);
        if(old == 0)
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                return;
    }
}
```



LLSC Lock Action Zone

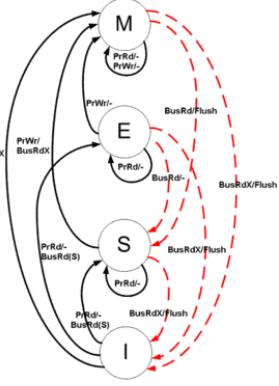


P1

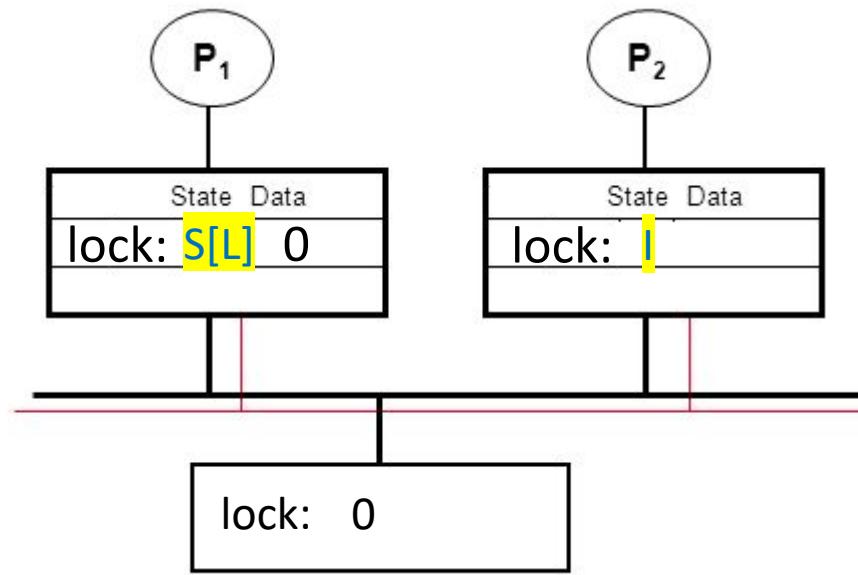
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P2

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LLSC Lock Action Zone

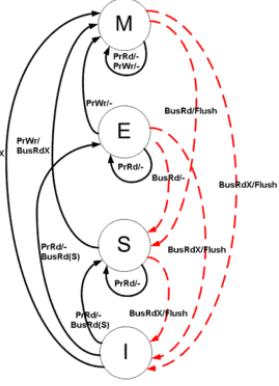


P1

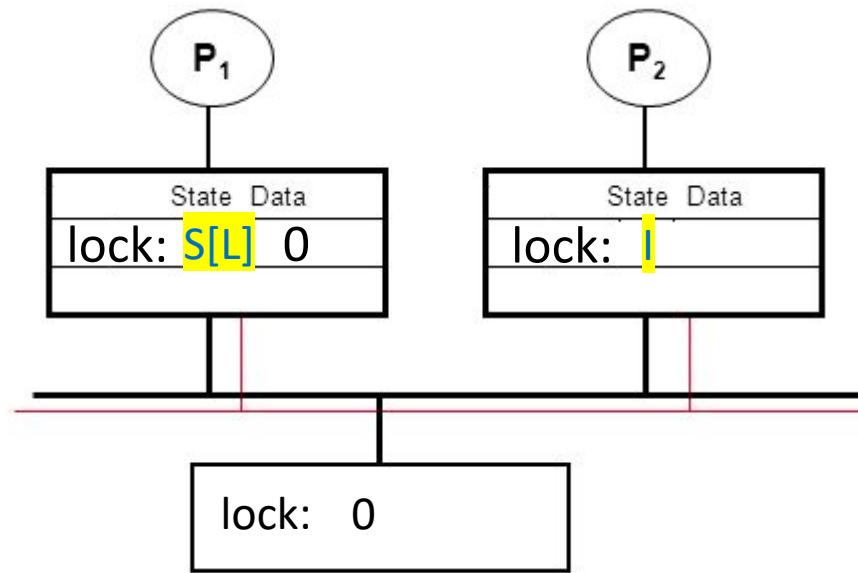
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LLSC Lock Action Zone

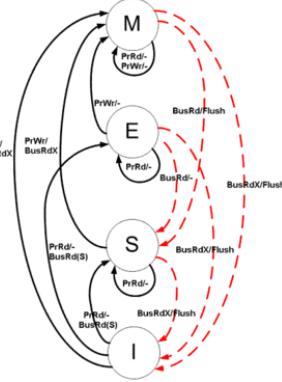


P1

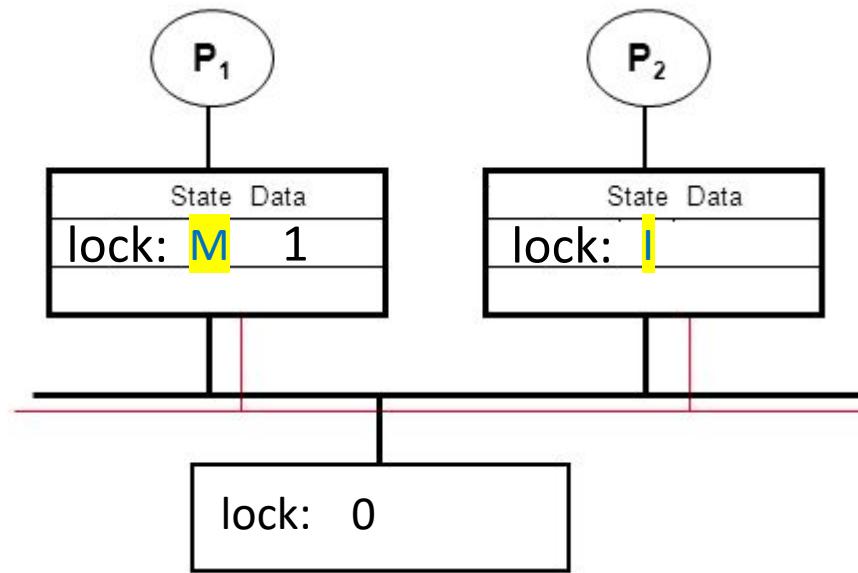
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LLSC Lock Action Zone

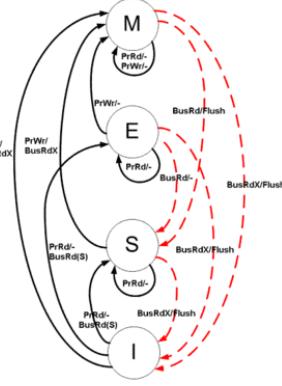


P1

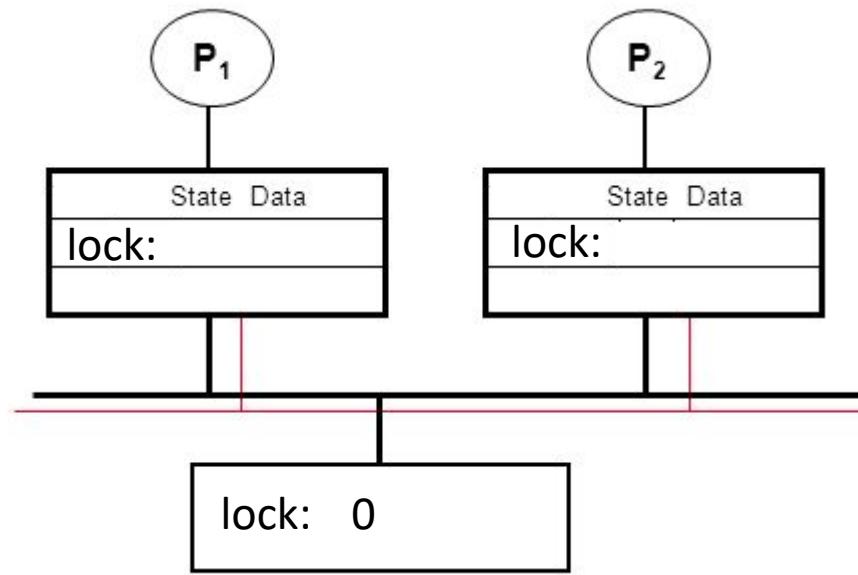
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}
```

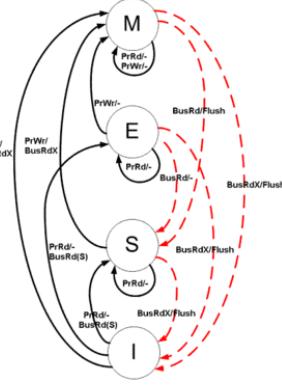


LLSC Lock Action Zone II

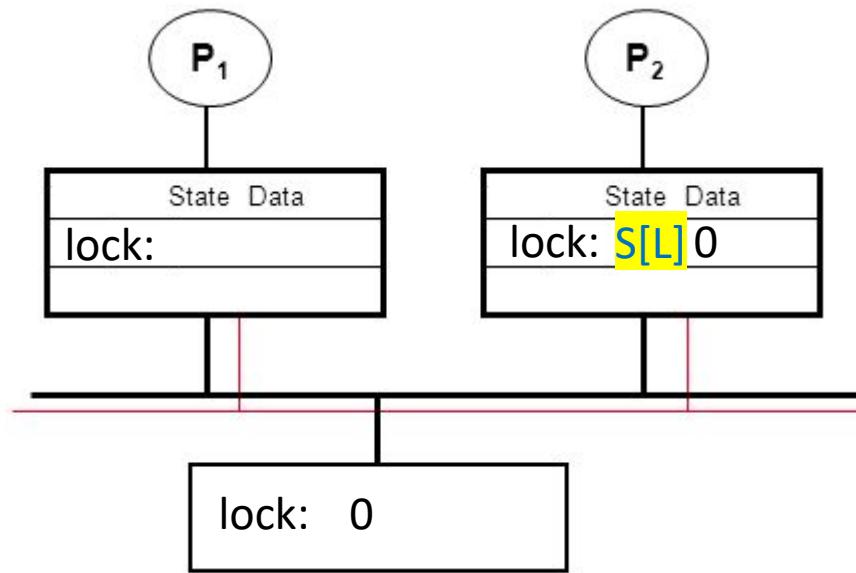


```
P1
lock(lock) {
    while(1) {
        old = ll(lock);
        if(old == 0)
            if(sc(lock, 1))
                return;
    }
}
```

```
P2
lock(lock) {
    while(1) {
        old = ll(lock);
        if(old == 0)
            if(sc(lock, 1))
                return;
    }
}
```



LLSC Lock Action Zone II

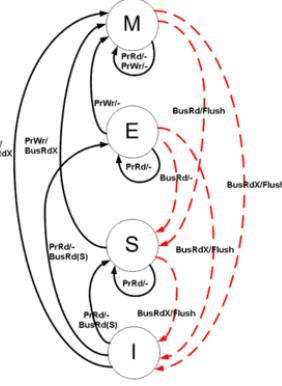


P1

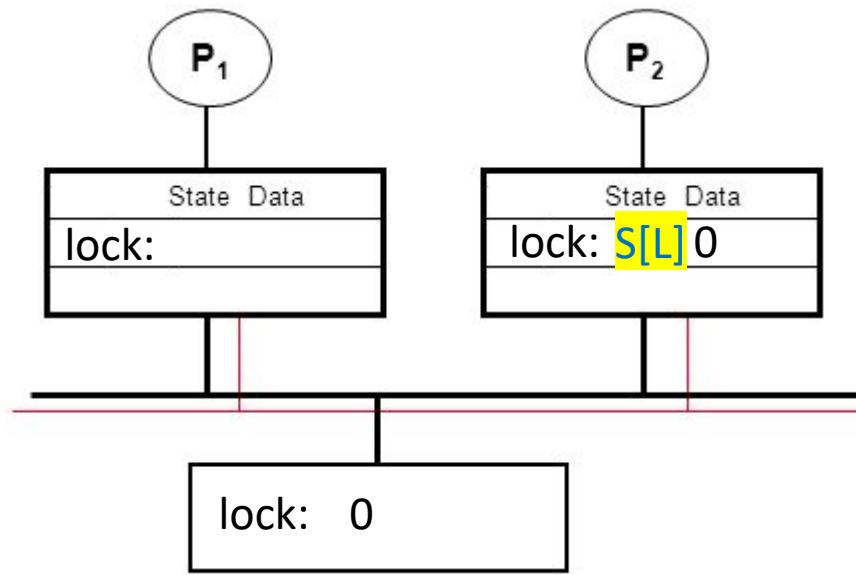
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P2

```
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    }  
}
```

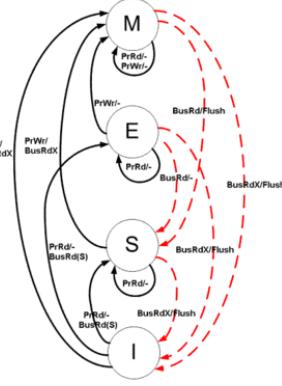


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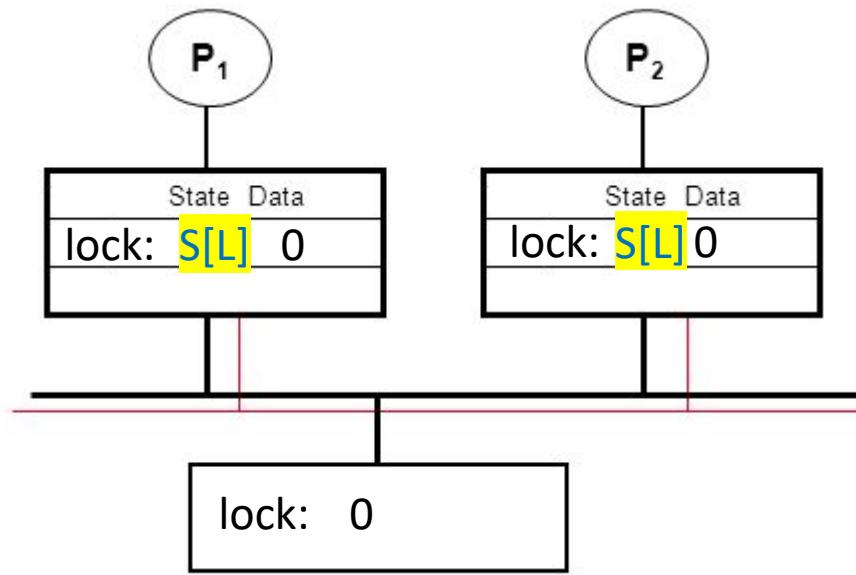


