

Optimization with Costly Information: a survey

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Shopping for a car...

Many possible choices...



Many possible actions for each

- Read reviews
- Test drive
- Negotiate with a dealer

...

A possible “solution”:

1. Pick top 5 cars based on ratings
2. Read reviews; shortlist 2 out of 5
3. Test drive the two
4. If you like one, negotiate with a dealer
Else go back to step 1
5. Repeat until a choice is made

Goal: to select the best option without expending too much time/effort

Many settings involve costly information acquisition before optimization ...

- **Hiring**: read resumes and letters, interview candidates before making offers
- **Procurement**: evaluate suppliers before awarding contracts
- **Data-driven advertising**: run experiments before allocating budget
- ...

Information can be expensive

Key Question: when should an algorithm pay to learn more?

How is this different from standard stochastic optimization?

- **Stochastic/online optimization**: algorithm observes information for free in a fixed order; or makes decisions without observing it
- **This setting**: whether to obtain information is itself a decision variable

Why is this challenging?

- **Task dependence**: what is worth learning depends on the downstream objective
- **Adaptivity**: what we learn changes what and how we should inspect next

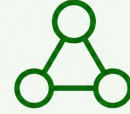


**General feasibility
constraints**

Three components of a costly information problem:

- Downstream optimization task
- Model of information revelation
- Objective function:

value of solution – cost of info acquisition



**Correlated /
dependent input
variables**

**Simplest setting:
Weitzman's Pandora's Box**

- Single-element selection
- Independent alternatives
- Binary information state: known or unknown
- Linear objective: value of selected item minus inspection cost



**General, possibly
nonlinear objectives**

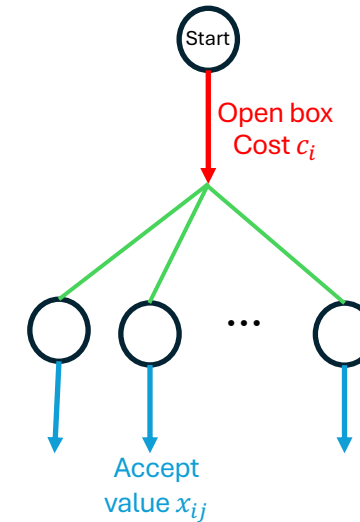
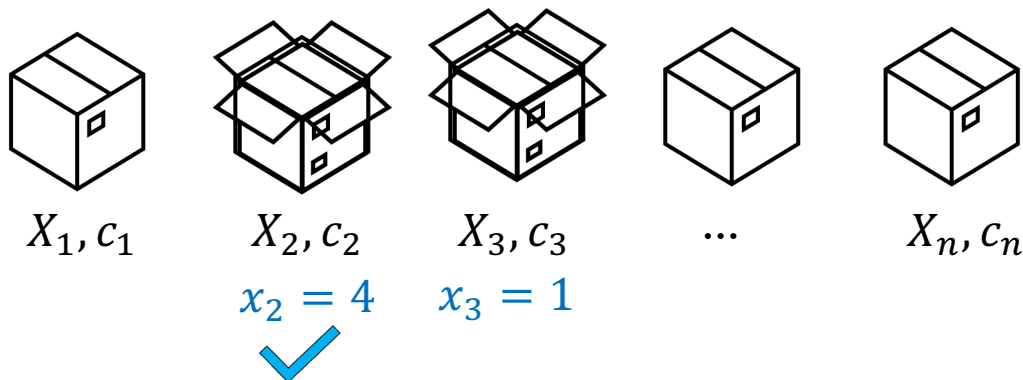


**General process of
information acquisition**

Classical special case: Weitzman's Pandora's Box [1979]



- Given: n boxes with unknown values $X_i \sim D_i$ and opening costs c_i .
- Optimization problem: select one alternative
- Information acquisition: opening box i costs c_i
 - Closed box $\equiv$ no information
 - Open box $\equiv$ full knowledge of value
- Algorithmic task: At every step decide whether to open some closed box i , or to stop and accept the best value seen so far.
- Maximize $X_{\text{selected}} - C_{\text{opening}}$



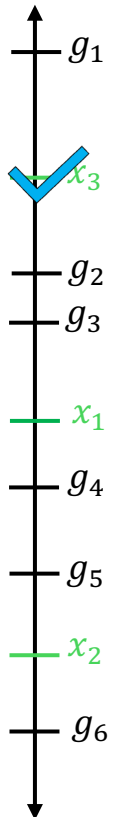
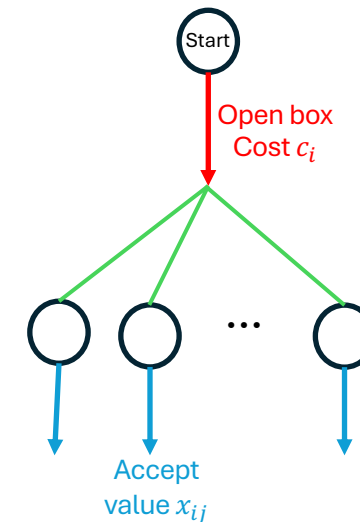
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Weitzman's algorithm: **index-based** policy

