CS371m - Mobile Computing

Sensing and Sensors





Sensors

- "I should have paid more attention in Physics 41"
- Most devices have built in sensors to measure and monitor
 - -motion
 - orientation (aka position of device)
 - -environmental conditions
- sensors deliver raw data to applications

Sensor Framework

- Determine which sensors are available on a device.
- Determine an individual sensor's capabilities, such as its range, manufacturer, power requirements, and resolution.
- Acquire raw sensor data and define the minimum rate at which you acquire sensor data.
- Register and unregister sensor event listeners that monitor sensor changes.

http://developer.android.com/guide/topics/sensors/sensors_overview.html

Sensor Framework Classes

- SensorManager
 - conduit between your classes and Sensors
- Sensors
 - abstract representations of Sensors on device
- SensorEventListener
 - register with SensorManager to listen for events from a Sensor
- SensorEvent
 - data sent to listener

Recall: Android Software Stack



TYPES OF SENSORS

- Three main classes of sensors:
- motion (acceleration and rotational forces)
 - accelerometers, gravity sensors, gyroscopes, rotational vector sensors, step detector
- environmental (ambient air temperature and pressure, illumination, and humidity)
 - -barometers, photometers, and thermometers.
- position (physical position of a device)

orientation sensors and magnetometers

- Hardware sensors
 - -built into the device
- Software sensors
 - takes data from hardware sensors and manipulates it
 - from our perspective acts like a hardware sensor
 - -aka synthetic or virtual sensors

Types of Sensors - Dev Phone - Older

Sensor: KR3DM 3-axis Accelerometer, STMicroelect	ron
Sensor: AK8973 3-axis Magnetic field sensor, Asa	ahi
Sensor: AK8973 Orientation sensor, Asahi Kasei M	4icr
Sensor: GP2A Light sensor, Sharp	
Sensor: GP2A Proximity sensor, Sharp	
Sensor: K3G Gyroscope sensor, STMicroelectronics	5
Sensor: Gravity Sensor, Google Inc.	
Sensor: Linear Acceleration Sensor, Google Inc.	
Sensor: Rotation Vector Sensor, Google Inc.	

 accelerometer, linear acceleration, magnetic field, orientation, light, proximity, gyroscope, gravity

Sensor Types - (<u>Sensor Class</u>)

int	TYPE_ACCELEROMETER	A constant describing an accelerometer sensor type.
int	TYPE_ALL	A constant describing all sensor types.
int	TYPE_AMBIENT_TEMPERATURE	A constant describing an ambient temperature sensor type.
int	TYPE_GAME_ROTATION_VECTOR	A constant describing an uncalibrated rotation vector sensor type.
int	TYPE_GEOMAGNETIC_ROTATION_VECTOR	A constant describing the geo-magnetic rotation vector.
int	TYPE_GRAVITY	A constant describing a gravity sensor type.
int	TYPE_GYROSCOPE	A constant describing a gyroscope sensor type.
int	TYPE_GYROSCOPE_UNCALIBRATED	A constant describing an uncalibrated gyroscope sensor type.
int	TYPE_LIGHT	A constant describing a light sensor type.
int	TYPE_LINEAR_ACCELERATION	A constant describing a linear acceleration sensor type.
int	TYPE_MAGNETIC_FIELD	A constant describing a magnetic field sensor type.
int	TYPE_MAGNETIC_FIELD_UNCALIBRATED	A constant describing an uncalibrated magnetic field sensor type.
int	TYPE_ORIENTATION	This constant was deprecated in API level 8. use SensorManager.getOrientation()
int	TYPE_PRESSURE	A constant describing a pressure sensor type.
int	TYPE_PROXIMITY	A constant describing a proximity sensor type.
int	TYPE_RELATIVE_HUMIDITY	A constant describing a relative humidity sensor type.
int	TYPE_ROTATION_VECTOR	A constant describing a rotation vector sensor type.
int	TYPE_SIGNIFICANT_MOTION	A constant describing a significant motion trigger sensor.
int	TYPE_STEP_COUNTER	A constant describing a step counter sensor.
int	TYPE_STEP_DETECTOR	A constant describing a step detector sensor.
int	TYPE_TEMPERATURE	This constant was deprecated in API level 14. use Sensor. TYPE_AMBIENT_TEMPERATUR