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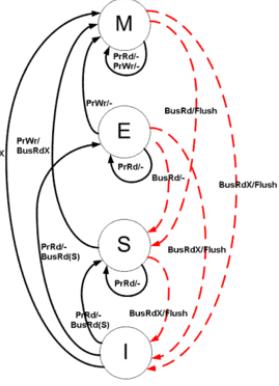


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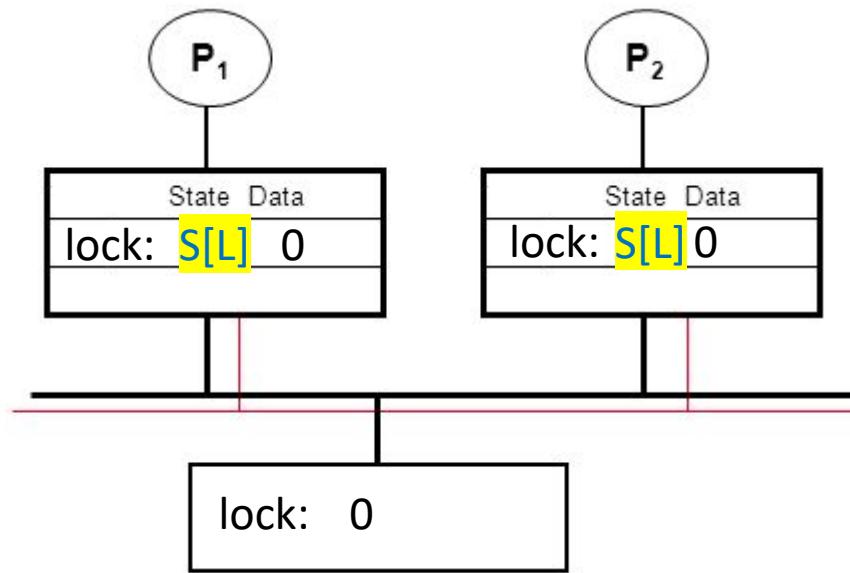


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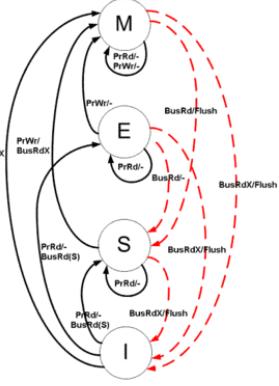


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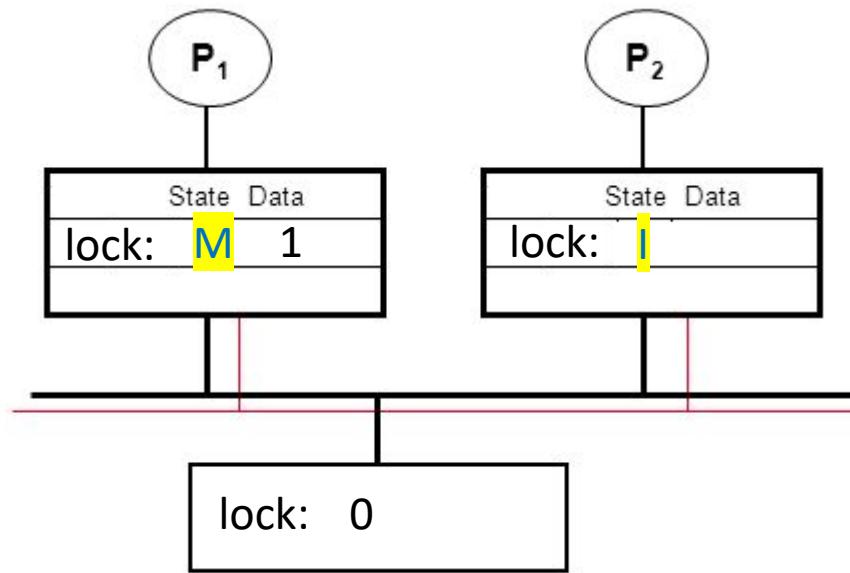
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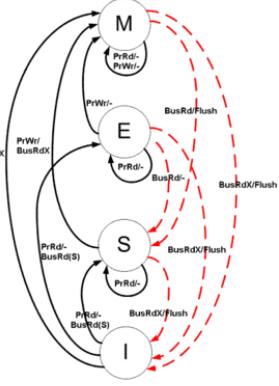


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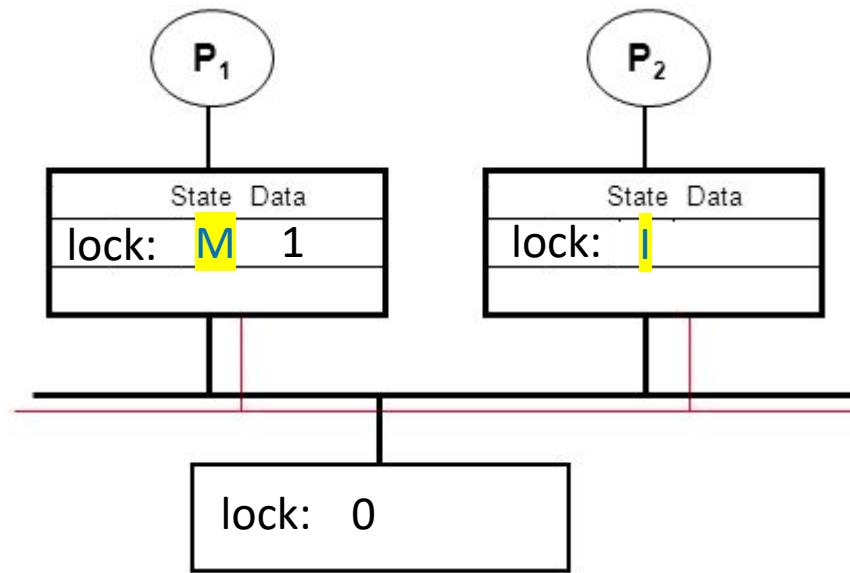
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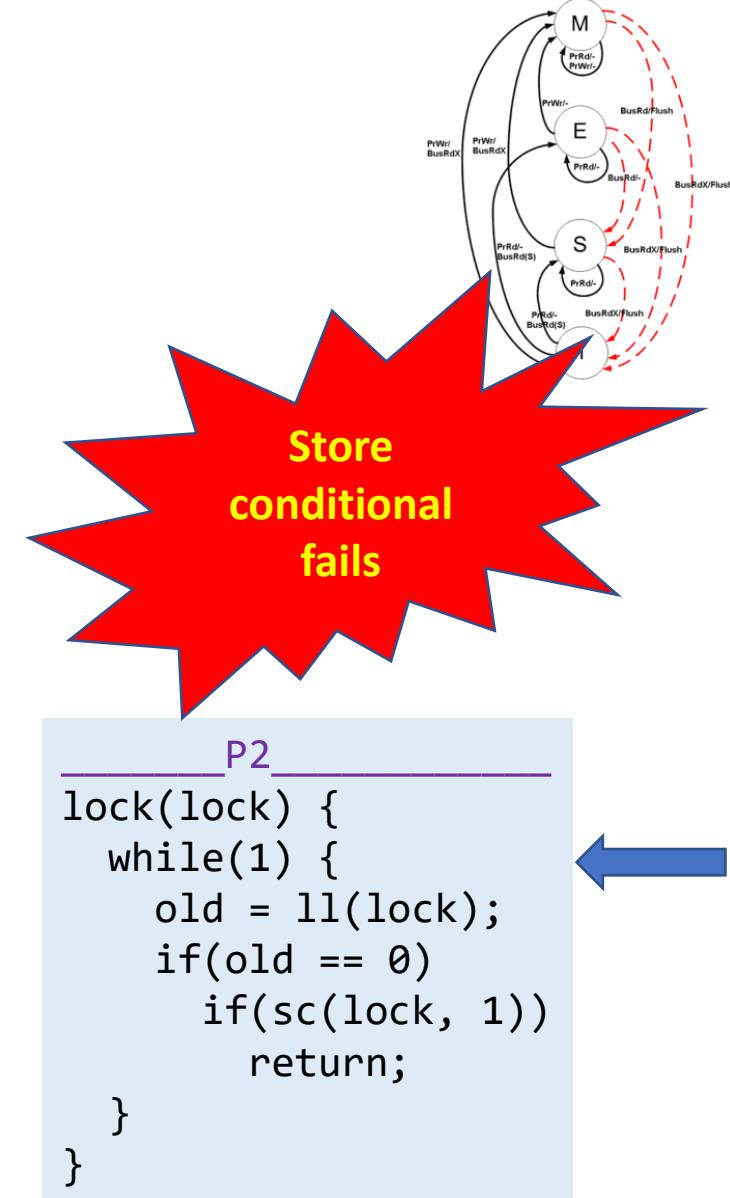


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```
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        if(old == 0)  
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                return;  
    }  
}
```



Implementing Locks with Test&set

```
int lock_value = 0;  
int* lock = &lock_value;
```

```
Lock::Acquire() {  
    while (test&set(lock) == 1)  
        ; //spin  
}
```

(test & set ~ CAS ~ LLSC)



Implementing Locks with Test&set

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int lock_value = 0;  
int* lock = &lock_value;
```

```
Lock::Acquire() {  
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(test & set ~ CAS ~ LLSC)