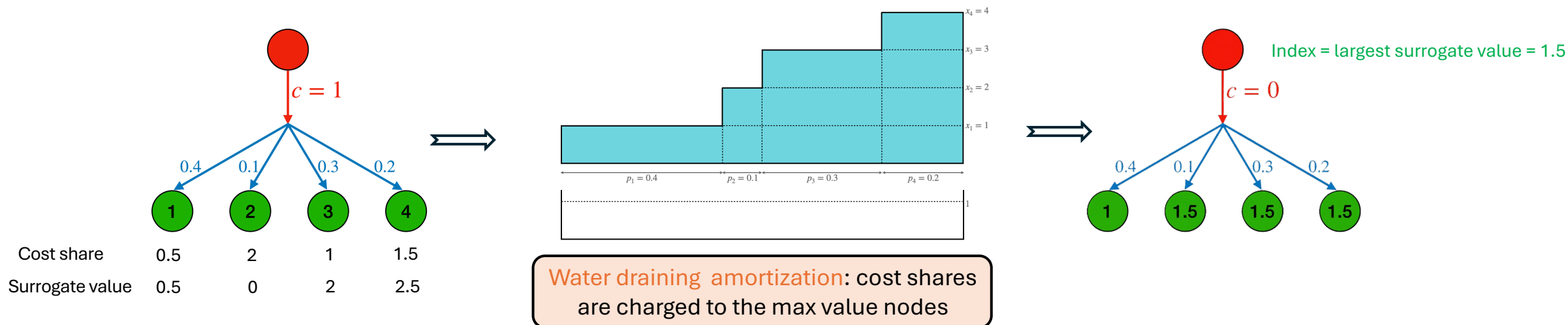
- Compute the "Gittins index" g_i of every box
- Open boxes in decreasing order of index
- Until we find a value larger than all remaining indices
- Stop and return the largest value



Weitzman's algorithm is **optimal** for Pandora's Box. – Let's prove it!

Technique: amortization and surrogate costs

Key idea: amortize the action costs down to the leaves.



Surrogate value = value of node - amortized cost share

$E[\text{cost share}] = \text{action cost } c$

Promise of payment: if a node with cost share > 0 is realized, the alg must accept at that node.

Weitzman's algorithm: index-based policy

- Open boxes in decreasing order of index
- Until we find a value larger than all remaining indices
- Stop and return the largest value

Claim 1: For any alg and any amortization, surrogate value of selection $\geq$ actual value.

Claim 2: For any alg satisfying promise of payment, surrogate value of selection = actual value.

Claim 3: Weitzman's algorithm satisfies promise of payment and accepts the largest realized surrogate value.

$\Rightarrow$ optimality

Extension to multi-stage information acquisition



General process of
information acquisition

- Optimization problem: select one alternative
- Information acquisition:
 - Sequence of information revelation steps
 - Each costly step further refines distribution
- Algorithmic task: At every step decide whether to learn more about i , or to stop and accept the best value seen so far.

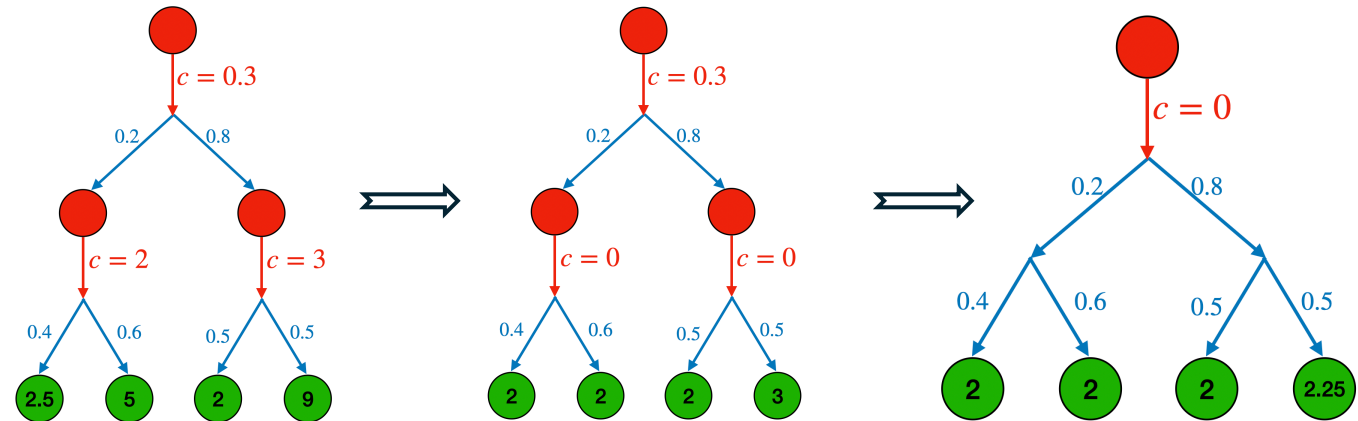
References:

- Weitzman '79 defines indices
- Dumitrescu Tetali Winkler '03 extend indices to Markov chains
- Amortization idea is due to Kleinberg Waggoner Weyl '16
- Water draining proof is due to C. Christou Harlev Scully '26

Optimal algorithm: index-based policy

- Compute the “Gittins index” g_i of every state
- Advance the state with the largest index
- If this leads to an “accept” action, stop

The same water draining amortization and analysis works!