Sensor Capabilities - Dev Phones - Older

KR3DM 3-axis Accelerometer - minDelay: 20000, power: 0.23 max range: 19.6133, resolution: 0.019153614 AK8973 3-axis Magnetic field sensor - minDelay: 16667, power: 6.8 max range: 2000.0, resolution: 0.0625 GP2A Light sensor - minDelay: 0, power: 0.75 max range: 3626657.8, resolution: 1.0 GP2A Proximity sensor - minDelay: 0, power: 0.75 max range: 5.0, resolution: 5.0 K3G Gyroscope sensor - minDelay: 1190, power: 6.1 max range: 34.906586, resolution: 0.0012217305 Rotation Vector Sensor - minDelay: 20000, power: 13.13 max range: 1.0, resolution: 5.9604645E-8 Gravity Sensor - minDelay: 20000, power: 13.13 max range: 19.6133, resolution: 0.019153614 Linear Acceleration Sensor - minDelay: 20000, power: 13.13 max range: 19.6133, resolution: 0.019153614 Orientation Sensor - minDelay: 20000, power: 13.13 max range: 360.0, resolution: 0.00390625 Corrected Gyroscope Sensor - minDelay: 1190, power: 13.13 max range: 34.906586, resolution: 0.0012217305

Types of Sensors - Dev Phone - Newer

SensorTest. SensorTest. SensorTest SensorTest SensorTest. SensorTest SensorTest SensorTest. SensorTest. SensorTest. SensorTest SensorTest. SensorTest. SensorTest. SensorTest

GP2A Light sensor Sharp GP2A Proximity sensor Sharp BMP180 Pressure sensor Bosch MPL Gyroscope Invensense MPL Accelerometer Invensense MPL Magnetic Field Invensense MPL Orientation Invensense MPL Rotation Vector Invensense MPL Linear Acceleration Invensense MPL Gravity Invensense Rotation Vector Sensor Google Inc. Gravity Sensor Google Inc. Linear Acceleration Sensor Google Inc. Orientation Sensor Google Inc. Corrected Gyroscope Sensor Google Inc.

Sensor Capabilities - Dev Phone - Newer

GP2A Light sensor - minDelay: 0, power: 0.75 max range: 646239.5, resolution: 1.0 GP2A Proximity sensor - minDelay: 0, power: 0.75 max range: 5.0, resolution: 5.0 BMP180 Pressure sensor - minDelay: 20000, power: 0.67 max range: 1100.0, resolution: 0.01 MPL Gyroscope - minDelay: 10000, power: 6.1 max range: 34.90656, resolution: 0.57246757 MPL Accelerometer - minDelay: 10000, power: 0.139 max range: 19.6133, resolution: 0.038344003 MPL Magnetic Field - minDelay: 10000, power: 4.0 max range: 8001.0, resolution: 0.012 MPL Orientation - minDelay: 10000, power: 10.239 max range: 360.0, resolution: 1.0E-5 MPL Rotation Vector - minDelay: 10000, power: 10.239 max range: 1.0, resolution: 1.0E-5 MPL Linear Acceleration - minDelay: 10000, power: 0.5 max range: 10240.0, resolution: 1.0 MPL Gravity - minDelay: 10000, power: 10.239 max range: 19.6133, resolution: 0.038344003 Rotation Vector Sensor - minDelay: 10000, power: 10.239 max range: 1.0, resolution: 5.9604645E-8 Gravity Sensor - minDelay: 10000, power: 10.239 max range: 19.6133, resolution: 0.038344003 Linear Acceleration Sensor - minDelay: 10000, power: 10.239 max range: 19.6133, resolution: 0.038344003 Orientation Sensor - minDelay: 10000, power: 10.239 max range: 360.0, resolution: 0.00390625 Corrected Gyroscope Sensor - minDelay: 10000, power: 10.239 max range: 34.90656, resolution: 0.57246757