```
Lock::Release() {  
    *lock = 0;  
}
```

Implementing Locks with Test&set

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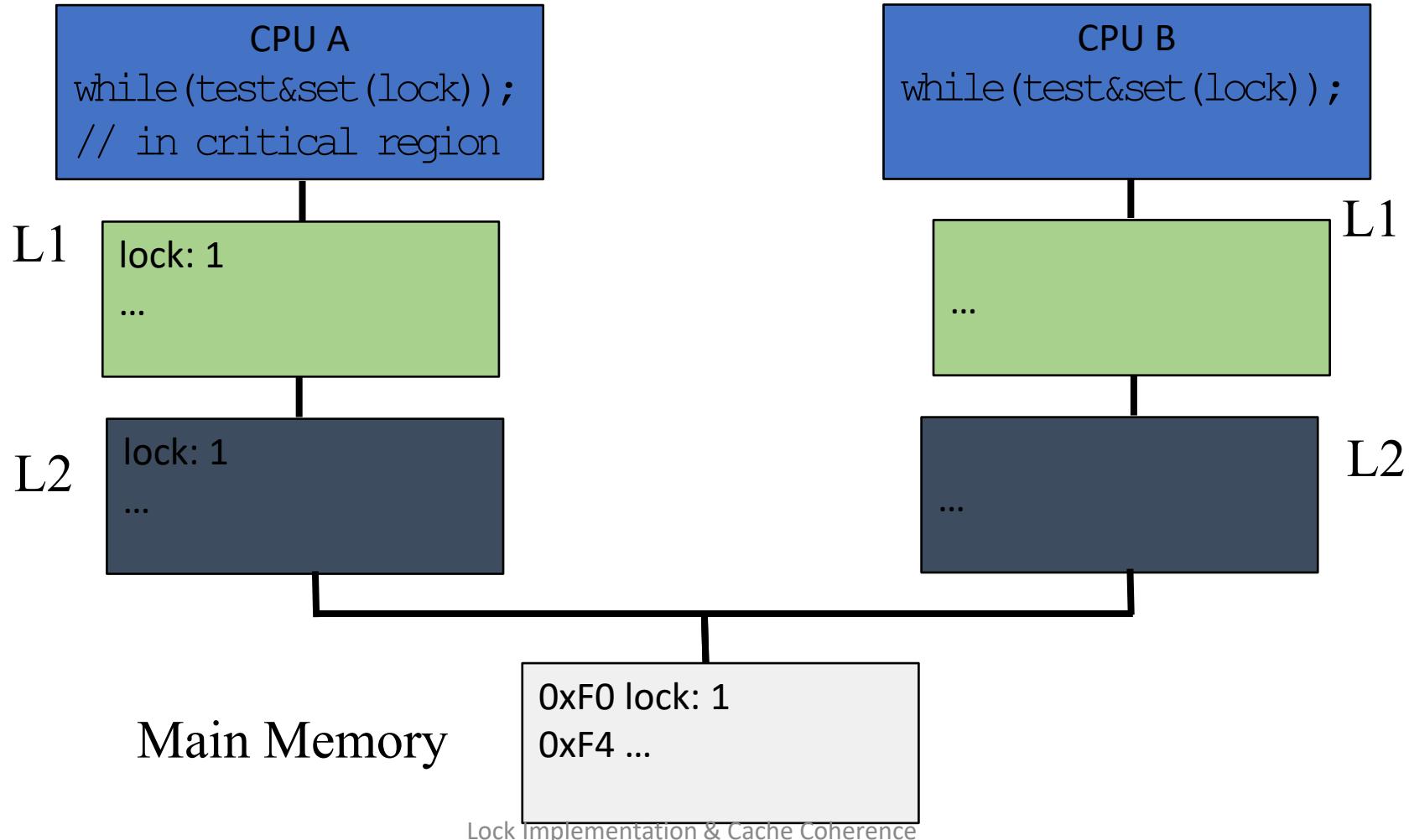
What is the problem with this?

- A. CPU usage B. Memory usage C. Lock::Acquire() latency
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Test & Set with Memory Hierarchies

Initially, lock already held by some other CPU—A, B busy-waiting

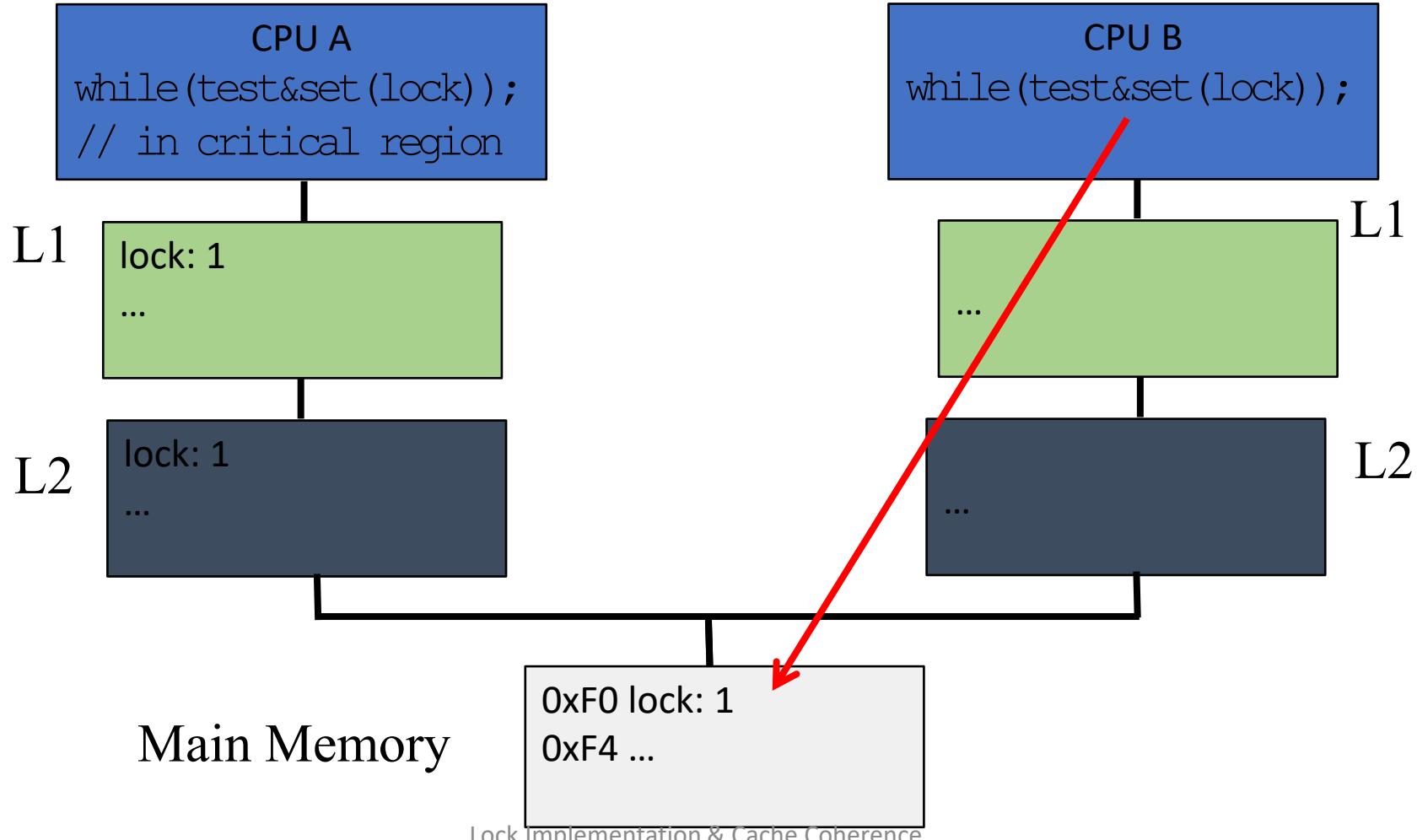
What happens to lock variable's cache line when different cpu's contend?



Test & Set with Memory Hierarchies

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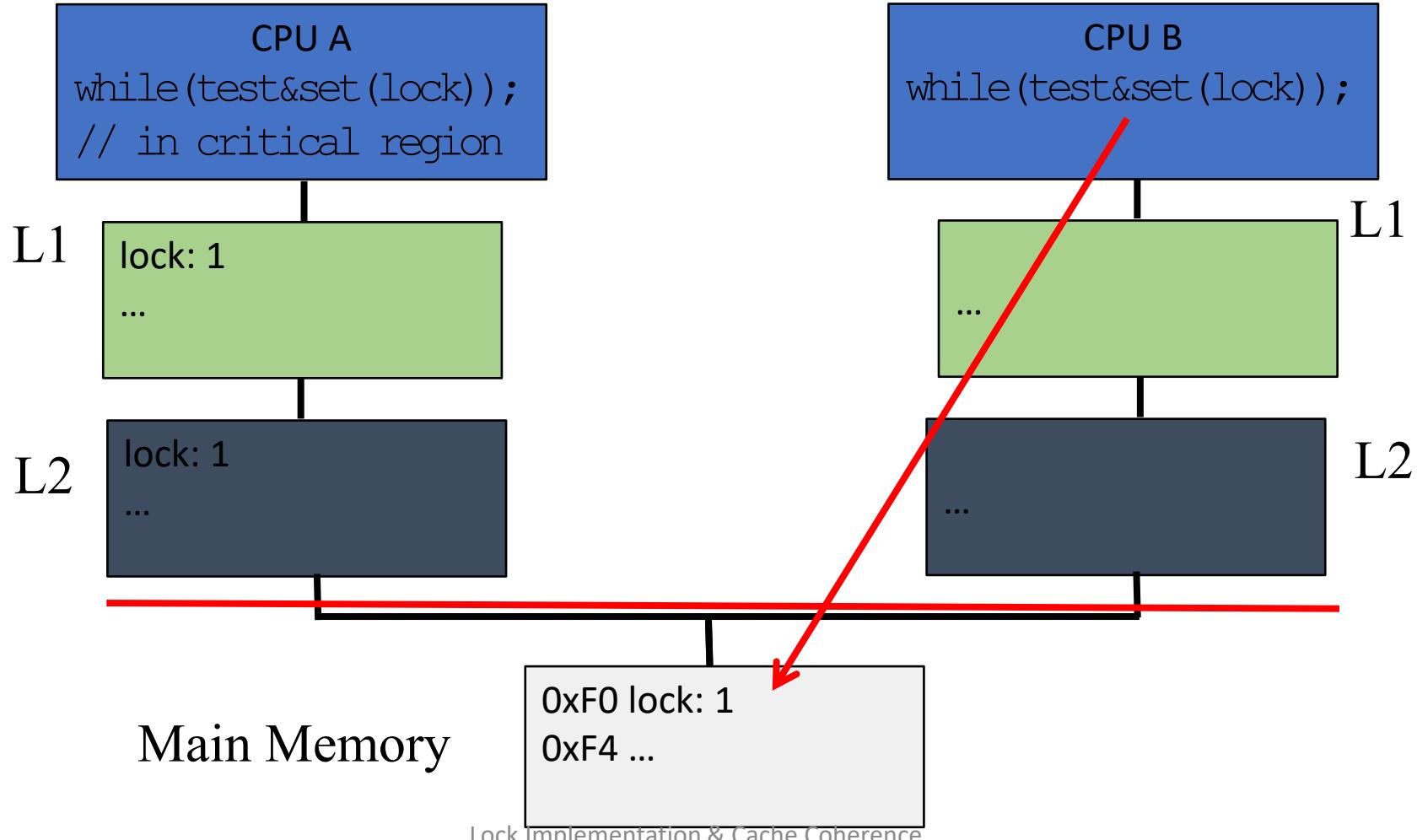
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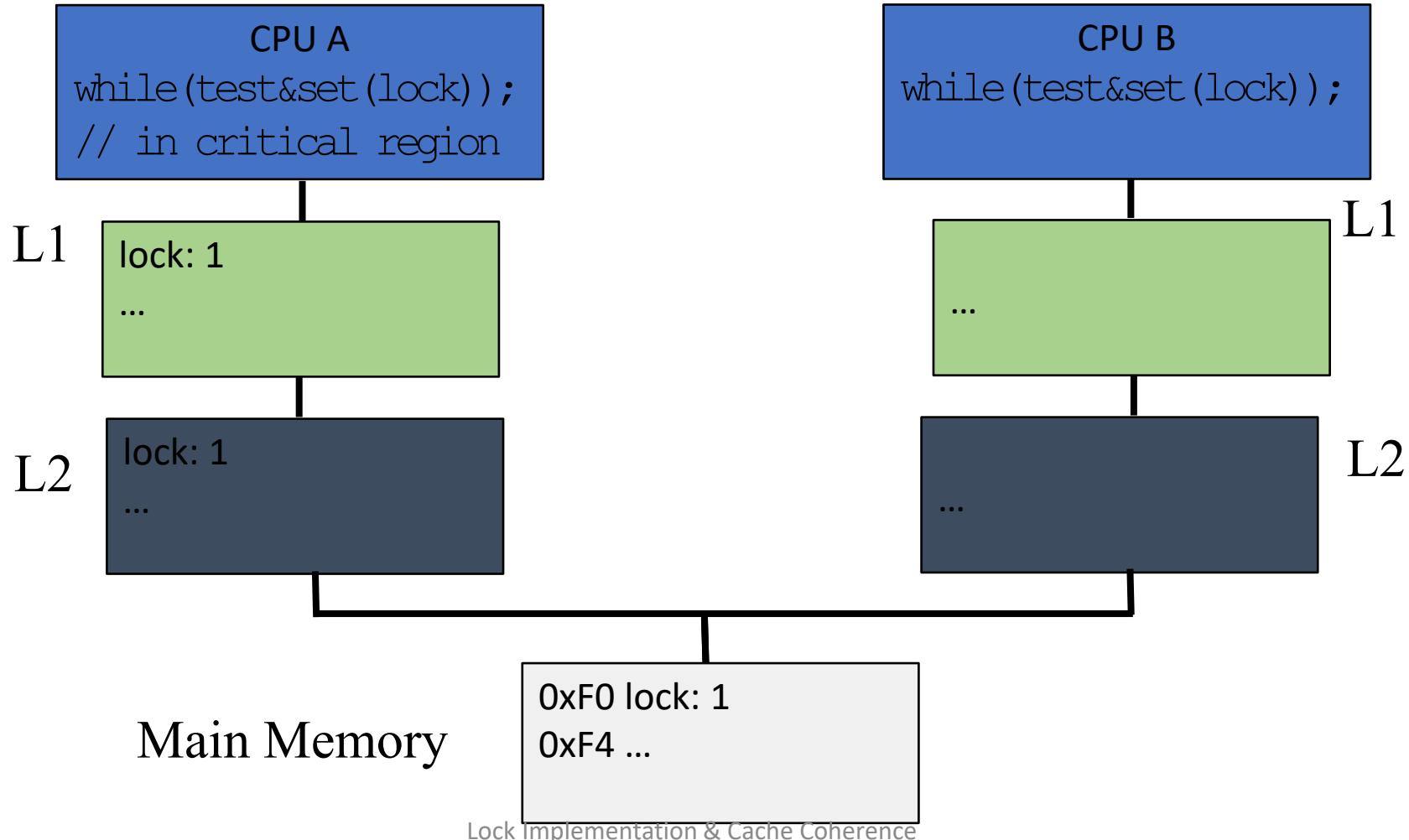
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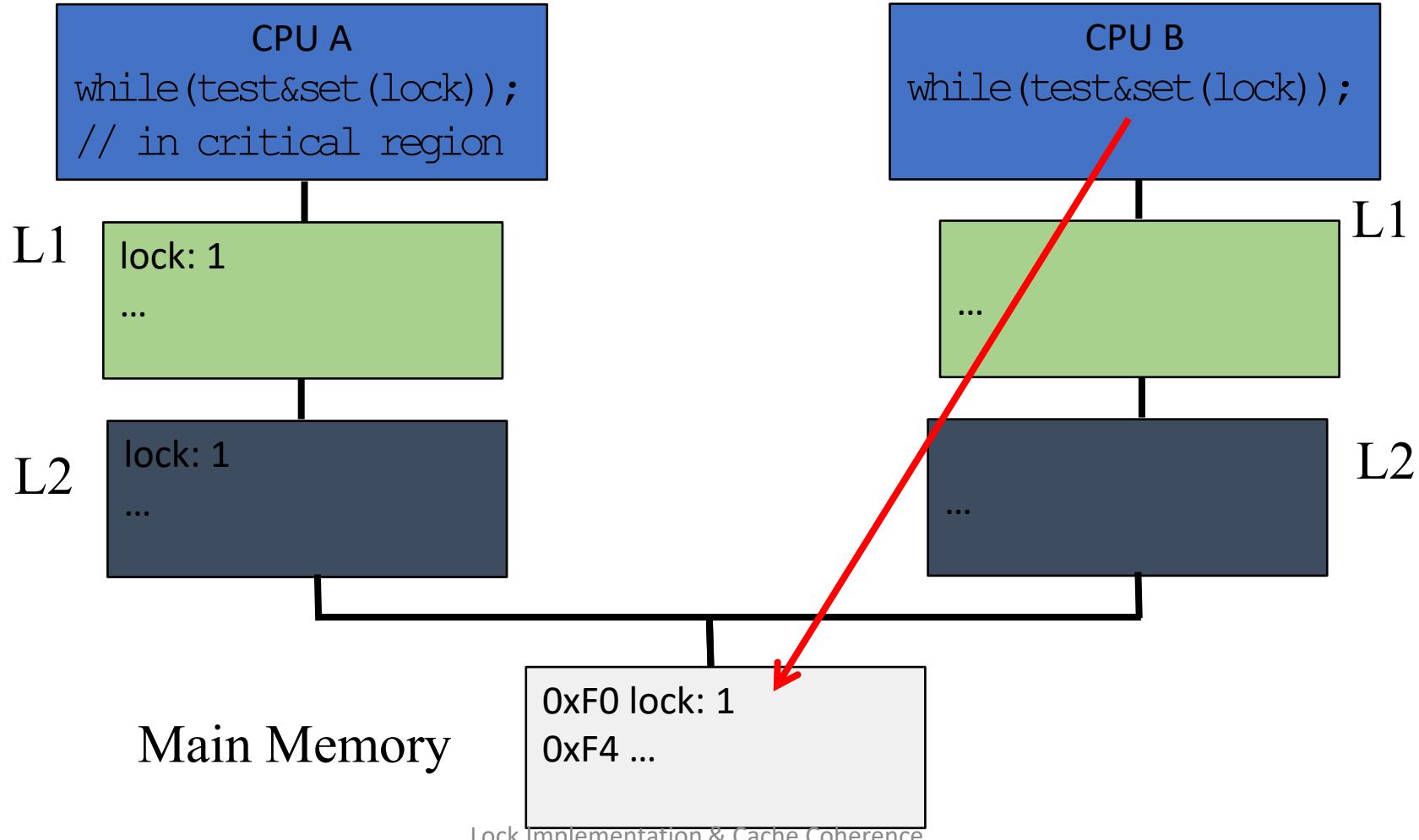
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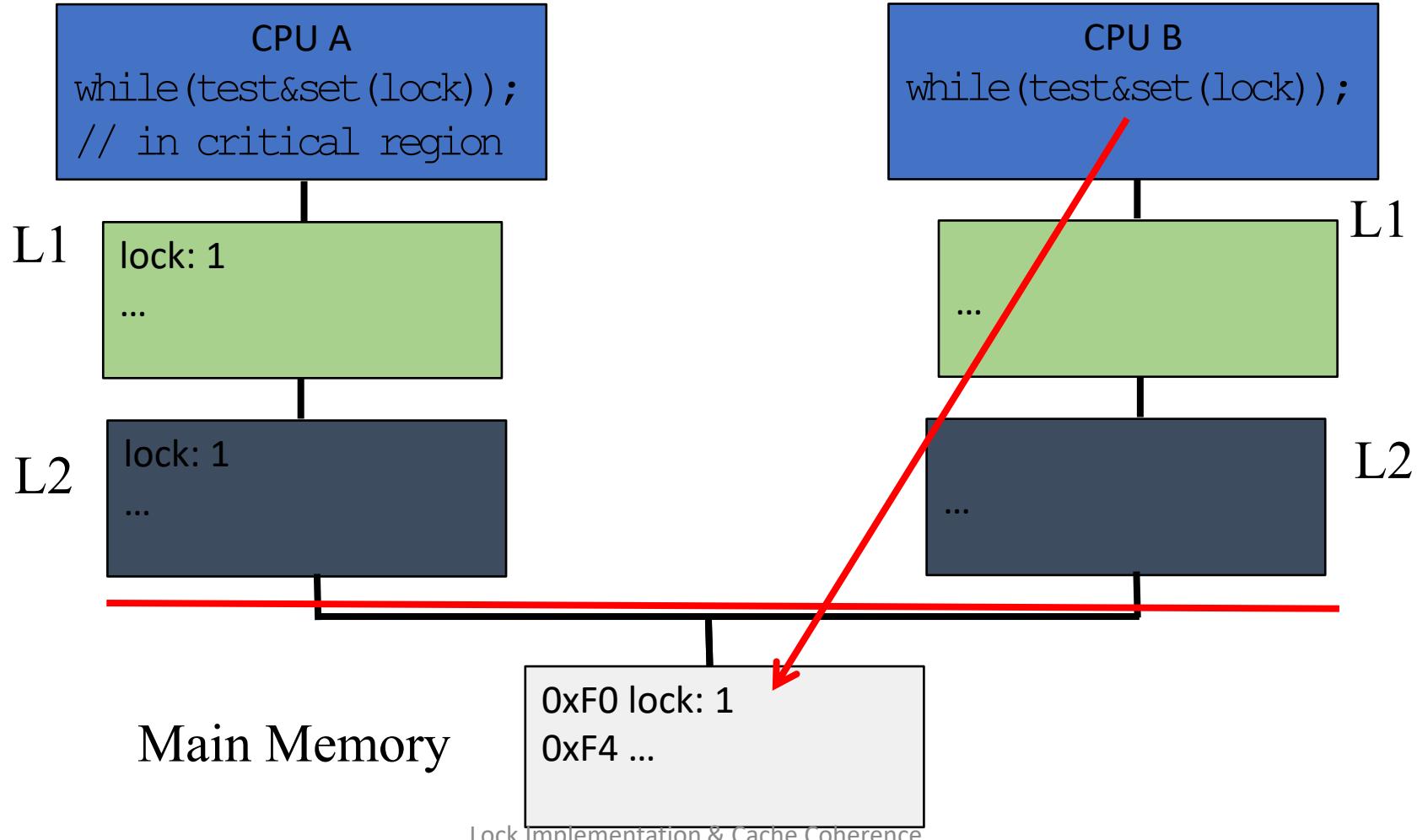