Extension to general feasibility constraints

Concept: Frugality

[Singla '18, Gupta Jiang Scully Singla '20]



General feasibility
constraints

- Optimization problem: select subset $S \in \mathcal{F} \leftarrow$ feasibility constraint
- Information acquisition: each alternative lies in a box; has binary state: known or unknown
- Algorithmic task: At every step decide whether to open some closed box i , or to stop and accept the best feasible set seen so far.

Recall:

- For every algorithm, **surrogate value collected** $\geq$ **actual value collected**
- And, if the algorithm satisfies **promise of payment**, **surrogate value collected** = **actual value**

Question: can we maximize surrogate value collected while satisfying promise of payment?

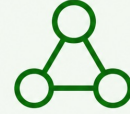
Singla's idea: use a greedy algorithm – select a box to open based on its index and previous revealed info; must accept if value $\geq$ index.

Frugality = performance ratio of greedy algorithm; **Approximation ratio** of Singla's algorithm = **frugality of $\mathcal{F}$** .



General feasibility constraints

- ✓ Any constraints that admit good frugal algorithms



Correlated /
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variables

Simplest setting: Weitzman's Pandora's Box

- Single-element selection
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General, possibly
nonlinear objectives

Next: Multi-modal info.
acquisition

- ✓ Any Markov chain type
process of info. acquisition



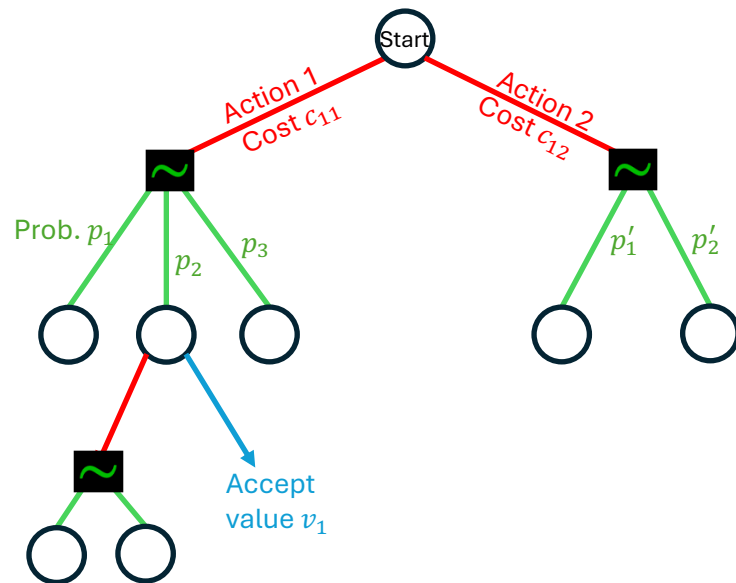
General process of
information acquisition

Extension to multi-modal information acquisition



General process of
information acquisition

Markov Decision Process $\mathcal{M}_i$:
one per alternative X_i



Two components in the algorithm

- Which alternative to explore?
- **How** to explore it?

- At every step, choose an MDP $\mathcal{M}_i$ and take an action in it.
- Process terminates when some “accept” action is taken.

Old problem: Bandit Super Process [Nash’73, Whittle’80, Glazebrook’82, ...]

But much recent interest:

[Doval’18, Beyhaghi-Kleinberg’19, Ke-Villas-Boas’19, Aouad-Ji-Shaposhnik’20, Beyhaghi-Cai’22, Fu-Li-Liu’22, Scully-Doval’24, ...]

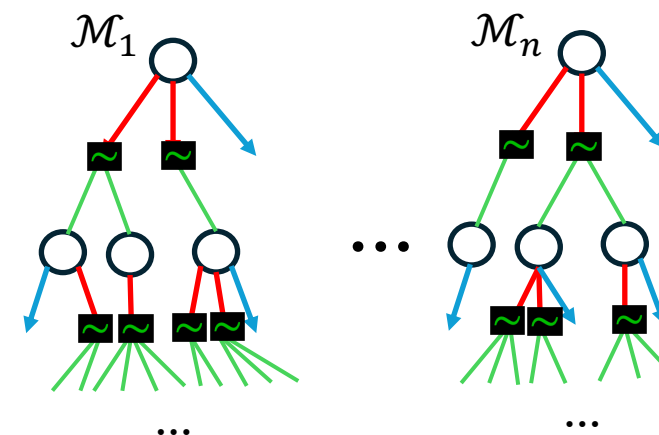
See survey by Beyhaghi & Cai (2023)

