Parallelism at Scale: MPI

Chris Rossbach and Calvin Lin

cs380p





Outline for Today

Scale MPI

Acknowledgements:

- Portions of the lectures slides were adopted from: Argonne National Laboratory, MPI tutorials. Lawrence Livermore National Laboratory, MPI tutorials
 - See online tutorial links in course webpage

intel

(intel

(intel

W. Gropp, E. Lusk, and A. Skjellum, Using MPI: Portable Parallel Programming with the Message Passing Interface, MIT Press, ISBN 0-262-57133-1, 1999.

W. Gropp, E. Lusk, and R. Thakur, Using MPI-2: Advanced Features of the Message Passing Interface, MIT Press, ISBN 0-262-57132-3, 1999.



Scale Out vs Scale Up









Vertical Scaling	Horizontal Scaling
Higher Capital Investment	On Demand Investment
Utilization concerns	Utilization can be optimized
Relatively Quicker and works with the current design	Relatively more time consuming and needs redesigning
Limiting Scale	Internet Scale

Hot Startup Idea:

1. User Browses Potential Pets



- 1. User Browses Potential Pets
- 2. Clicks "Purchase Pooch"



- 1. User Browses Potential Pets
- 2. Clicks "Purchase Pooch"
- 3. Web Server, CGI/EJB + Database complete request



- 1. User Browses Potential Pets
- 2. Clicks "Purchase Pooch"
- 3. Web Server, CGI/EJB + Database complete request
- 4. Pooch delivered (not shown)



- 1. User Browses Potential Pets
- 2. Clicks "Purchase Pooch"
- 3. Web Server, CGI/EJB + Database complete request
- 4. Pooch delivered (not shown)

How to handle lots and lots of dogs?







Web Servers App Servers



Web Servers (Presentation Tier) and App servers (Business Tier) scale *horizontally*

Web Servers App Servers



Web Servers App Servers



Web Servers App Servers



Web Servers App Servers











Web Servers (Presentation Tier) and Apr Database Server → scales vertically Horizontal Scale → "Shared Nothing" Why is this a good arrangement?

Vertical scale gets you a long way, but there is always a bigger problem size

zontally

Horizontal Scale: Goal






















Distributed Memory Multiprocessor

Messaging between nodes



Massively Parallel Processor (MPP) Many, many processors

Cluster of SMPs

- Shared memory in SMP
 node
- Messaging $\leftarrow \rightarrow$ SMP nodes



 also regarded as MPP if processor # is large

Distributed Memory Multiprocessor

Messaging between nodes



Massively Parallel Processor (MPP) Many, many processors

Cluster of SMPs

- Shared memory in SMP
 node
- Messaging $\leftarrow \rightarrow$ SMP nodes



 also regarded as MPP if processor # is large

Multicore SMP+GPU Cluster

- Shared mem in SMP node
- Messaging between nodes



GPU accelerators attached

Distributed Memory Cluster of SMPs Multiprocessor Messaging between nodes node • memory memory ... Μ processor processor interconnection network network interface processor processor ... memory memory ... Μ Massively Parallel Processor (MPP) also regarded Many, many processors processor # is

- Shared memory in SMP
- Messaging $\leftarrow \rightarrow$ SMP nodes

Multicore SMP+GPU Cluster

- Shared mem in SMP node
- Messaging between nodes ٠

000000





Simulations—why?

Simulations—why?

Simulations are sometimes more cost effective than experiments

Simulations—why?

Simulations are sometimes more cost effective than experiments Why extreme scale?

> More compute cycles, more memory, etc, lead for faster and/or more accurate simulations

Simulations—why?

Simulations are sometimes more cost effective than experiments Why extreme scale?

More compute cycles, more memory, etc, lead for faster and/or more accurate simulations







CS Climate Change Image credit: Prabhat, LBNL Astrophysics

How big is "extreme" scale?