- TYPE_ACCELEROMETER
 - hardware
 - -acceleration in m/s²
 - -x, y, z axis
 - includes gravity

- TYPE_AMBIENT_TEMPERATURE [deprecated)]
 - hardware
 - "room" temperature in degrees Celsius
 - no such sensor on dev phones TYPE_GRAVITY
 - -software or hardware
 - just gravity
 - if phone at rest same as TYPE_ACCELEROMETER

- TYPE_GYROSCOPE
 - hardware
 - measure device's rate of rotation in radians / second around 3 axis
- TYPE_LIGHT
 - hardware
 - -light level in lx,
 - lux is SI measure illuminance in luminous flux per unit area

- TYPE_LINEAR_ACCELERATION
 - -software or hardware
 - measure acceleration force applied to device in three axes excluding the force of gravity
- TYPE_MAGNETC_FIELD
 - -hardware
 - -ambient geomagnetic field in all three axes
 - -uT micro Teslas

- TYPE_ORIENTATION [deprecated]
 - software
 - measure of degrees of rotation a device makes around all three axes
- TYPE_PRESSURE
 - hardware
 - ambient air pressure in hPa or mbar
 - force per unit area
 - -1 Pascal = 1 Newton per square meter
 - -hecto Pascals (100 Pascals)
 - milli bar 1 mbar = 1hecto Pascal

- TYPE_PROXIMITY
 - hardware
 - proximity of an object in cm relative to the view screen of a device
 - -usually binary (see range, resolution)
 - typically used to determine if handset is being held to person's ear during a call
- TYPE_RELATIVE_HUMIDITY

-ambient humidity in percent (0 to 100)

- TYPE_ROTATION_VECTOR (ABSOLUTE)
 - hardware or software
 - orientation of device, three elements of the device's rotation vector
- TYPE_ROTATION_VECTOR
 - -orientation sensor
 - replacement for TYPE_ORIENTATION
 - combination of angle of rotation and access
 - -uses geomagnetic field in calculations
 - compare to TYPE_GAME_ROTATION_VECTOR

Availability of Sensors

Sensor	Android 4.0 (API Level 14)	Android 2.3 (API Level 9)	Android 2.2 (API Level 8)	Android 1.5 (API Level 3)
TYPE ACCELEROMETER	Yes	Yes	Yes	Yes
TYPE AMBIENT TEMPERATURE	Yes	n/a	n/a	n/a
TYPE GRAVITY	Yes	Yes	n/a	n/a
TYPE GYROSCOPE	Yes	Yes	n/a ¹	n/a ¹
TYPE LIGHT	Yes	Yes	Yes	Yes
TYPE LINEAR ACCELERATION	Yes	Yes	n/a	n/a
TYPE MAGNETIC FIELD	Yes	Yes	Yes	Yes
TYPE ORIENTATION	Yes ²	Yes ²	Yes ²	Yes
TYPE PRESSURE	Yes	Yes	n/a ¹	n/a ¹
TYPE PROXIMITY	Yes	Yes	Yes	Yes
TYPE RELATIVE HUMIDITY	Yes	n/a	n/a	n/a
TYPE ROTATION VECTOR	Yes	Yes	n/a	n/a
TYPE TEMPERATURE	Yes ²	Yes	Yes	Yes

Sensor Capabilities

- Various methods in Sensor class to get capabilities of Sensor
- minDelay (in microseconds)
- power consumption in mA (microAmps)
- maxRange
- resolution