Extension to multi-modal information acquisition

- Global ordering is not index-based
 - Whether to evaluate X_1 or X_2 first depends on what we know about X_3
- Optimal local decisions depend on what else we know.
 - Which action to take in an MDP depends on our state in other MDPs.
- Actions that are never locally optimal may be globally optimal!
- NP-hard, even with just two action choices per alternative [Fu Li Liu'22]

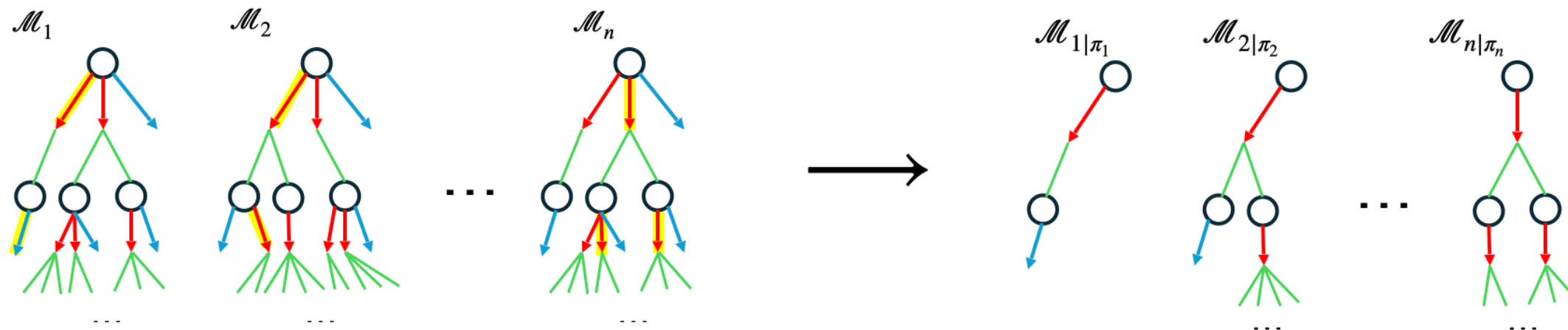


General process of
information acquisition



Concept: Commitment Policies and Commitment Gap

[Beyhaghi Kleinberg '19]



- A commitment π_i for the MDP $\mathcal{M}_i$ is a mapping from all states s_i to actions $a \in A(s_i)$.
- For any $\Pi = (\pi_1, \dots, \pi_n)$ we can efficiently find $\text{OPT}_{|\Pi}$

$$\text{Commitment Gap} = \min_{\Pi} \frac{\text{OPT}}{\text{OPT}_{|\Pi}}$$

Technique: Ex Ante Relaxation

[Bowers Lindgren Waggoner '26]

- Original problem: Select one car to maximize $E[X_{\text{selected}} - c(\text{actions})]$
- New relaxation: Select a subset S of cars to maximize $E[\sum_{i \in S} X_i - c(\text{actions})]$ such that $E[|S|] \leq 1$



$$X_1 \sim D_1$$



$$X_2 \sim D_2$$



$$X_3 \sim D_3$$



$$X_4 \sim D_4$$

Prob. of acceptance:

0.1

0.3

0.5

0.1

An algorithm based on the ex ante relaxation

[C. Christou Dang '25]

- **Solve the ex ante relaxation** $\Rightarrow$ obtain acceptance probability q_i for each alternative i
 - Can solve optimally using a linear program of size $\sum_i |\mathcal{M}_i|$
- For each alternative i , **find the “optimal” local policy π_i** that accepts with probability q_i
- **Commit** to the local actions $(\pi_1, \dots, \pi_n)$ and **run the index policy** of Weitzman and DTW03



$X_1 \sim D_1$



$X_2 \sim D_2$



$X_3 \sim D_3$



$X_4 \sim D_4$

Prob. of acceptance: 0.1

0.3

0.5

0.1

Prescribed local actions:

Read reviews
Test drive if ★ ★ ★+

Read reviews
Buy if ★ ★ ★ ★ ★

Why does this work?

[C. Christou Dang '25]

- Solve the **ex ante relaxation** $\Rightarrow$ obtain acceptance probability q_i for each alternative i
- For each alternative i , find the “**optimal**” **local policy** π_i that accepts with probability q_i
- **Commit** to the local actions $(\pi_1, \dots, \pi_n)$ and **run the index policy** of Weitzman and DTW03

$$\text{Ex Post OPT}(\mathcal{M}_1^{\pi_1}, \dots, \mathcal{M}_n^{\pi_n}) \stackrel{?}{=} \text{Ex Ante OPT}(\mathcal{M}_1^{\pi_1}, \dots, \mathcal{M}_n^{\pi_n}) = \text{Ex Ante OPT}(\mathcal{M}_1, \dots, \mathcal{M}_n) \geq \text{Ex Post OPT}(\mathcal{M}_1, \dots, \mathcal{M}_n)$$

Our algorithm ↑ What is this gap? ↑ By construction ↑ Relaxation ↑ Benchmark

Correlation gap $\Rightarrow$ Approximation ratio

- The correlation gap of the max function is $e/(e - 1)$. [Agrawal-Ding-Saberi-Ye'10, Yan'11]

Theorem: The approximation ratio of the above algorithm for single element selection over any MDPs is at most $e/(e - 1)$.