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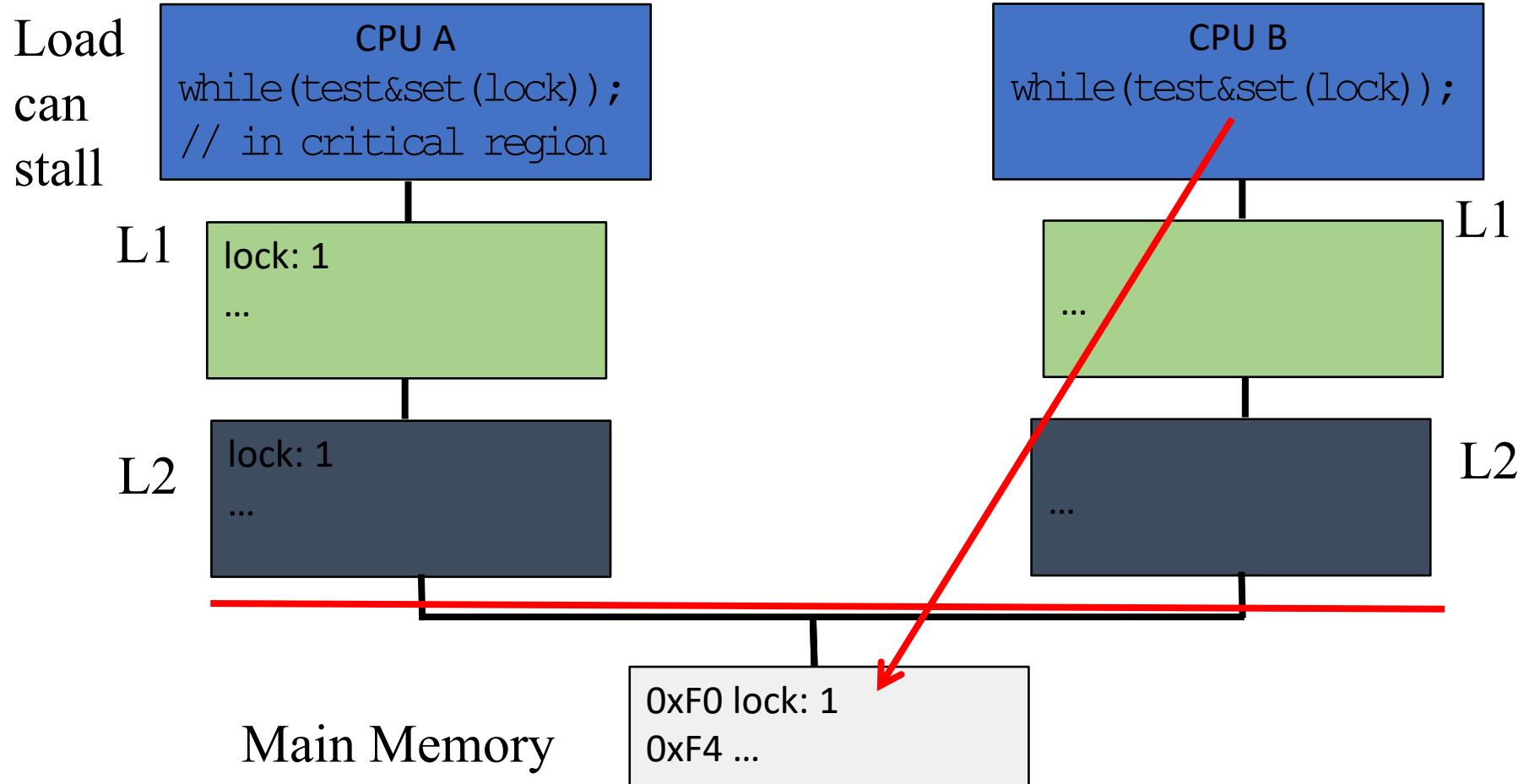
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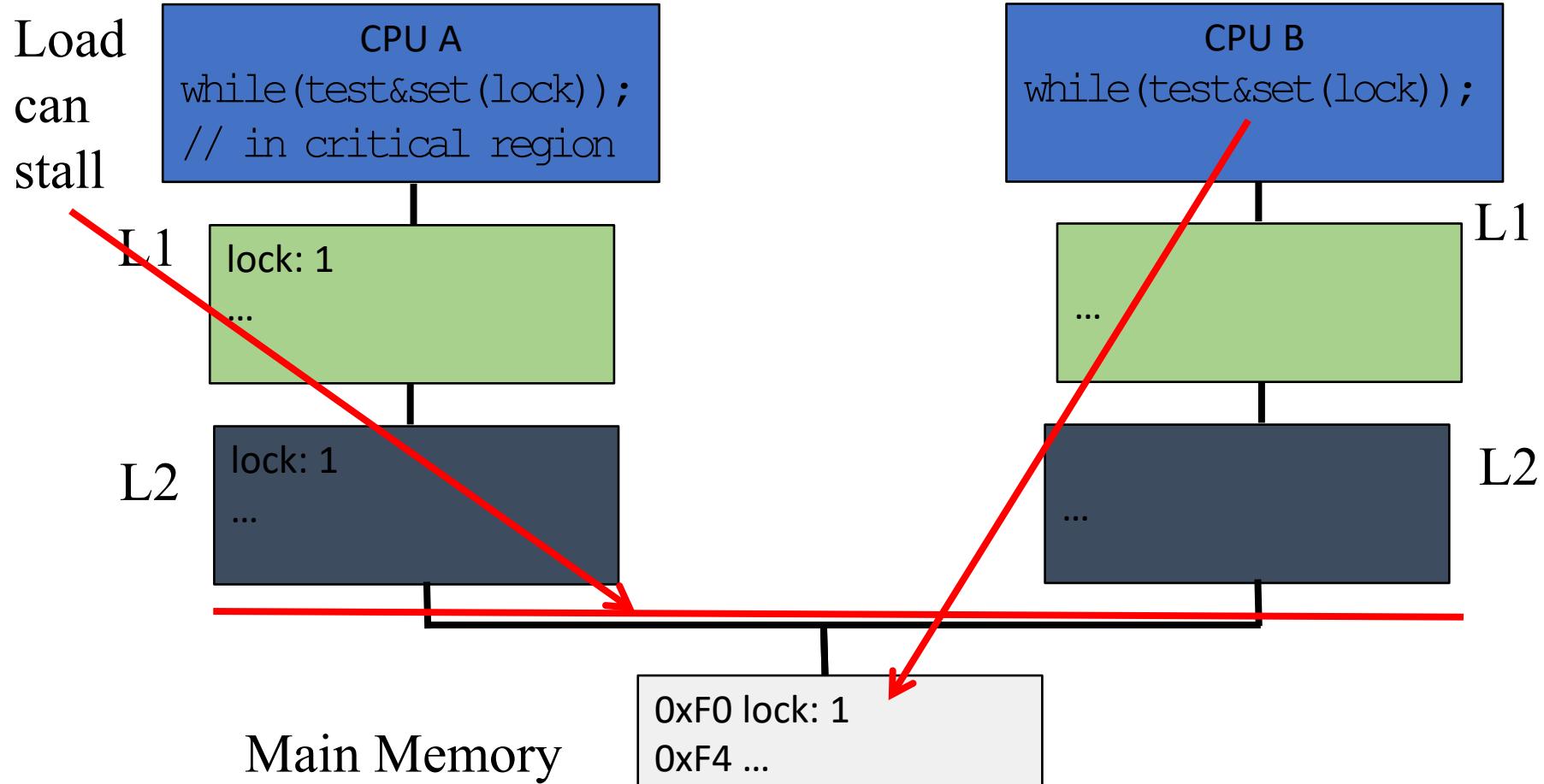
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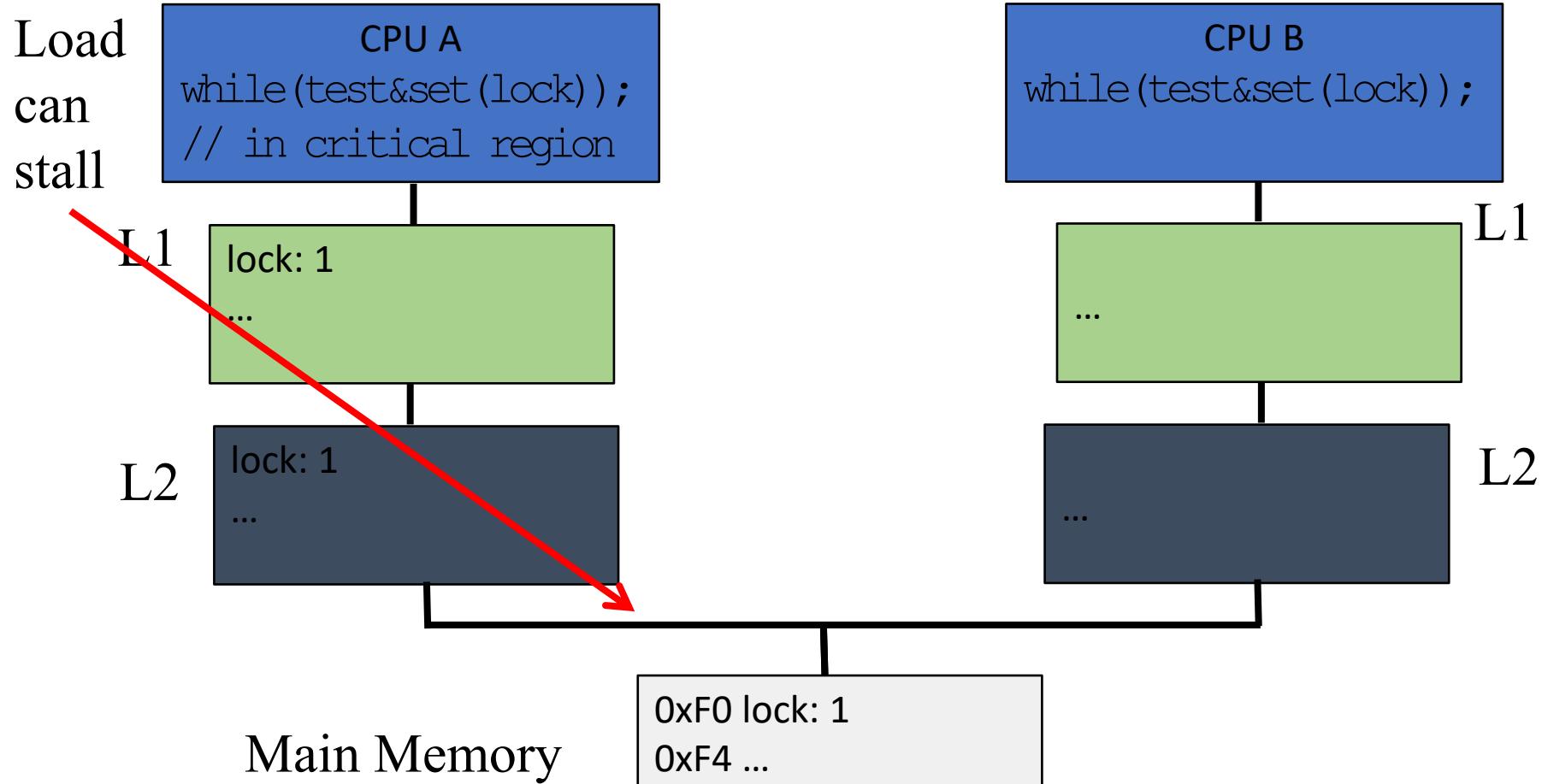
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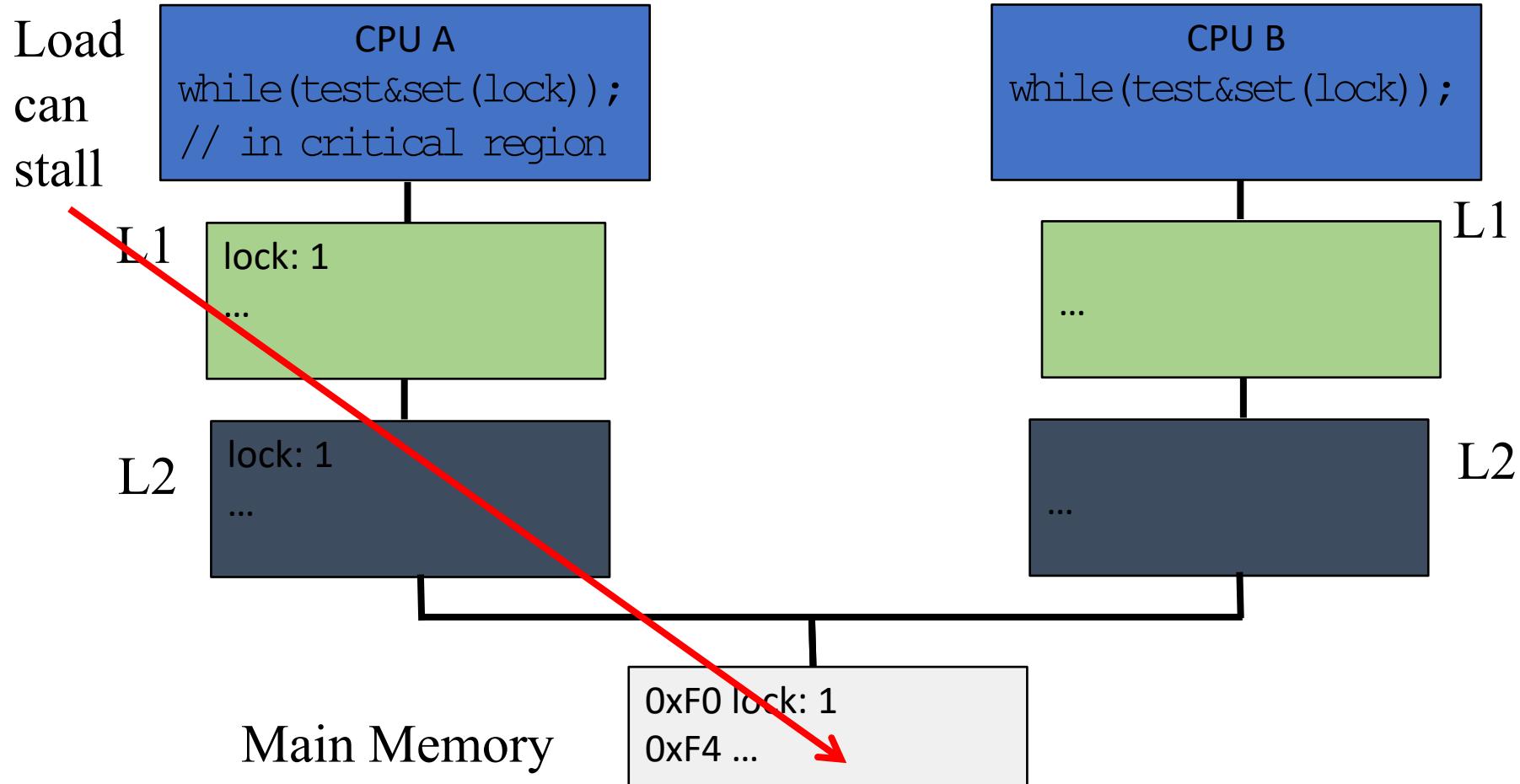
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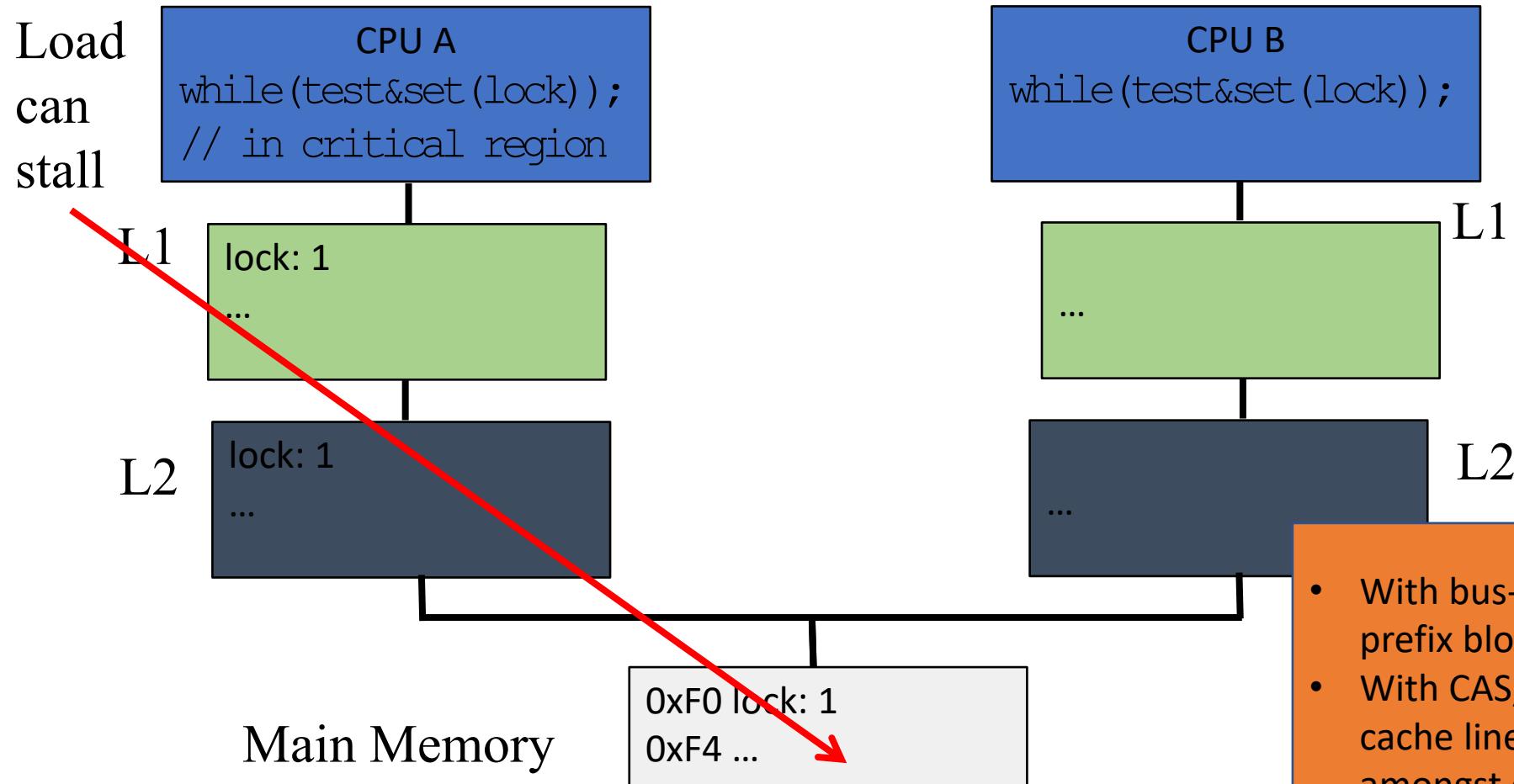
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Test & Set with Memory Hierarchies

Initially, lock already held by some other CPU—A, B busy-waiting

What happens to lock variable's cache line when different cpu's contend?



- With bus-locking, lock prefix blocks **everyone**
- With CAS, LL-SC, cache line cache line “ping pongs” amongst contenders

TTS: Reducing busy wait contention

Test&Set