Triggered Sensors

- Android 4.4, API level 19, Kit-Kat added trigger sensors
- TYPE SIGNIFICANT MOTION
- <u>TYPE STEP COUNTER</u>
- <u>TYPE STEP DETECTOR</u>

USING SENSORS EXAMPLE

Using Sensors - Basics

- Obtain the *SensorManager* object
- create a SensorEventListener for SensorEvents
 - -logic that responds to sensor event
 - varying amounts of data from sensor depending on type of sensor
- Register the sensor listener with a Sensor via the SensorManager
- Unregister when done
 - a good thing to do in the onPause method

Using Sensors

```
private void createSensor() {
```

```
sensorManager =
```

(SensorManager) getSystemService(Context.SENSOR_SERVICE);

```
showSensors();
```

- registerListener(SensorEventListener, Sensor, int rate)
- rate is just a *hint*
- SENSOR_DELAY_NORMAL, SENSOR_DELAY_UI, SENSOR_DELAY_GAME, or SENSOR_DELAY_FASTEST, or time in microseconds (millionths of a second)

SensorEventListener

- Interface with two methods:
 - void onAccuracyChanged (Sensor sensor, int accuracy)
 - –void onSensorChanged (SensorEvent event)
 - Sensor values have changed
 - this is the key method to override
 - don't do significant computations in this method
 - -don't hold onto the event
 - part of pool of objects and the values may be altered soon

Listing Sensors on a Device to Log

```
private void showSensors() {
    List<Sensor> sensors
            sensorManager.getSensorList(Sensor.TYPE_ALL);
    Log.d(TAG, sensors.toString());
    for(Sensor s : sensors) {
        Log.d(TAG, s.getName() + " - minDelay: "
             + s.getMinDelay() + ", power: " + s.getPower());
        Log.d(TAG, "max range: " + s.getMaximumRange()
                + ", resolution: " + s.getResolution());
    }
```

Simple Sensor Example

- App that shows acceleration —TYPE_ACCELEROMETER
- options to display current
- ... or maximum, ignoring direction
- Linear Layout
- TextViews for x, y, and z
- Buttons to switch between max or current and to reset max

- For most motion sensors:
- +x to the right
- +y up
- +z out of front face
- relative to device
- based on natural orientation of device
 - tablet -> landscape



Clicker

- With the device flat on a surface what, roughly, will be the magnitude of the largest acceleration?
- A. 0 m/s²
- B. 1 m/s²
- C. 5 m/s²
- D. 10 m/s²
- E. 32 m/s²

Accelerometer - Includes Gravity

- Sensor. *TYPE_ACCELEROMETER*
- Device flat on table
- g ~= 9.81 m/s²

SensorTest

SensorTest

SensorTest

Clearly some error

i: 0,

i:

i: 1, zero

2,

zero

zero

SensorTest					
Accelerometer	Linear Acceleration				
x Axis					
-0.114					
y Axis					
-0.152					
z Axis					
9.579					
Current	Reset Max				
value: -0.190	007805				
value: -0.42606363					
v_{2}					

 Hold phone straight up and down:



 Hold phone on edge





 Hold phone straight up and down and pull towards the floor:

Accelerometer	Linear Acceleration			
x Axis -3.333				
y Axis 18.087				
z Axis 4.099				
Current	Reset Max			
\leftarrow				

Getting Sensor Data

private void createSensor() {

sensorManager =

(SensorManager) getSystemService(Context.SENSOR_SERVICE);

```
showSensors();
```

- registerListener
 - sensorEventListener
 - Sensor -> obtain via SensorManager
 - rate of updates, a hint only, or microseconds (not much effect)
- returns true if successful

SensorEventListener

```
private SensorEventListener sensorEventListener =
        new SensorEventListener() {
            @Override
            public void onSensorChanged(SensorEvent event) {
                // Log.d(TAG, event + "");
                // accelerationValues[0].setText("" + event.values[0]
                if(displayCurrent)
                    displayCurrent(event);
                else
                    displayMax(event);
                // displayCurrentRotation(event);
            }
```