$W_1 = 0$ or 1 w.p. $\frac{1}{2}$



$W_2 = 0$ or 1 w.p. $\frac{1}{2}$

Ex Post expected value = $\frac{3}{4}$
Ex Ante expected value = 1

$$\begin{array}{ccc} E[\max_i W_i^{\pi_i}] & \xleftrightarrow{\text{Correlation gap of the max function}} & E[\max_i Z_i] \\ \parallel & & \parallel \end{array}$$

where $(Z_1, \dots, Z_n)$ are correlated random variables such that:

- the marginal distribution of Z_i is identical to the distribution of $W_i^{\pi_i}$
- the expected maximum is maximized

$$\begin{array}{ccccccc} \text{Ex Post OPT}(\mathcal{M}_1^{\pi_1}, \dots, \mathcal{M}_n^{\pi_n}) & ? & \text{Ex Ante OPT}(\mathcal{M}_1^{\pi_1}, \dots, \mathcal{M}_n^{\pi_n}) & = & \text{Ex Ante OPT}(\mathcal{M}_1, \dots, \mathcal{M}_n) & \geq & \text{Ex Post OPT}(\mathcal{M}_1, \dots, \mathcal{M}_n) \\ \text{Our algorithm} & \uparrow & & \uparrow & \uparrow & & \text{Benchmark} \\ & \text{What is this gap?} & & \text{By construction} & \text{Relaxation} & & \end{array}$$

Technique: Reduction to Bayesian Selection

[C. Christou Dang '25]

Fix distributions $D_1, \dots, D_n$ and $F \subseteq 2^{[n]}$. Select $S \in F$ to maximize $\sum_{i \in S} X_i$ in expectation over $X_i \sim D_i$.

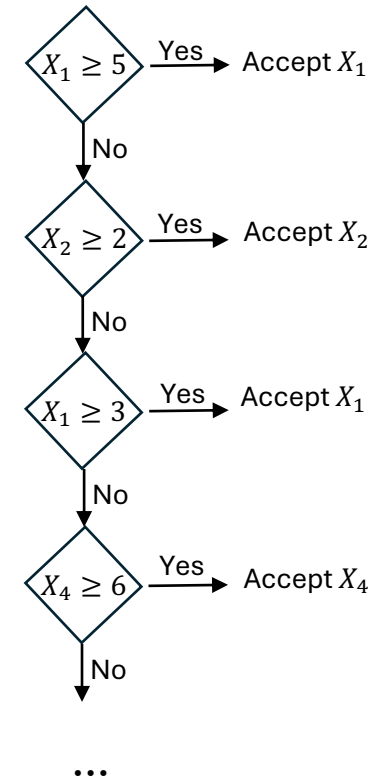
Benchmark $\rightarrow$ • **Ex Ante OPT**: Maximizes sum subject to ex ante feasibility

• **Ex Post OPT**: Selects the optimal set after learning the X_i s

Any alg satisfying $\rightarrow$ • **Semi-Online**: Choose i ; Choose threshold τ_i ; Observe whether $X_i \geq \tau_i$
– If $X_i \geq \tau_i$, must **accept**
– If $X_i < \tau_i$, **continue** and may revisit i with a different threshold later

• **Fixed-Order Online**: Given i in adversarial order, see $X_i \sim D_i$, decide **accept** or **reject**