```
Lock::Acquire() {  
    while (test&set(lock) == 1);  
}  
Lock::Release() {  
    *lock = 0;  
}
```

Busy-wait on in-memory copy

Test&Test&Set

```
Lock::Acquire() {  
    while(1) {  
        while (*lock == 1); // spin just reading  
        if (test&set(lock) == 0) break;  
    }  
}
```

Busy-wait on cached copy

TTS: Reducing busy wait contention

Test&Set

```
Lock::Acquire() {  
    while (test&set(lock) == 1);  
}
```

Busy-wait on in-memory copy

```
Lock::Release() {  
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```

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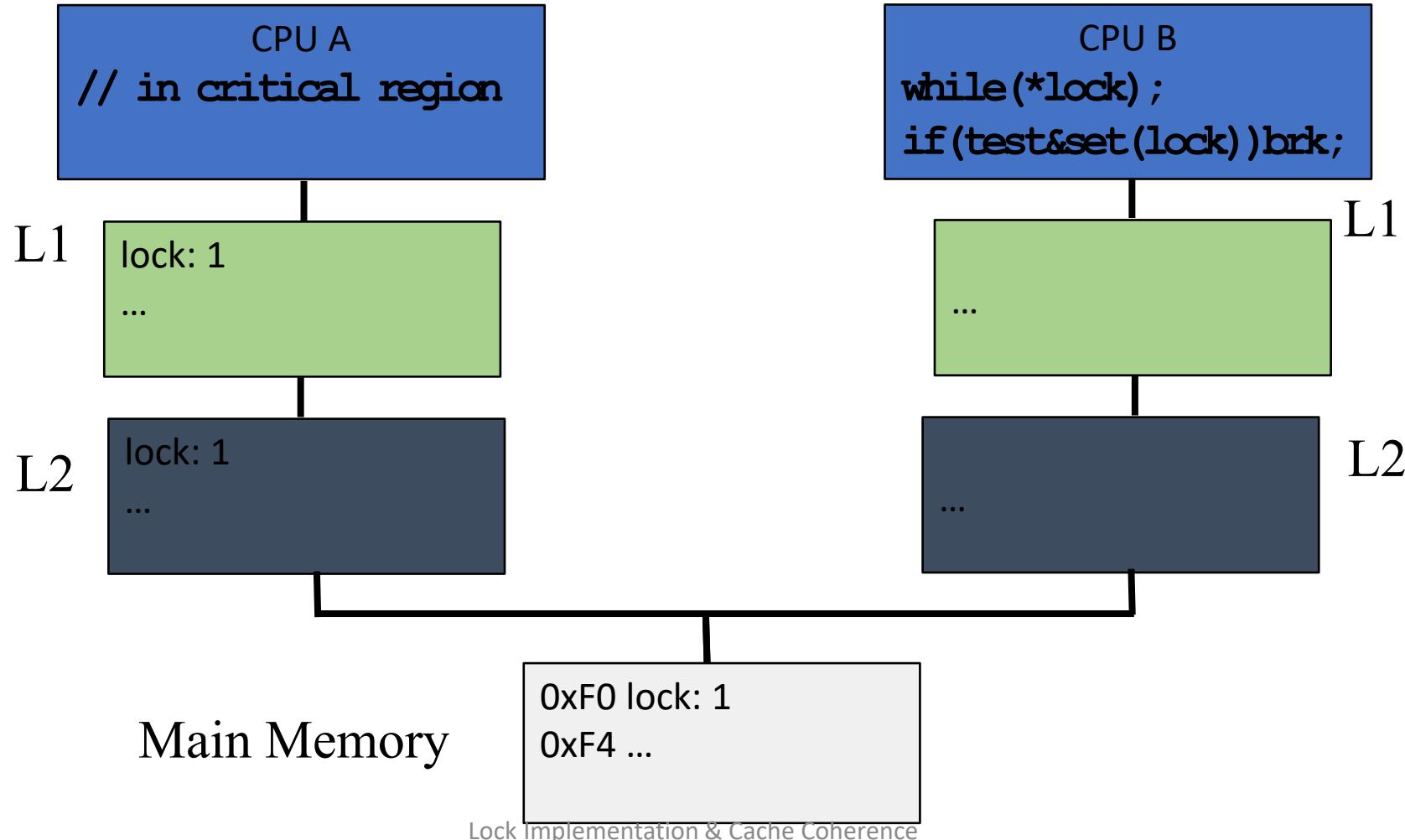