Measured in FLOPs

FLoating point Operations Per second 1 GigaFLOP = 1 billion FLOPs 1 TeraFLOP = 1000 GigaFLOPs 1 PetaFLOP = 1000 TeraFLOPs Most current super computers 1 ExaFLOP = 1000 PetaFLOPs Arriving in 2018 (supposedly)



How big is "extreme" scale?

Measured in FLOPs

Rank	System	Cores	Rmax (TFlop/s)	Rpeak (TFlop/s)	Power (kW)
1	Sunway TaihuLight - Sunway MPP, Sunway SW26010 260C 1.45GHz, Sunway , NRCPC National Supercomputing Center in Wuxi China	10,649,600	93,014.6	125,435.9	15,371
2	Tianhe-2 (MilkyWay-2) - TH-IVB-FEP Cluster, Intel Xeon E5-2692 12C 2.200GHz, TH Express-2, Intel Xeon Phi 31S1P , NUDT National Super Computer Center in Guangzhou China	3,120,000	33,862.7	54,902.4	17,808
3	Piz Daint - Cray XC50, Xeon E5-2690v3 12C 2.6GHz, Aries interconnect , NVIDIA Tesla P100 , Cray Inc. Swiss National Supercomputing Centre (CSCS) Switzerland	361,760	19,590.0	25,326.3	2,272
4	Gyoukou - ZettaScaler-2.2 HPC system, Xeon D-1571 16C 1.3GHz, Infiniband EDR, PEZY-SC2 700Mhz , ExaScaler Japan Agency for Marine-Earth Science and Technology Japan	19,860,000	19,135.8	28,192.0	1,350
5	Titan - Cray XK7, Opteron 6274 16C 2.200GHz, Cray Gemini interconnect, NVIDIA K20x , Cray Inc. DOE/SC/Oak Ridge National Laboratory United States	560,640	17,590.0	27,112.5	8,209
6	Sequoia - BlueGene/Q, Power BQC 16C 1.60 GHz, Custom , IBM D0E/NNSA/LLNL	1,572,864	17,173.2	20,132.7	7,890



How big is "extreme" scale?

Measured in FLOPs

	System	Cores	Rmax	Rpeak (TFlop/s)	Power (kW)	
1	Sunway TaihuLight - Sunway MPP, Sunway SW26010 260C 1.45GHz, Sunway , NRCPC National Supercomputing Center in Wuxi China	\subset	014.6	125,435.9	15,371	Performance of over 10 Peta
2	Tianhe-2 (MilkyWay-2) - TH-IVB-FEP Cluster, Intel Xeon E5-2692 12C 2.200GHz, TH Express-2, Intel Xeon Phi 31S1P , NUDT National Super Computer Center in Guangzhou China	3,120,000	33,862.7	54,902.4	17,808	Hoating point number operations per second (10 Peta=10,000,000,000,000)
3	Piz Daint - Cray XC50, Xeon E5-2690v3 12C 2.6GHz, Aries interconnect , NVIDIA Tesla P100 , Cray Inc. Swiss National Supercomputing Centre (CSCS) Switzerland	361,760	19,590.0	25,326.3	2,272	থাKEN K / Kei computer 4 on Top500.org, 10PFLOPs
4	Gyoukou - ZettaScaler-2.2 HPC system, Xeon D-1571 16C 1.3GHz, Infiniband EDR, PEZY-SC2 700Mhz , ExaScaler Japan Agency for Marine-Earth Science and Technology Japan	19,860,000	19,135.8	28,192.0	1,350	
5	Titan - Cray XK7, Opteron 6274 16C 2.200GHz, Cray Gemini interconnect, NVIDIA K20x , Cray Inc. DOE/SC/Oak Ridge National Laboratory United States	560,640	17,590.0	27,112.5	8,209	RNL Titan
6	Sequoia - BlueGene/Q, Power BQC 16C 1.60 GHz, Custom , IBM DOE/NNSA/LLNL	1,572,864	17,173.2	20,132.7	7,890	on Top500.org, 27 PFLOPS