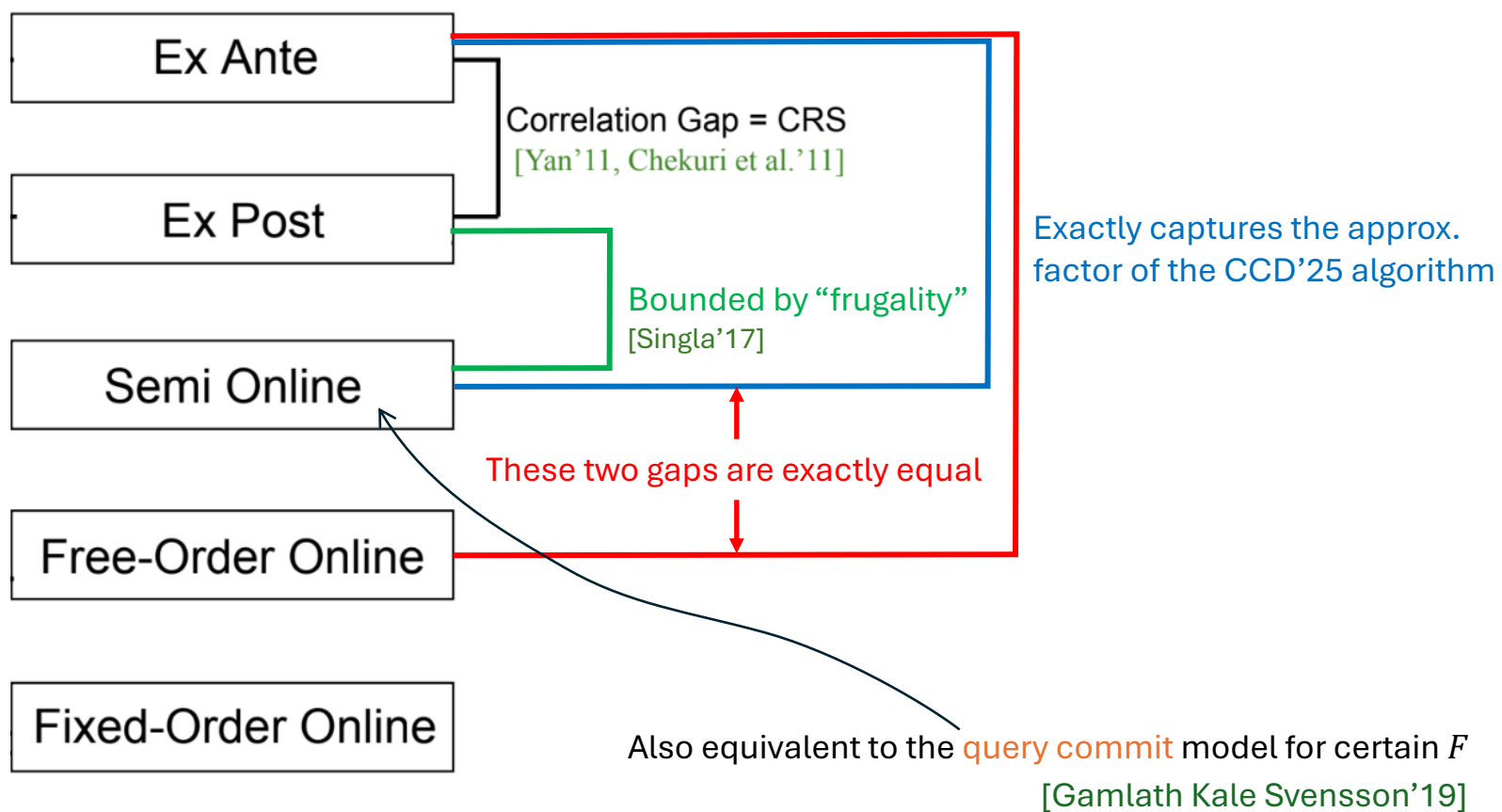
• **Free-Order Online**: Visit i in optimal order, see $X_i \sim D_i$, decide **accept** or **reject**



Technique: Reduction to Bayesian Selection

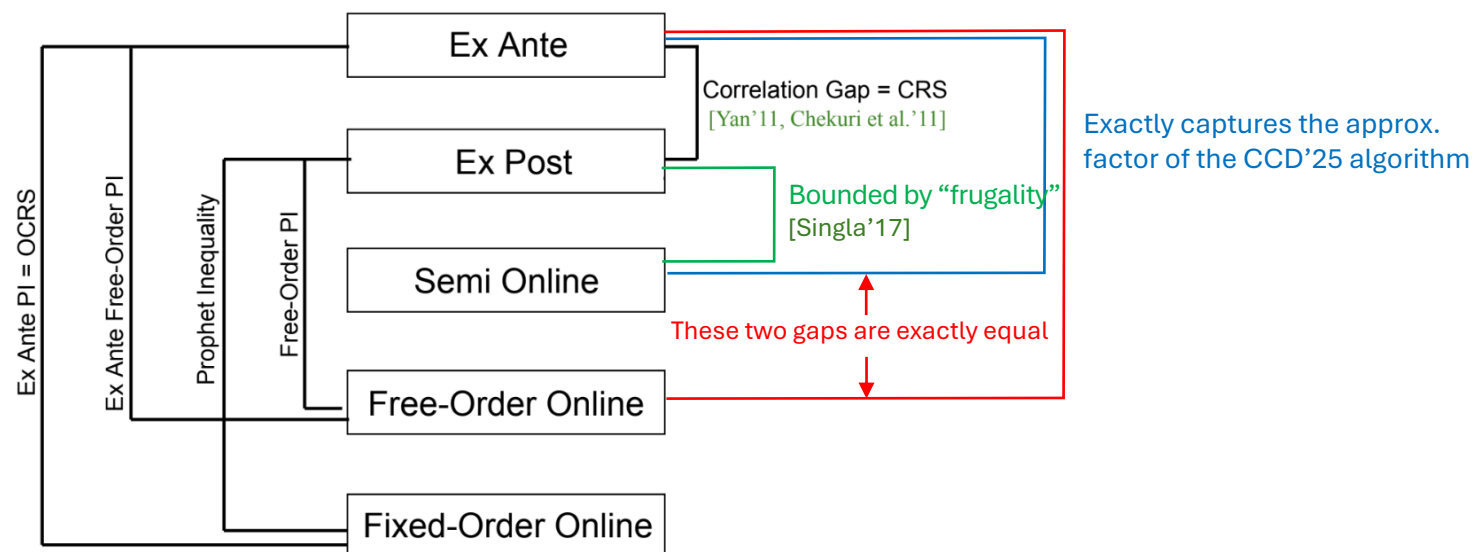
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Technique: Reduction to Bayesian Selection