Display Max

```
private void displayMax(SensorEvent event) {
    for(int i = 0; i < maxVals.length; i++)
        if(Math.abs(event.values[i]) > maxVals[i]) {
            maxVals[i] = (float) Math.abs(event.values[i]);
            float value = ((int) (maxVals[i] * 1000)) / 1000f;
            accelerationValues[i].setText("" + value);
        }
```

Recall, max range of linear acceleration on dev phone is 19.613 + gravity = 29.423 - a baseball pitcher throwing a fastball reaches 350 m/s² or more (various "physics of baseball" articles)

Display Current

private void displayCurrent(SensorEvent event) {
 if(!zeroingComplete)
 gatherZeroData(event);

```
for(int i = 0; i < accelerationValues.length; i++) {
    float value = event.values[i];
    value = ((int) (value * 1000)) / 1000f;
    accelerationValues[i].setText("" + value);
}</pre>
```

- Lots of jitter
- Not a laboratory device
 simple sensors on a mobile device

Linear Acceleration

- At rest of table
- Recall
- units are m/s²



Zeroing out

 Take average of first multiple (several hundred) events and average

- shorter time = more error

• Potential error

-should be 0 at rest

SensorTest	i:	0,	zerovalue:	7.4665865E-4
SensorTest	i:	1,	zerovalue:	-0.003574672
SensorTest	i:	2,	zerovalue:	-0.02909316

i:	Ο,	zerovalue:	-0.0035472375
i:	1,	zerovalue:	-0.0018564985
i:	2,	zerovalue:	-0.022586245

Rate of Events

- 1000 events
- SensorManager.SENSOR_DELAY_UI —times in seconds: 21, 21, 21
 - -21 seconds / 1000 events
- SensorManager.SENSOR_DELAY_FASTEST — times in seconds: 21, 21, 21
- Recall delay of 20,000 micro seconds
- $2x10^4 \times 1x10^3 = 2x10^7 = 20$ seconds

USING SENSORS

Using Sensors

- Recall basics for using a Sensor:
 - -Obtain the SensorManager object
 - -create a SensorEventListener for SensorEvents
 - logic that responds to sensor event
 - Register the sensor listener with a Sensor via the SensorManager

Sensor Best Practices

- Unregister sensor listeners
 - when done with Sensor or activity using sensor paused (onPause method)
 - sensorManager.
 unregisterListener(sensorListener)
 - otherwise data still sent and battery resources continue to be used

Sensors Best Practices

- verify sensor available before using it
- use getSensorList method and type
- ensure list is not empty before trying to register a listener with a sensor

Sensors Best Practices

- Avoid deprecated sensors and methods
- TYPE_ORIENTATION and TYPE_TEMPERATURE are deprecated as of Ice Cream Sandwich / Android 4.0

Sensors Best Practices

- Don't block the onSensorChanged() method
 - recall the resolution on sensors
 - 50 updates a second for onSensorChange method not uncommon
 - when registering listener update is only a hint and may be ignored
 - if necessary save event and do work in another thread or asynch task

Sensor Best Practices

- Testing on the emulator
- Android SDK doesn't provide any simulated sensors
- 3rd party sensor emulator
- <u>http://code.google.com/p/openintents/wiki/SensorSimulator</u>

SensorSimulator

- Download the Sensor Simulator tool
- Start Sensor Simulator program
- Install SensorSimulator apk on the emulator
- Start app, connect simulator to emulator, start app that requires sensor data
- Must modify app so it uses Sensor Simulator library