#3 on Top500.org, 20 PFLOPs 880 LOPs

LLNL Sequoia





- Nodes: complete computer
 - Including I/O
- Nodes communicate via network
 - Standard networks (IP)
 - Specialized networks (RDMA, fiber)

Each processor has a local memory Physically separated address space



- Nodes: complete computer
 - Including I/O
- Nodes communicate via network
 - Standard networks (IP)
 - Specialized networks (RDMA, fiber)

Each processor has a local memory Physically separated address space Processors communicate to access non-local data

Message communication Message passing architecture Processor interconnection network



Network interface

- Nodes: complete computer
 - Including I/O
- Nodes communicate via network
 - Standard networks (IP)
 - Specialized networks (RDMA, fiber)

Each processor has a local memory Physically separated address space Processors communicate to access non-local data

Message communication *Message passing architecture* Processor interconnection network

Parallel applications partitioned across

Processors: execution units Memory: data partitioning



Network interface

- Nodes: complete computer
 - Including I/O
- Nodes communicate via network
 - Standard networks (IP)
 - Specialized networks (RDMA, fiber)

Each processor has a local memory Physically separated address space Processors communicate to access non-local data

> Message communication Message passing architecture Processor interconnection network

Parallel applications partitioned across

Processors: execution units

Memory: data partitioning

Scalable architecture

Incremental cost to add hardware (cost of node)



Network interface

- Nodes: complete computer
 - Including I/O
- Nodes communicate via network
 - Standard networks (IP)
 - Specialized networks (RDMA, fiber)

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and processor Network interface speed vs. network bisection bandwidth

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and proce Network interface speed vs. network bisection bandwidth

Wait...bisection bandwidth?

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and proce Network interface speed vs. network bisecti bandwidth

Wait...bisection bandwidth?

if network is bisected, bisection
bandwidth == bandwidth

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and proce Network interface speed vs. network bisection bandwidth

Wait...bisection bandwidth?

if network is bisected, bisection
bandwidth == bandwidth
between the two partitions

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and proce Network interface speed vs. network bisecti bandwidth

Wait...bisection bandwidth?

if network is bisected, bisection
bandwidth == bandwidth
between the two partitions



Bandwidth

Need high bandwidth in communication Match limits in network, memory, and processor Network interface speed vs. network bisection bandwidth

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and processor Network interface speed vs. network bisection bandwidth

Latency

Performance affected: processor may have to wait Hard to overlap communication and computation Overhead to communicate: a problem in many machines

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and processor Network interface speed vs. network bisection bandwidth

Latency

Performance affected: processor may have to wait Hard to overlap communication and computation Overhead to communicate: a problem in many machines

Latency hiding

Increases programming system burden

E.g.: communication/computation overlap, prefetch

Bandwidth

Need high bandwidth in communication Match limits in network, memory, and processor Network interface speed vs. network bisection bandwidth

Latency

Performance affected: processor may have to wait Hard to overlap communication and computation Overhead to communicate: a problem in many machines

Latency hiding

Increases programming system burden

E.g.: communication/computation overlap, prefetch

Is this different from metrics we've cared about so far?

Hardware simpler (especially versus NUMA), more scalable

Hardware simpler (especially versus NUMA), more scalable Communication explicit, simpler to understand

Hardware simpler (especially versus NUMA), more scalable
 Communication explicit, simpler to understand
 Explicit communication →
 focus attention on costly aspect of parallel computation

Hardware simpler (especially versus NUMA), more scalable

Communication explicit, simpler to understand

Explicit communication \rightarrow

focus attention on costly aspect of parallel computation

Synchronization \rightarrow

naturally associated with sending messages reduces possibility for errors from incorrect synchronization

Hardware simpler (especially versus NUMA), more scalable

Communication explicit, simpler to understand

Explicit communication \rightarrow

focus attention on costly aspect of parallel computation

Synchronization \rightarrow

naturally associated with sending messages reduces possibility for errors from incorrect synchronization

Easier to use sender-initiated communication → some advantages in performance

Hardware simpler (especially versus NUMA), more scalable

Communication explicit, simpler to understand

Explicit communication \rightarrow

focus attention on costly aspect of parallel computation

Synchronization \rightarrow

naturally associated with sending messages reduces possibility for errors from incorrect synchronization

Easier to use sender-initiated communication → some advantages in performance

Can you think of any *disadvantages*?
- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

Sometimes 1 job takes whole machine These are called "hero runs"...