[C. Christou Dang '25]



Results for optimization with costly information under constraint F

Constraint F	Matroid	k -system	Knapsack	Bipartite Matching
Correlation Gap	$e/(e-1)$ [Yan'10]	$k+1$ [Yan'10]	3.13 [Jiang Ma Zhang'21]	1.96 [Nuti-Vondrak'24]
Frugality	1	k [Singla'17]	2 [Singla'17]	1.52 [Huang et al.'25]
Approximation factor	$e/(e-1)$	$k+1$	3.13 [Jiang Ma Zhang'21]	2.98

Summary: extension to multi-modal information acquisition



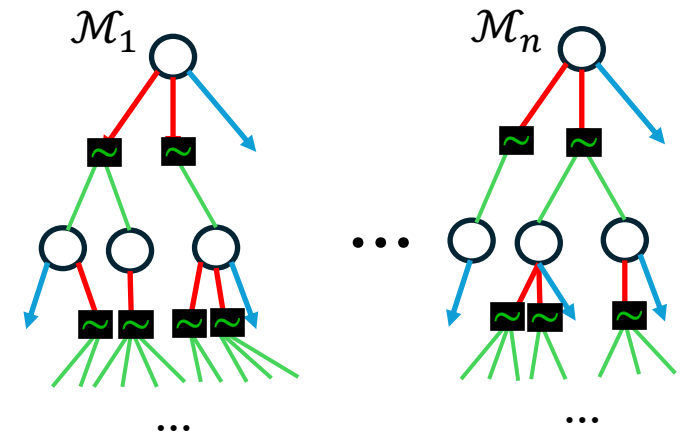
General process of
information acquisition

- Maximization problems can be solved by combining

- Ex Ante Relaxation
- Correlation Gap + Frugality
- Ex Ante Free Order Prophet Inequalities

- What about minimization?

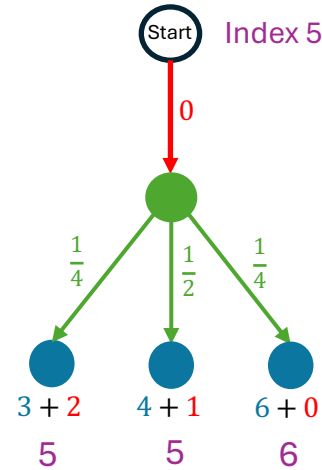
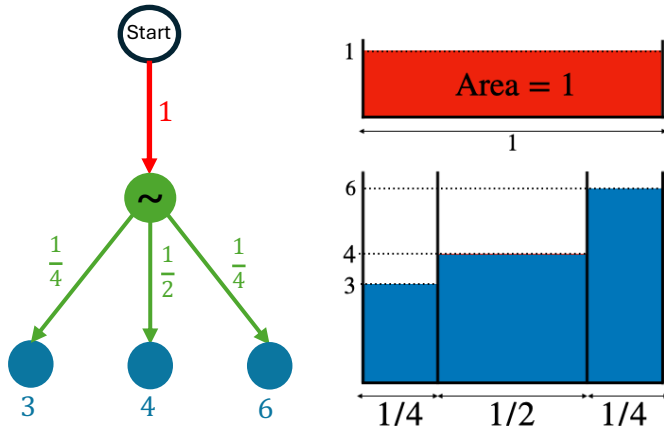
Objective: minimize value of selection + cost of info. acquisition



Concept: Amortization for MDPs

[C. Christou Harlev Scully '26]

Surrogate cost = value of node
+ amortized cost share
Index of a node = smallest surrogate cost
in its subtree (best case scenario)

