

Topic 19

Binary Search Trees

"Yes. Shrubberies are my trade. I am a shrubber. My name is 'Roger the Shrubber'. I arrange, design, and sell shrubberies."

-Monty Python and The Holy Grail



The Problem with Linked Lists

- ▶ Accessing a item from a linked list takes $O(N)$ time for an arbitrary element
- ▶ Binary trees can improve upon this and reduce access to $O(\log N)$ time for the average case
- ▶ Expands on the binary search technique and allows insertions and deletions
- ▶ Worst case degenerates to $O(N)$ but this can be avoided by using balanced trees (AVL, Red-Black)

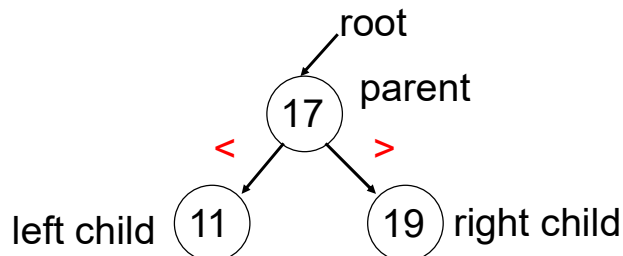
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Binary Search Trees

- ▶ A binary search tree is a binary tree in which **every node's** left subtree holds values less than the node's value, and every right subtree holds values greater than the node's value.
- ▶ A new node is added as a leaf.



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BST Insertion

- ▶ Add the following values one at a time to an initially empty binary search tree using the naïve algorithm:

90 20 9 98 10 28 -25

- ▶ What is the resulting tree?

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Traversals

- ▶ What is the result of an inorder traversal of the resulting tree?
- ▶ How could a preorder traversal be useful?

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- ▶ After adding N distinct elements in random order to a Binary Search Tree what is the expected height of the tree? (using the simple insertion algorithm)

- A. $O(\log N)$
- B. $O(N^{1/2})$
- C. $O(N)$
- D. $O(N \log N)$
- E. $O(N^2)$

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- ▶ After adding N distinct elements to a Binary Search Tree what is the **worst case** height of the tree? (using the simple insertion algorithm)

- A. $O(\log N)$
- B. $O(N^{1/2})$
- C. $O(N)$
- D. $O(N \log N)$
- E. $O(N^2)$

Worst Case Performance

- ▶ Insert the following values into an initially empty binary search tree using the simple, naïve algorithm:

2 3 5 7 11 13 17

- ▶ What is the height of the tree?
- ▶ What is the worst case height of a BST?

Node for Binary Search Trees

```
public class BSTNode<E extends Comparable<E> > {
    private Comparable<E> myData;
    private BSTNode<E> myLeft;
    private BSTNode<E> myRight;

    public BinaryNode(E item)
    {
        myData = item;
    }

    public E getValue()
    {
        return myData;
    }

    public BinaryNode<E> getLeft()
    {
        return myLeft;
    }

    public BinaryNode<E> getRight()
    {
        return myRight;
    }

    public void setLeft(BSTNode<E> b)
    {
        myLeft = b;
    }
    // setRight not shown
}
```

More on Implementation

- ▶ Many ways to implement BSTs
- ▶ Using nodes is just one and even then many options and choices

```
public class BinarySearchTree<E extends Comparable<E>> {

    private BSTNode<E> root;
    private int size;
}
```

Add an Element, Recursive

Add an Element, Iterative

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- What are the best case and worst case order to add N distinct elements, one at a time, to an initially empty binary search tree using the simple add algorithm?

	Best	Worst
A.	$O(N)$	$O(N)$
B.	$O(N \log N)$	$O(N \log N)$
C.	$O(N)$	$O(N \log N)$
D.	$O(N \log N)$	$O(N^2)$
E.	$O(N)$	$O(N^2)$

```
// given int[] data
// no duplicates in
// data
BST<Integer> b =
    new BST<Integer>();
for(int x : data)
    b.add(x);
```

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Performance of Binary Trees

- For the three core operations (add, access, remove) a binary search tree (BST) has an average case performance of $O(\log N)$
- Even when using the *naïve insertion / removal algorithms*
 - no checks to maintain balance
 - balance achieved based on the randomness of the data inserted

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Remove an Element

- Three cases
 - node is a leaf, 0 children (easy)
 - node has 1 child (easy)
 - node has 2 children (interesting)

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Properties of a BST

- The minimum value is in the left most node
- The maximum value is in the right most node
 - useful when removing an element from the BST

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Alternate Implementation

- In class examples of dynamic data structures have relied on *null terminated ends*.
 - Use null to show end of list, no children
- Alternative form
 - use structural recursion and polymorphism

BST Interface

```
public interface BST<E extends
    Comparable<? super E>> {

    public int size();
    public boolean contains(E obj);
    public boolean add(E obj);
}
```

EmptyBST

```
public class EmptyBST<E extends Comparable<? super E>> implements BST<E> {

    private static EmptyBST theOne = new EmptyBST();

    private EmptyBST() {}

    public static EmptyBST getEmptyBST(){ return theOne; }

    public BST add(E obj) { return new NEBST(obj); }

    public boolean contains(E obj) { return false; }

    public int size() { return 0; }
}
```

Non Empty BST – Part 1

```
public class NEBST <E extends Comparable<? super E>> implements BST<E> {

    private E data;
    private BST left;
    private BST right;

    public NEBST(E d){
        data = d;
        right = EmptyBST.getEmptyBST();
        left = EmptyBST.getEmptyBST();
    }

    public BST add(E obj) {
        int direction = obj.compareTo( data );
        if( direction < 0 )
            left = left.add( obj );
        else if( direction > 0 )
            right = right.add( obj );
        return this;
    }
}
```

Non Empty BST – Part 2

```
public boolean contains(E obj){  
    int dir = obj.compareTo(data);  
    if( dir == 0 )  
        return true;  
    else if (dir < 0)  
        return left.contains(obj);  
    else  
        return right.contains(obj);  
}  
  
public int size() {  
    return 1 + left.size() + right.size();  
}  
}
```