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

Sometimes 1 job takes whole machine These are called "hero runs"... Sometimes many smaller jobs

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Scheduler runs scripts that initialize the environment
 - Typically done with environment variables

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Scheduler runs scripts that initialize the environment
 - Typically done with environment variables
- At the end of initialization, it is possible to infer:
 - What the desired job configuration is (i.e., how many tasks per node)
 - What other nodes are involved
 - How your node's tasks relates to the overall program

- Programmer plans a *job*; job ==
 - parallel binary program
 - "input deck" (specifies input data)
- Submit job to a *queue*
- Scheduler allocates resources when
 - resources are available,
 - (or) the job is deemed "high priority"

- Scheduler runs scripts that initialize the environment
 - Typically done with environment variables
- At the end of initialization, it is possible to infer:
 - What the desired job configuration is (i.e., how many tasks per node)
 - What other nodes are involved
 - How your node's tasks relates to the overall program
- MPI library interprets this information, hides the details

Process: a program counter and address space

Processes: multiple threads sharing a single address space



Not threads

Inter-process communication consists of

Synchronization

Data movement

Process: a program counter and address space

Processes: multiple threads sharing a single address space



Inter-process communication consists of

Synchronization

Data movement

How does this compare with CSP?

Process: a program counter and address space

Pro MPI Inte UJF !

Process: a program counter and address space

Proc • MPI == Message-Passing Interface specification

- Extended message-passing model
- Not a language or compiler specification
- Not a specific implementation or product

MPI



Process: a program counter and address space

Proc • MPI == Message-Passing Interface specification

CJT !

- Extended message-passing model
- Not a language or compiler specification
- Not a specific implementation or product
- Specified in C, C++, Fortran 77, F90

MPI

Process: a program counter and address space

Prof • MPI == Message-Passing Interface specification

- Extended message-passing model
- Not a language or compiler specification
- Not a specific implementation or product
- Specified in C, C++, Fortran 77, F90
- Message Passing Interface (MPI) Forum
 - <u>http://www.mpi-forum.org/</u>
 - <u>http://www.mpi-forum.org/docs/docs.html</u>



Process: a program counter and address space

Prof • MPI == Message-Passing Interface specification

- Extended message-passing model
- Not a language or compiler specification
- Not a specific implementation or product
- Specified in C, C++, Fortran 77, F90
- Message Passing Interface (MPI) Forum
 - <u>http://www.mpi-forum.org/</u>
 - <u>http://www.mpi-forum.org/docs/docs.html</u>
 - Two flavors for communication
 - Cooperative operations
 - One-sided operations

MPI







Data is cooperatively exchanged in message-passing





Data is cooperatively exchanged in message-passing Explicitly sent by one process and received by another



Data is cooperatively exchanged in message-passing Explicitly sent by one process and received by another Advantage of local control of memory

Change in the receiving process's memory made with receiver's explicit participation



Data is cooperatively exchanged in message-passing Explicitly sent by one process and received by another Advantage of local control of memory

Change in the receiving process's memory made with receiver's explicit participation

Communication and synchronization are combined



Data is cooperatively exchanged in message-passing Explicitly sent by one process and received by another Advantage of local control of memory

Change in the receiving process's memory made with receiver's explicit participation

Communication and synchronization are combined



One-Sided Operations

One-Sided Operations





One-sided operations between processes Include remote memory reads and writes





One-sided operations between processes Include remote memory reads and writes Only one process needs to explicitly participate There is still agreement implicit in the SPMD program



One-Sided Operations

One-sided operations between processes Include remote memory reads and writes Only one process needs to explicitly participate There is still agreement implicit in the SPMD program Implication:

Communication and synchronization are decoupled





Are 1-sided operations better for performance?