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}
```

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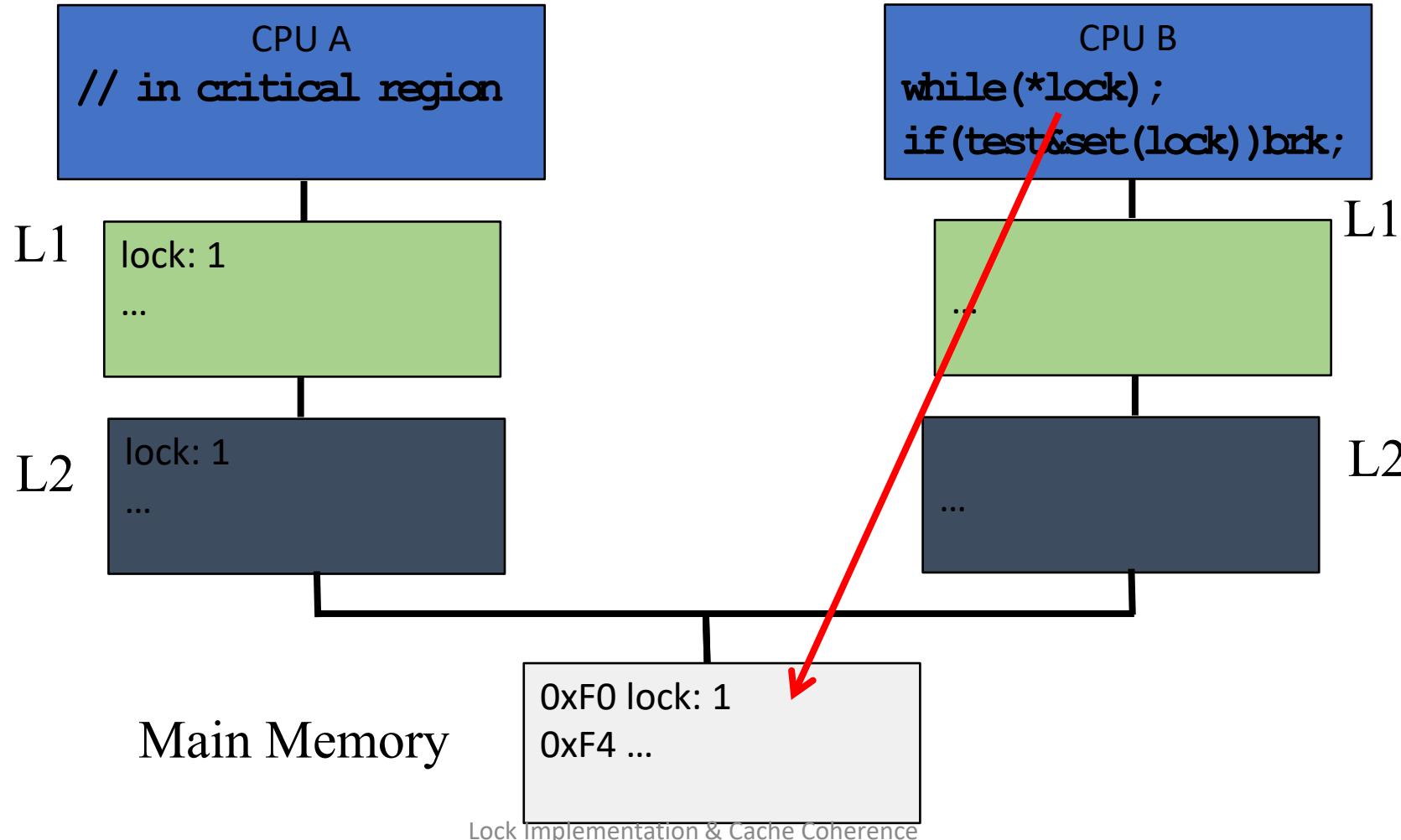
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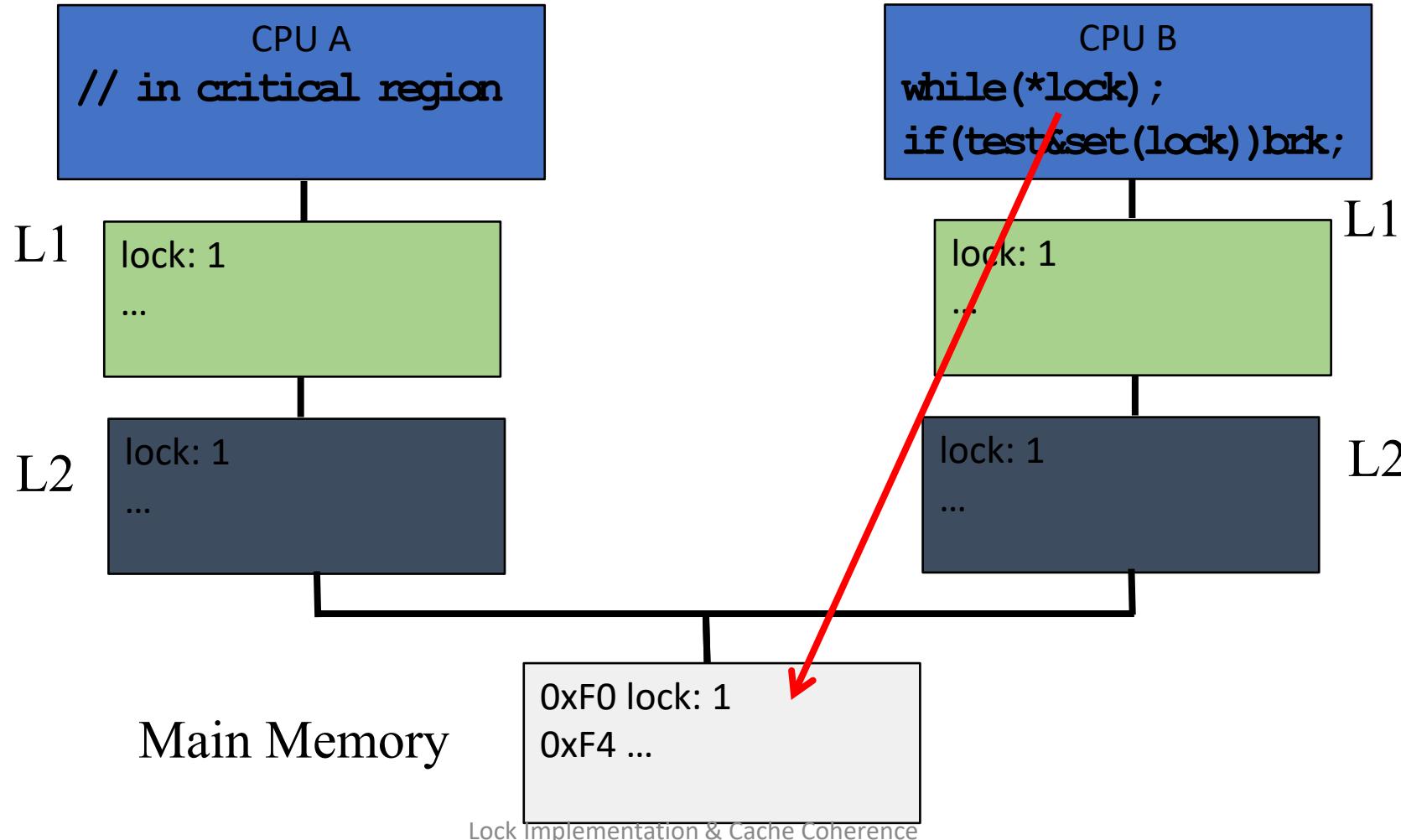
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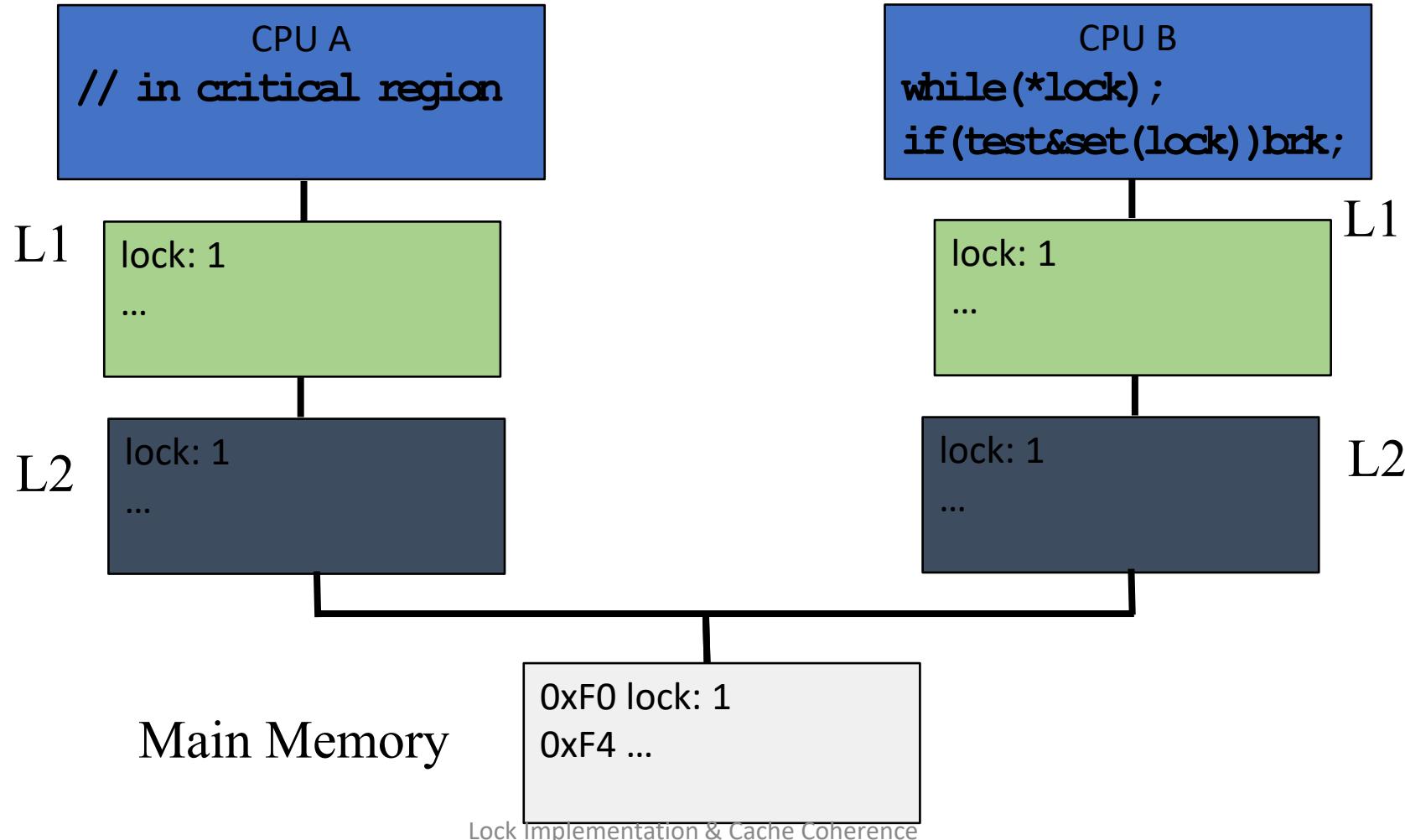
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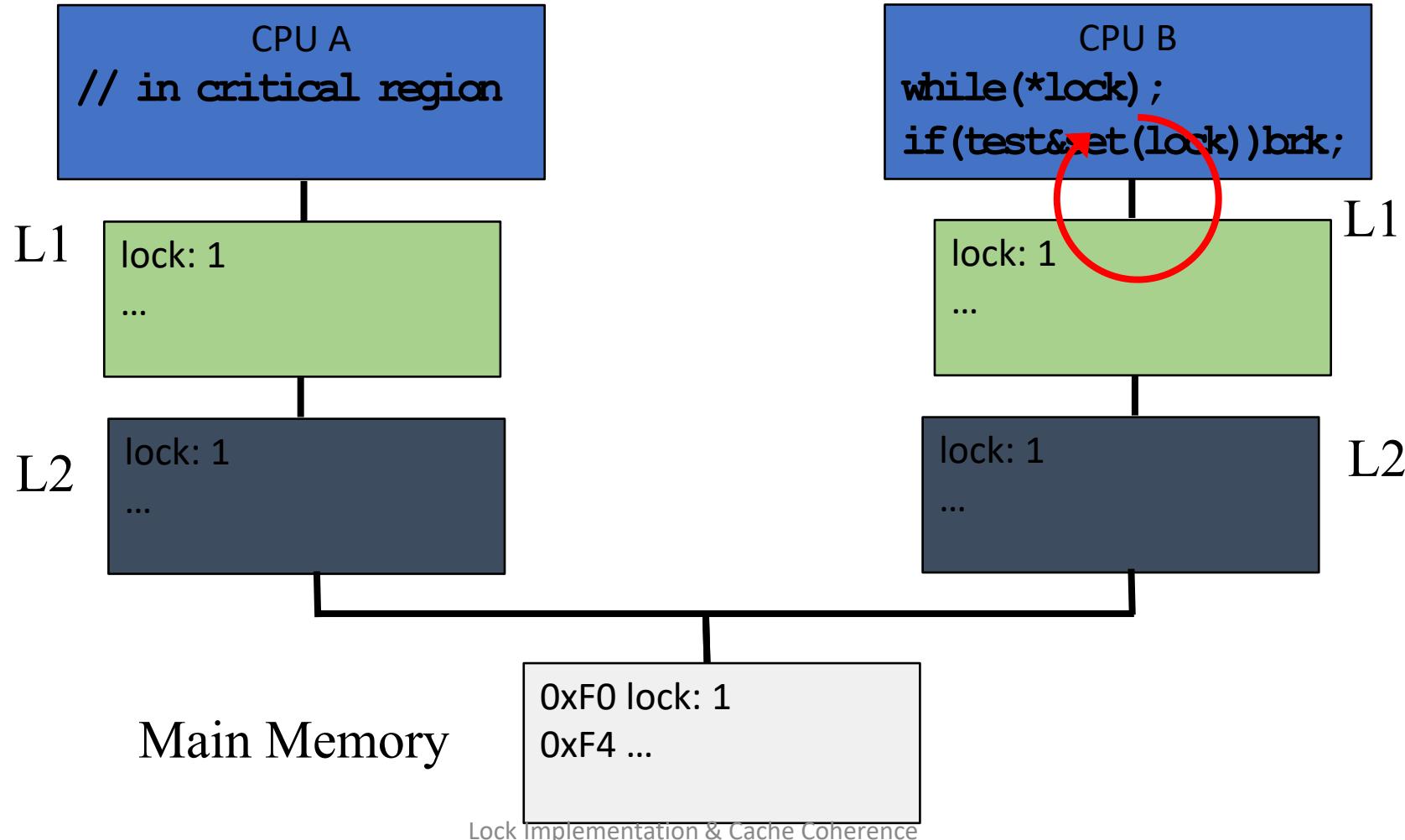
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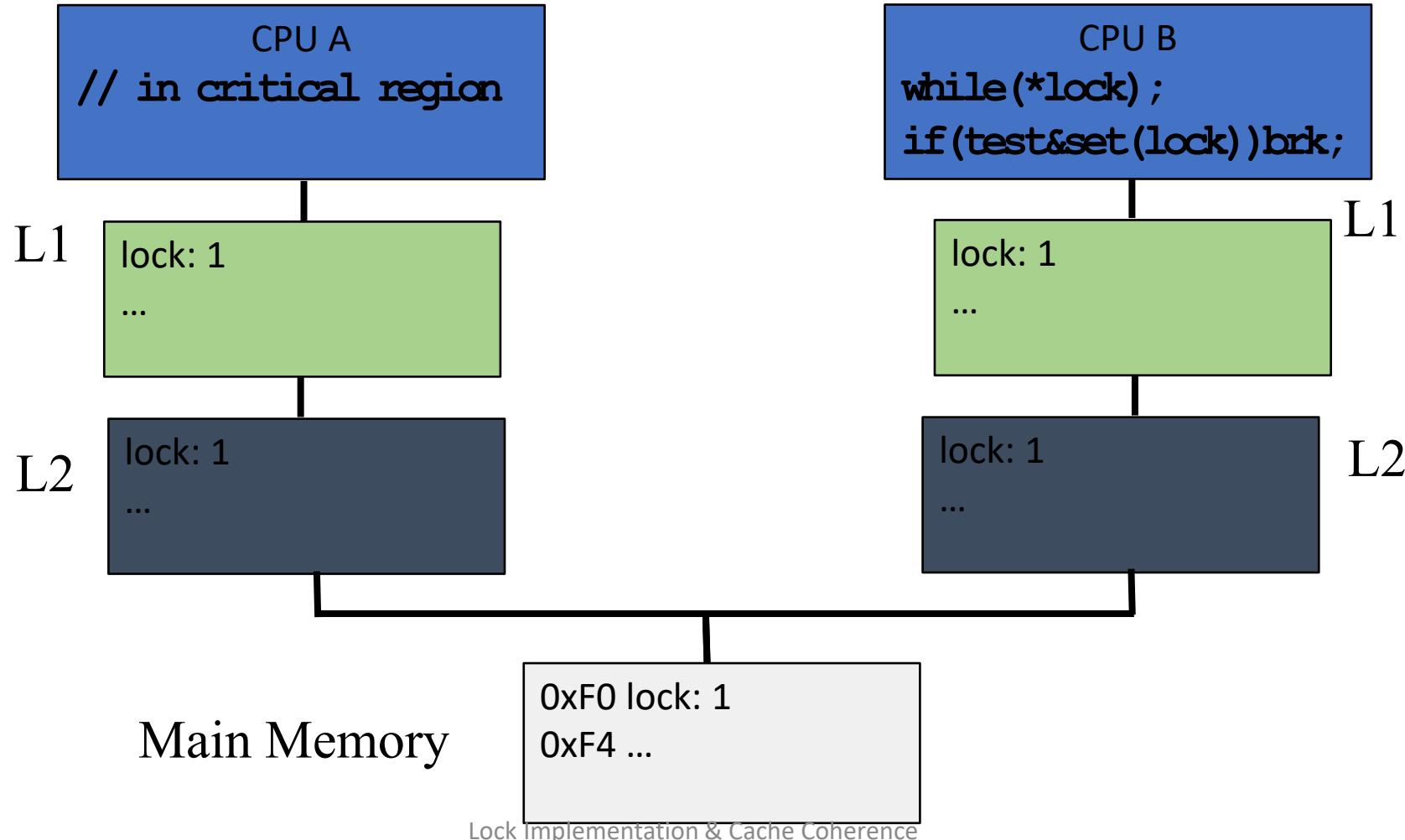
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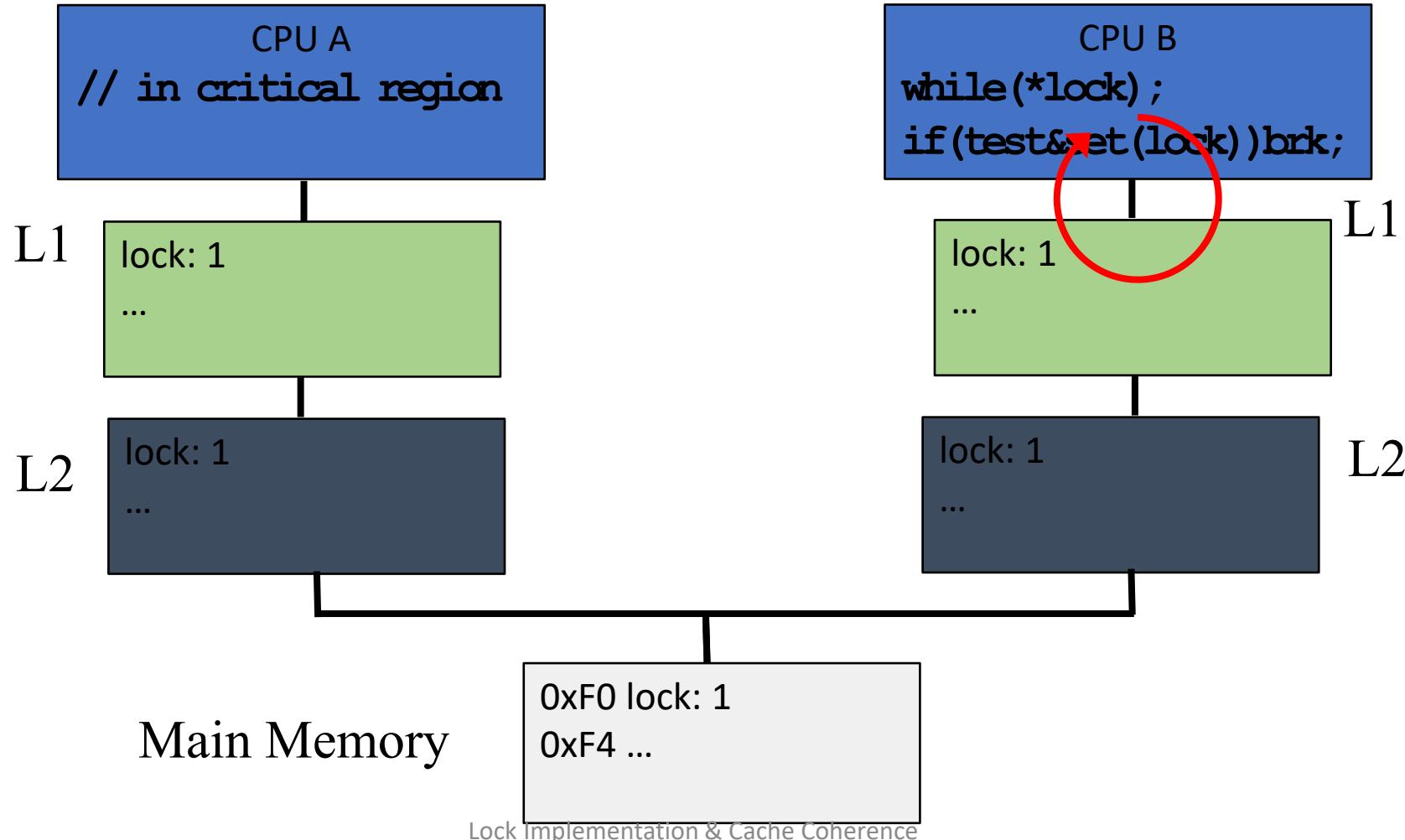