Sensor Simulator

🔊 SensorSimulator		
		3
● yaw & pitch ◯ roll & pitch ◯ move	Sensors Scenario Simulator Quick Settings Sensors Parameters	
	Choose Device	
	Basic Orientation Environment Sensors	3
Sensor update: 13.00 ms	accelerometer temperature	
accelerometer: 0.00, -0.68, 9.78 magnetic field: 23.43, 6.07, -42.86 orientation: 292.00, 4.00, 0.00 light: 400.00	magnetic field light orientation proximity	
gravity: 0.00, -0.68, 9.78	Extended Orientation Other Sensors	
	gravity barcode reader	
Write emulator command port and click on set to create connection. Possible IP addresses:	rotation vector gyroscope	
10.0.2.2 128.83.141.69 192.168.1.74		

Sensor Simulator

- Mouse in Sensor Simulator controls device, feeds sensor data to emulator
- Can also record sensor data from real device and play back on emulator



Sensing Orientation

- Orientation of the device
- x tangential to ground and points roughly east
- y tangential to the ground and points towards magnetic north
- z perpendicular to the ground and points towards the sky



Orientation Sensor

- Deprecated
- Instead use the Rotation vector sensor
- int TYPE_ROTATION_VECTOR

SENSOR SAMPLE - MOVING BALLS

Sensor Sample - Moving Ball

- Place ball in middle of screen
- Ball has position, velocity, and acceleration
- acceleration based on linear acceleration sensor
- update over time, based on equations of motion, but fudged to suit application

Sensor Sample - Moving Ball

- Gross Simplification
- <u>velocity set equal to</u> <u>acceleration</u>

public void onSensorChanged(SensorEvent e
 //set ball speed based on phone tilt
 // speed set equal to acceleration
 mBallVelocity.x = -event.values[0];
 mBallVelocity.y = event.values[1];



Reality is Unrealistic

 "When exposed to an exaggeration or fabrication about certain real-life occurrences or facts, some people will perceive the fictional account as being more true than any factual account."



Reality is Unrealistic



Sensor Sample - Moving Ball

Alternate Implementation

```
// try more realistic movement
float xA = -event.values[0];
float yA = event.values[1];
float aveXA = (xA + mPrevXAcc) / 2;
float aveYA = (yA + mPrevYAcc) / 2;
long currentTime = System.currentTimeMillis();
long elapsedTime = currentTime - mPrevTime;
mBallVelocity.x += aveXA * elapsedTime / 1000 / ACC_FUDGE_FACTOR;
mBallVelocity.y += aveYA * elapsedTime / 1000 / ACC_FUDGE_FACTOR;
mPrevXAcc = xA;
mPrevYAcc = yA;
```

```
mPrevTime = currentTime;
```

 position updated in separate thread which redraws the view

Sensor Sample

Draw lines for x and y velocities

```
//called by invalidate()
@Override
protected void onDraw(Canvas canvas) {
    super.onDraw(canvas);
    mPaint.setStrokeWidth(1);
    mPaint.setColor(0xFF00FF00);
    canvas.drawCircle(mX, mY, mR, mPaint);
```



Sensor Sample - TBBT

 Inspired by <u>http://tinyurl.com/bxzaspy</u> and <u>http://tinyurl.com/6nhvnnv</u>



TBBT Sound Effect App





Responding to Events

```
private class LinAccListener implements SensorEventListener {
    public void onSensorChanged(SensorEvent event) {
        if(event.sensor.getType() == Sensor.TYPE_LINEAR_ACCELERATION) {
            float x = event.values[0];
            float y = event.values[1];
            float z = event.values[2];
            float acc = (float)Math.sqrt( x * x + y * y);
            // Log.d("BBT", "" + acc);
            if(acc > 31) {
                Log.d("BBT", "" + acc);
                if(soundPlayer != null && !soundPlayer.isPlaying()) {
                    soundPlayer.start();
                    picture.setImageResource(R.drawable.crack);
            }
        }
```

Changing Images

- Use of an Image View
- Initial Image set in onCreate
- new image set in onSensorChange
- register listener with MediaPlayer
- on completion reset image

@Override

public void onCompletion(MediaPlayer mp) {
 picture.setImageResource(R.drawable.shake);
}