One-sided operations between processes Include remote memory reads and writes Only one process needs to explicitly participate There is still agreement implicit in the SPMD program Implication:

Communication and synchronization are decoupled



A Simple MPI Program

```
#include "mpi.h"
```

#include <stdio.h>

```
int main( int argc, char *argv[] )
{
```

```
MPI_Init( &argc, &argv );
printf( "Hello, world!\n" );
MPI_Finalize();
return 0;
```





Hardware resources allocated MPI-managed ones anyway...



Hardware resources allocated
MPI-managed ones anyway...
Start processes on different nodes
Where does their executable program come from?



Hardware resources allocated MPI-managed ones anyway...
Start processes on different nodes Where does their executable program come from?
Give processes what they need to know Wait...what do they need to know?



Hardware resources allocated MPI-managed ones anyway...
Start processes on different nodes Where does their executable program come from?
Give processes what they need to know Wait...what do they need to know?
Configure OS-level resources


Hardware resources allocated MPI-managed ones anyway...
Start processes on different nodes Where does their executable program come from?
Give processes what they need to know Wait...what do they need to know?
Configure OS-level resources
Configure tools that are running with MPI



Hardware resources allocated MPI-managed ones anyway...
Start processes on different nodes Where does their executable program come from?
Give processes what they need to know Wait...what do they need to know?
Configure OS-level resources
Configure tools that are running with MPI

•••





Why do we need to finalize MPI?



Why do we need to finalize MPI? What is necessary for a "graceful" MPI exit? Can bad things happen otherwise? Suppose one process exits...



Why do we need to finalize MPI?
What is necessary for a "graceful" MPI exit?
Can bad things happen otherwise?
Suppose one process exits...
How do resources get de-allocated?









• By default, an error causes all processes to abort



- By default, an error causes all processes to abort
- The user can cause routines to return (with an error code)
 - In C++, exceptions are thrown (MPI-2)



- By default, an error causes all processes to abort
- The user can cause routines to return (with an error code)
 - In C++, exceptions are thrown (MPI-2)
- A user can also write and install custom error handlers



- By default, an error causes all processes to abort
- The user can cause routines to return (with an error code)
 - In C++, exceptions are thrown (MPI-2)
- A user can also write and install custom error handlers
- Libraries may handle errors differently from applications

MPI-1 does not specify how to run an MPI program

MPI-1 does not specify how to run an MPI program Starting an MPI program is dependent on implementation Scripts, program arguments, and/or environment variables

MPI-1 does not specify how to run an MPI program
 Starting an MPI program is dependent on implementation
 Scripts, program arguments, and/or environment variables
 % mpirun -np <procs> a.out
 For MPICH under Linux

MPI-1 does not specify how to run an MPI program

Starting an MPI program is dependent on implementation

Scripts, program arguments, and/or environment variables

% mpirun -np <procs> a.out

For MPICH under Linux

mpiexec <args>

Recommended part of MPI-2, as a recommendation **mpiexec** for MPICH (distribution from ANL) **mpirun** for SGI's MPI

Finding Out About the Environment

Finding Out About the Environment

Two important questions that arise in message passing How many processes are being use in computation? Which one am I?

Finding Out About the Environment

Two important questions that arise in message passing How many processes are being use in computation? Which one am I?

MPI provides functions to answer these questions

MPI_Comm_size reports the number of processes

MPI_Comm_rank reports the rank number between 0 and size-1 identifies the calling process

Hello World Revisited

#include "mpi.h"

#include <stdio.h>

```
int main( int argc, char *argv[] )
{
    int rank, size;
    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &rank );
    MPI_Comm_size( MPI_COMM_WORLD, &size );
    printf( "I am %d of %d\n", rank, size );
    MPI_Finalize();
    return 0;
```

Hello World Revisited

#include "mpi.h"

#include <stdio.h>

```
int main( int argc, char *argv[] )
{
    int rank, size;
    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &rank );
    MPI_Comm_size( MPI_COMM_WORLD, &size );
    printf( "I am %d of %d\n", rank, size );
    MPI_Finalize();
    return 0;
}
```

□ What does this program do?