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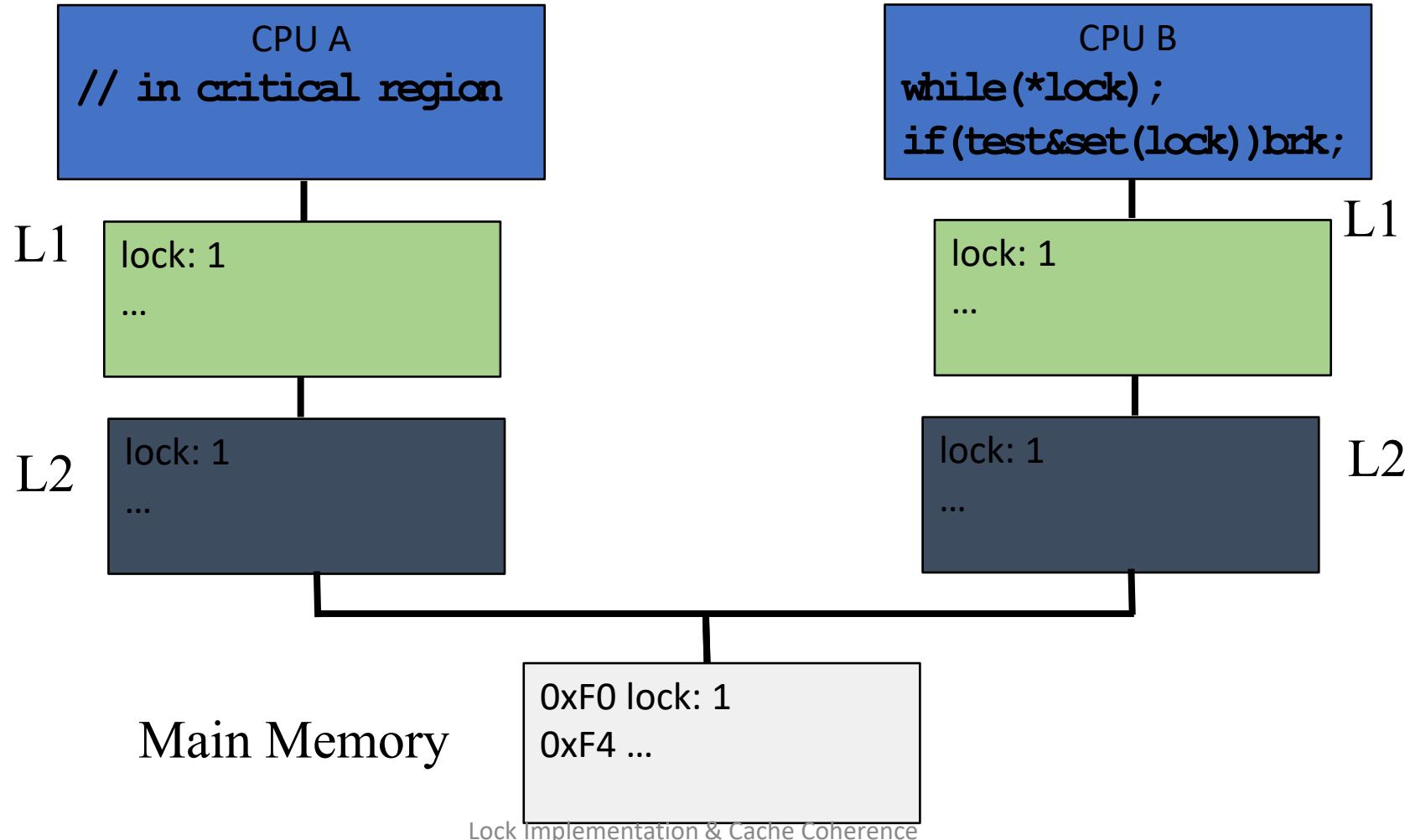
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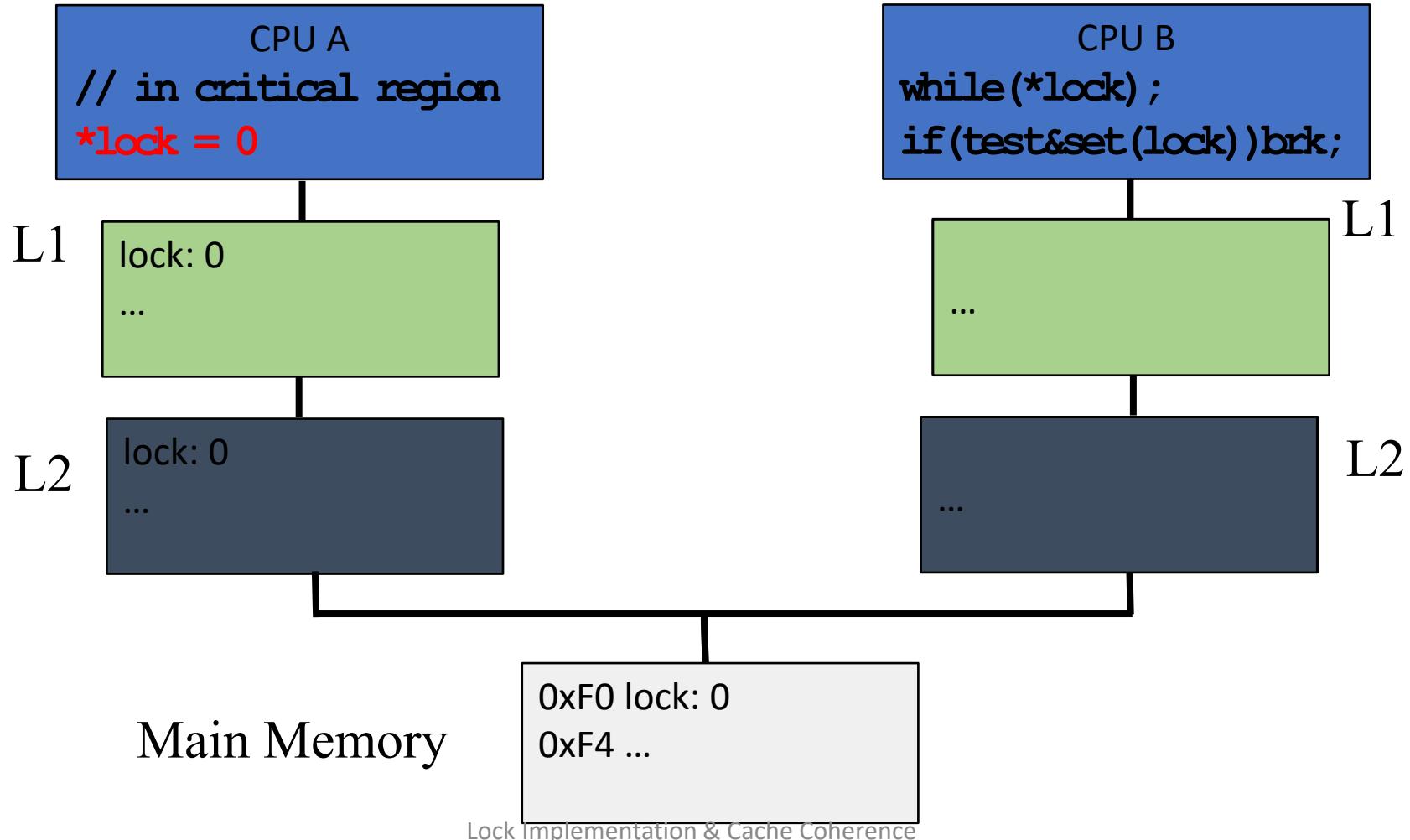
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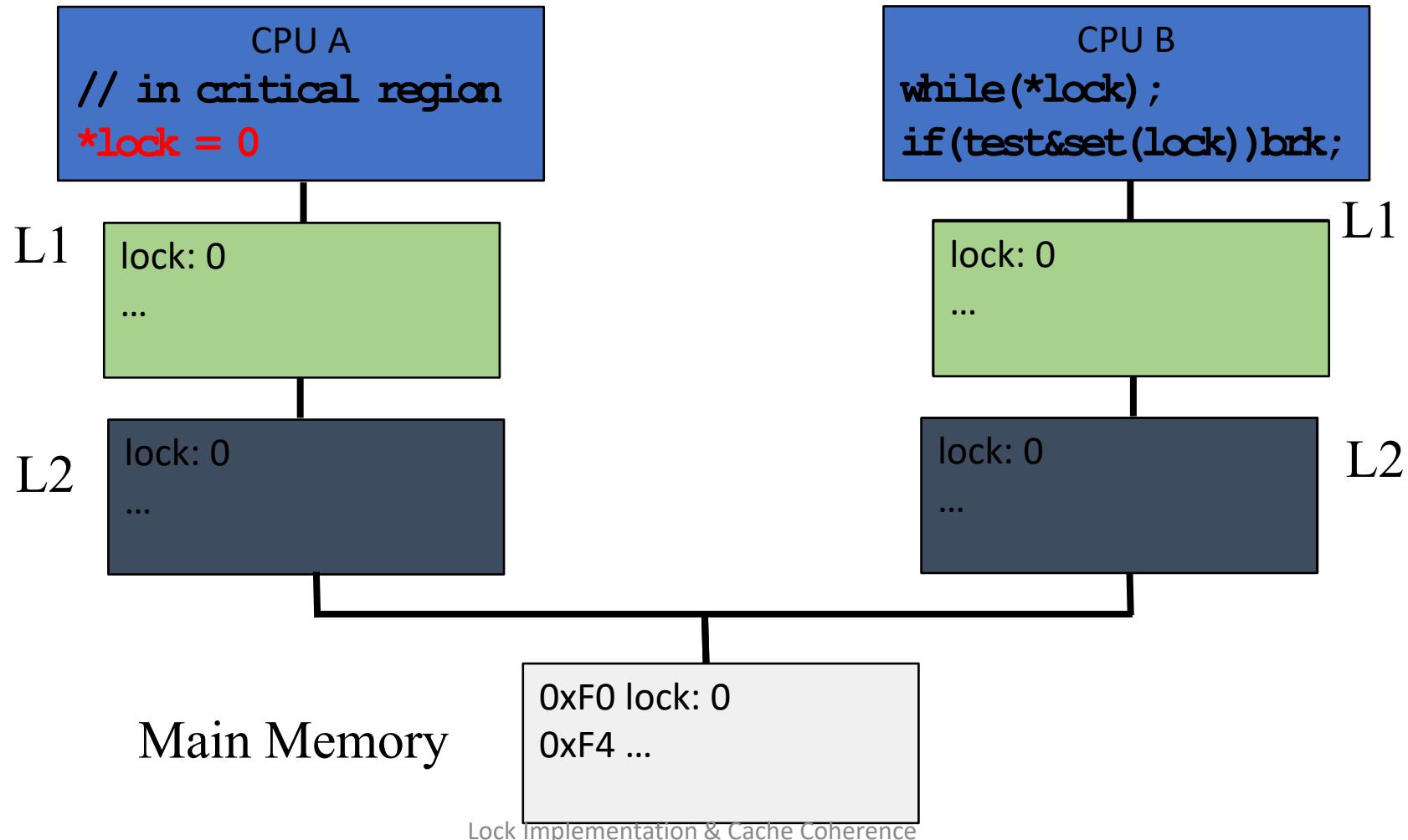
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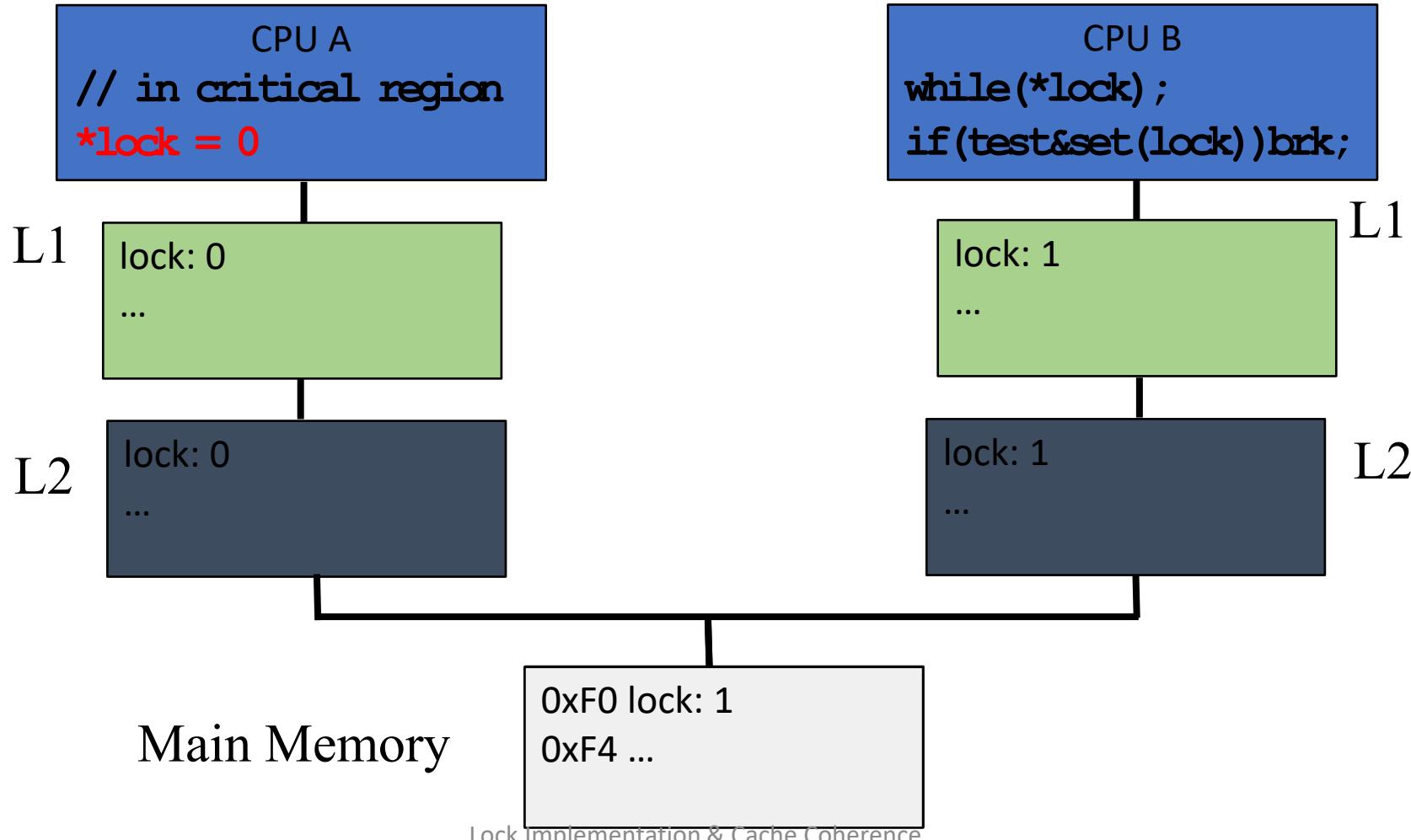
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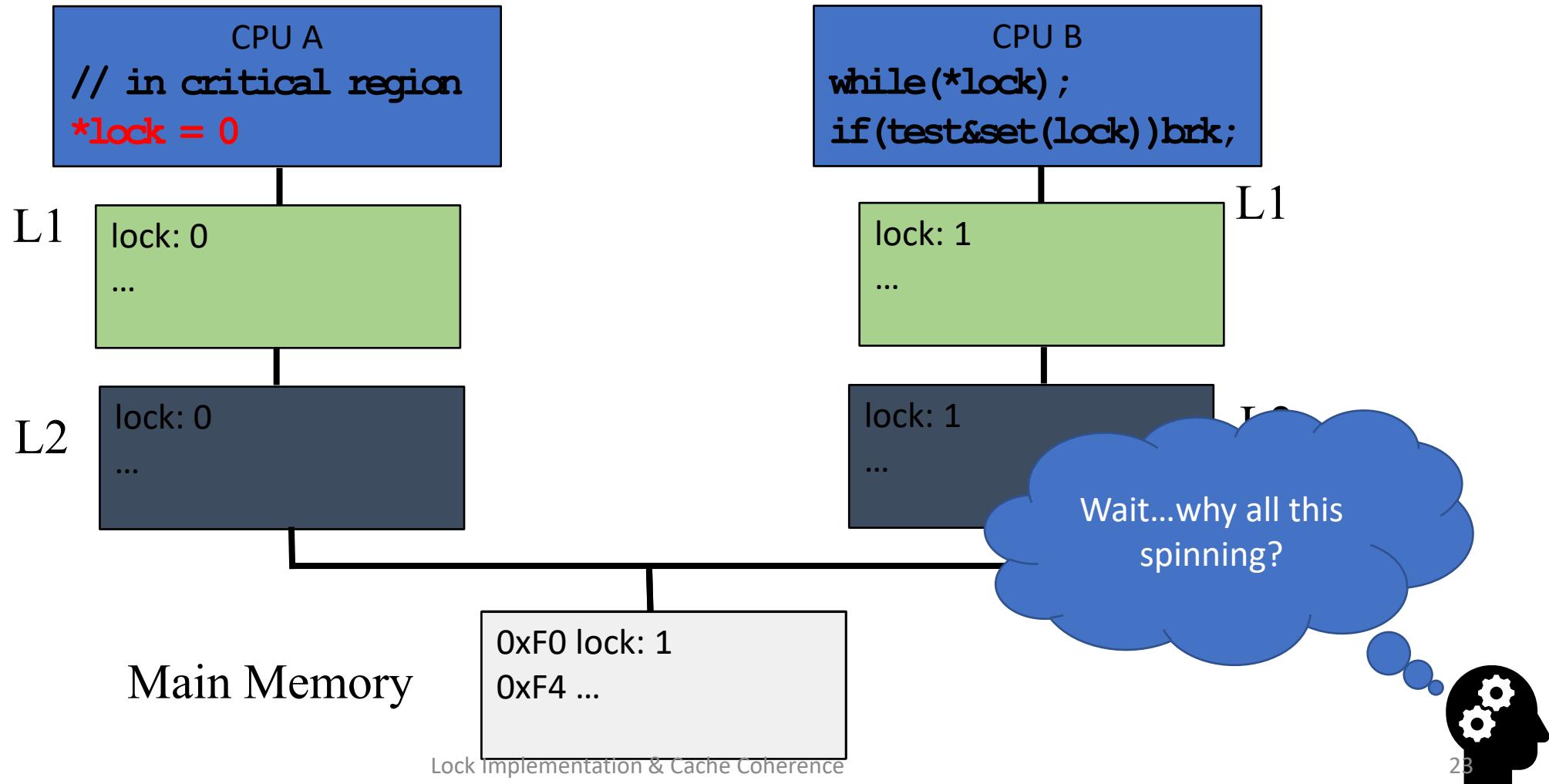
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Test & Test & Set with Memory Hierarchies

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How can we improve over busy-wait?