Hello World Revisited

#include "mpi.h"

#include <stdio.h>

```
int main( int argc, char *argv[] )
{
    int rank, size;
    MPI_Init( &argc, &argv );
    MPI_Comm_rank( MPI_COMM_WORLD, &rank );
    MPI_Comm_size( MPI_COMM_WORLD, &size );
    printf( "I am %d of %d\n", rank, size );
    MPI_Finalize();
    return 0;
```

□ What does this program do?

Comm? "Communicator"

Basic Concepts

Processes can be collected into groups

Each message is sent in a *context*

Must be received in the same context!

A group and context together form a *communicator*

A process is identified by its rank

With respect to the group associated with a communicator

There is a default communicator MPI_COMM_WORLD

Contains all initial processes





Message data (sent or received) is described by a triple address, count, datatype

Message data (sent or received) is described by a triple address, count, datatype An MPI datatype is recursively defined as: Predefined data type from the language A contiguous array of MPI datatypes A strided block of datatypes An indexed array of blocks of datatypes An arbitrary structure of datatypes

Message data (sent or received) is described by a triple

address, count, datatype

An MPI *datatype* is recursively defined as:

Predefined data type from the language

A contiguous array of MPI datatypes

- A strided block of datatypes
- An indexed array of blocks of datatypes
- An arbitrary structure of datatypes

There are MPI functions to construct custom datatypes

Array of (int, float) pairs

Row of a matrix stored columnwise

Message data (sent or received) is described by a triple address, count, datatype An MPI datatype is recursively defined as: Predefined data type from the language A contiguous array of MPI datatypes A strided block of datatypes An indexed array of blocks of datatypes An arbitrary structure of datatypes

Message data (sent or received) is described by a triple

address, count, datatype

An MPI *datatype* is recursively defined as: Predefined data type from the language A contiguous array of MPI datatypes A strided block of datatypes An indexed array of blocks of datatypes An arbitrary structure of datatypes

- Enables heterogeneous communication
 - Support communication between processes on machines with different memory representations and lengths of elementary datatypes
 - MPI provides the representation translation if necessary

Message data (sent or received) is described by a triple

address, count, datatype

An MPI *datatype* is recursively defined as: Predefined data type from the language A contiguous array of MPI datatypes A strided block of datatypes An indexed array of blocks of datatypes An arbitrary structure of datatypes

- Enables heterogeneous communication
 - Support communication between processes on machines with different memory representations and lengths of elementary datatypes
 - MPI provides the representation translation if necessary
- Allows application-oriented layout of data in memory
 - Reduces memory-to-memory copies in implementation
 - Allows use of special hardware (scatter/gather)





Messages are sent with an accompanying user-defined integer tag Assist the receiving process in identifying the message



Messages are sent with an accompanying user-defined integer *tag* Assist the receiving process in identifying the message Messages can be screened at receiving end by specifying specific tag MPI_ANY_TAG matches any tag in a receive



Messages are sent with an accompanying user-defined integer tag Assist the receiving process in identifying the message
Messages can be screened at receiving end by specifying specific tag MPI_ANY_TAG matches any tag in a receive
Tags are sometimes called "message types" MPI calls them "tags" to avoid confusion with datatypes

MPI Basic (Blocking) Send

MPI_SEND (start, count, datatype, dest, tag, comm)

The message buffer is described by: start, count, datatype

The target process is specified by **dest**

Rank of the target process in the communicator specified by **comm**

Process blocks until:

Data has been delivered to the system

Buffer can then be reused

Message may not have been received by target process!

Many parallel programs can be written using: MPI_INIT() MPI_FINALIZE() MPI_COMM_SIZE() MPI_COMM_RANK() MPI_SEND() MPI_RECV()

Many parallel programs can be written using:

MPI_INIT() MPI_FINALIZE() MPI_COMM_SIZE() MPI_COMM_RANK() MPI_SEND() MPI_RECV() Why have any other APIs (e.g. broadcast, reduce, etc.)?

Many parallel programs can be written using:

MPI_INIT() MPI_FINALIZE() MPI_COMM_SIZE() MPI_COMM_RANK() MPI_SEND() MPI_RECV() Why have any other APIs (e.g. broadcast, reduce, etc.)? Point-to-point (send/recv) isn't always the most efficient...

Add more support for communication

Excerpt: Barnes-Hut

```
int ctr=nLocalOriginal;
int offset=nLocalOriginal-nLocal;
for(i=0;i<worldSize;i++) {</pre>
if(i==rank){
    MPI Bcast (s particles, N POS ELEMS*nLocalMax+1, MPI DOUBLE, i, MPI COMM WORLD);
} else {
    MPI Bcast (1 particles, N POS ELEMS*nLocalMax+1, MPI DOUBLE, i, MPI COMM WORLD);
    for(k=0;k<1 particles[0];k++, ctr++){</pre>
    if(l particles[MASS(k)]<0) {</pre>
        offset++;
        nparticles--;
    } else {
        s particles[PX(ctr)]=l particles[PX(k)];
        s particles[PY(ctr)]=l particles[PY(k)];
        s particles[PZ(ctr)]=l particles[PZ(k)];
        s particles[MASS(ctr)]=l particles[MASS(k)];
        indexes[ctr-offset]=ctr;
```

Excerpt: Barnes-Hut

```
int ctr=nLocalOriginal;
int offset=nLocalOriginal-nLocal;
for(i=0;i<worldSize;i++) {</pre>
if(i==rank){
    MPI Bcast (s particles, N POS ELEMS*nLocalMax+1, MPI DOUBLE, i, MPI COMM WORLD);
} else {
    MPI Bcast (1 particles, N POS ELEMS*nLocalMax+1, MPI DOUBLE, i, MPI COMM WORLD);
    for(k=0;k<1 particles[0];k++, ctr++){</pre>
    if(l particles[MASS(k)]<0) {</pre>
        offset++;
        nparticles--;
    } else {
        s particles[PX(ctr)]=l particles[PX(k)];
        s particles[PY(ctr)]=l particles[PY(k)];
        s particles[PZ(ctr)]=l particles[PZ(k)];
        s particles[MASS(ctr)]=l particles[MASS(k)];
        indexes[ctr-offset]=ctr;
```

Excerpt: Barnes-Hut

```
int ctr=nLocalOriginal;
int offset=nLocalOriginal-nLocal;
for(i=0;i<worldSize;i++) {</pre>
if(i==rank){
    MPI Bcast(s particles, N POS ELEMS*nLocalMax+1, MPI DOUBLE,
} else {
    MPI Bcast (1 particles, N POS ELEMS*nLocalMax+1, MPI DOUBLE,
    for(k=0;k<1 particles[0];k++, ctr++){</pre>
    if(l particles[MASS(k)]<0) {</pre>
        offset++;
        nparticles--;
    } else {
        s particles[PX(ctr)]=l particles[PX(k)];
        s_particles[PY(ctr)]=l_particles[PY(k)];
        s particles[PZ(ctr)]=l particles[PZ(k)];
        s_particles[MASS(ctr)]=l_particles[MASS(k)];
        indexes[ctr-offset]=ctr;
```



To use or not use MPI?

To use or not use MPI?

• USE

- You need a portable parallel program
- You are writing a parallel library
- You have irregular or dynamic data relationships
- You care about performance

To use or not use MPI?

• USE

- You need a portable parallel program
- You are writing a parallel library
- You have irregular or dynamic data relationships
- You care about performance
- NOT USE
 - You don't need parallelism at all
 - You can use libraries (which may be written in MPI) or other tools
 - You can use multi-threading in a concurrent environment
 - You don't need extreme scale