```
Lock::Acquire() {  
    while(1) {  
        while (*lock == 1); // spin just reading  
        if (test&set(lock) == 0) break;  
    }  
}
```

Mutex

- Same abstraction as spinlock
- But is a “blocking” primitive
 - Lock available → same behavior
 - Lock held → yield/block
- Many ways to yield
- Simplest case of semaphore

```
void cm3_lock(u8_t* M) {  
    u8_t LockedIn = 0;  
    do {  
        if (__LDREXB(Mutex) == 0) {  
            // unlocked: try to obtain lock  
            if (__STREXB(1, Mutex)) { // got lock  
                __CLREX(); // remove __LDREXB() lock  
                LockedIn = 1;  
            }  
            else task_yield(); // give away cpu  
        }  
        else task_yield(); // give away cpu  
    } while (!LockedIn);
```

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- Is it better to use a spinlock or mutex on a uni-processor?
- Is it better to use a spinlock or mutex on a multi-processor?

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```

- Is it better to use a spinlock or mutex on a uni-processor?
- Is it better to use a spinlock or mutex on a multi-processor?
- How do you choose between spinlock/mutex on a multi-processor?

Priority Inversion

A(prio-0) → enter(l);

B(prio-100) → enter(l); → must wait.

Solution?

Priority Inversion

A(prio-0) → enter(l);

B(prio-100) → enter(l); → must wait.

Solution?

Priority inheritance: A runs at B's priority

MARS pathfinder failure:

<http://wiki.csie.ncku.edu.tw/embedded/priority-inversion-on-Mars.pdf>

Other ideas?