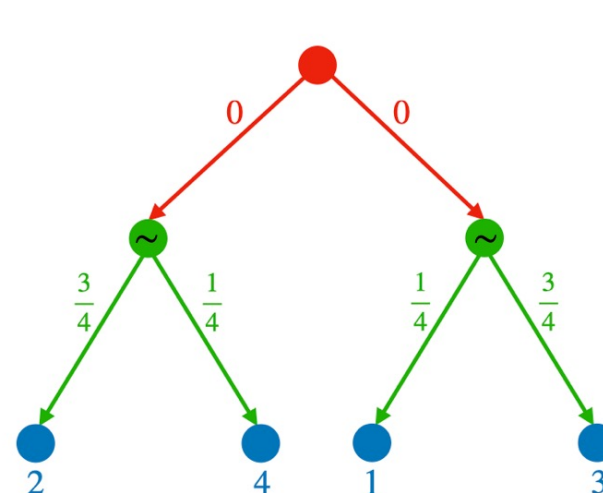
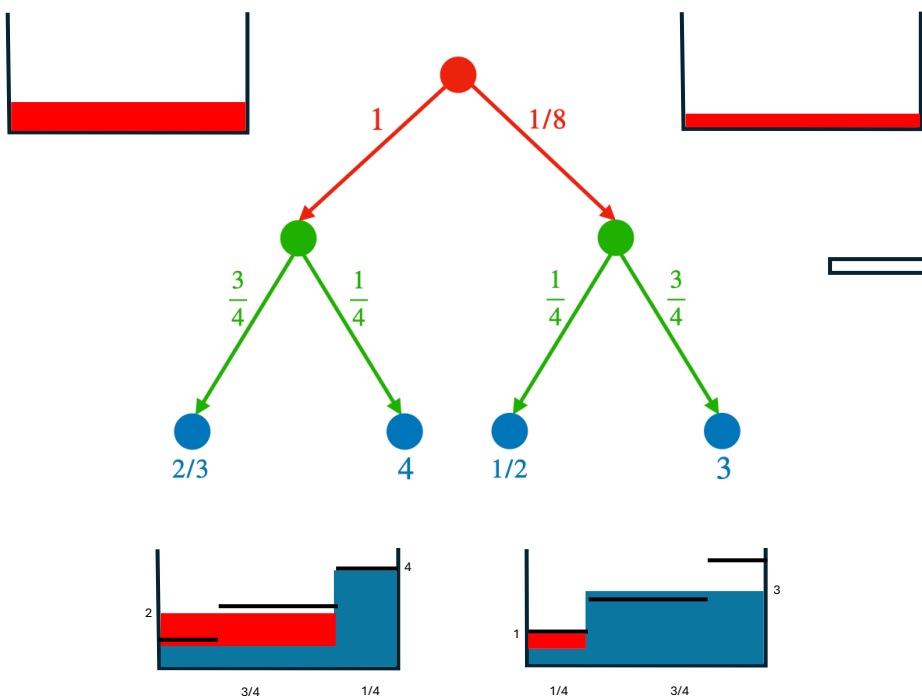


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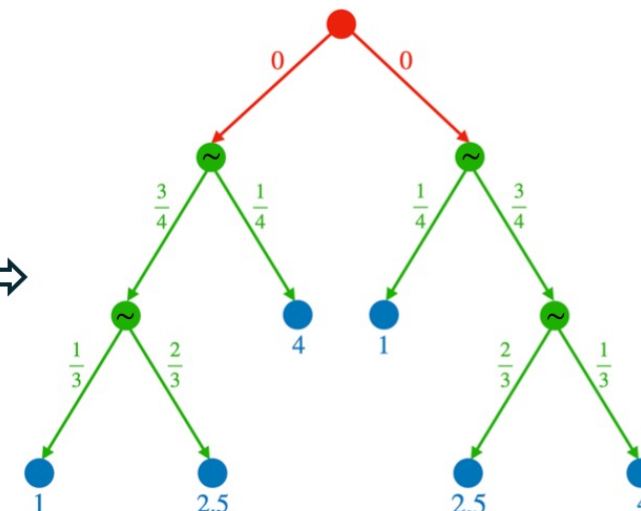
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$$W_l = \begin{cases} 2 & \text{w.p. } 3/4 \\ 4 & \text{w.p. } 1/4 \end{cases} \quad W_r = \begin{cases} 1 & \text{w.p. } 1/4 \\ 3 & \text{w.p. } 3/4 \end{cases}$$



$$W^* = \begin{cases} 1 & \text{w.p. } 1/4 \\ 2.5 & \text{w.p. } 1/2 \\ 4 & \text{w.p. } 1/4 \end{cases}$$

Can we define surrogate costs W_i so that $\text{OPT} \geq \mathbb{E}[\min_i W_i]$?

- Problem: surrogate costs depend on which action is taken.
- Solution: define a common “lower bound”.

We define W^* such that for **each** action a ,

$$W^* \leq_{\text{SOSD}} W^a.$$

Replacing W^a by W^* only lowers charged cost.

Concept: Amortization for MDPs

[C. Christou Harlev Scully '26]

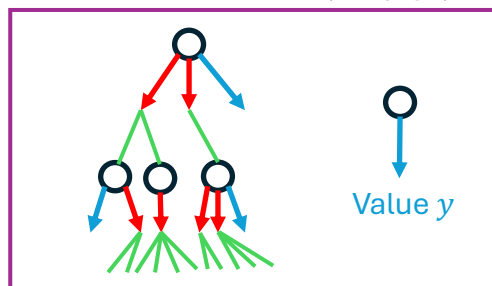
Surrogate cost = value of node
+ amortized cost share

Index of a node = smallest surrogate cost
in its subtree (best case scenario)

Theorem: For each MDP $\mathcal{M}_i$, we can define a surrogate cost W_i^* such that:

1. For the full game $(\mathcal{M}_1, \mathcal{M}_2, \dots, \mathcal{M}_n)$ we have $\text{OPT} \geq \mathbb{E}[\min W_i^*]$.
2. In each local game $(\mathcal{M}_i, y)$ we have $\text{OPT} = \mathbb{E}[\min(y, W_i^*)]$.

Local game $(\mathcal{M}_i, y)$



Can we define surrogate costs W_i so that $\text{OPT} \geq \mathbb{E}[\min_i W_i]$?

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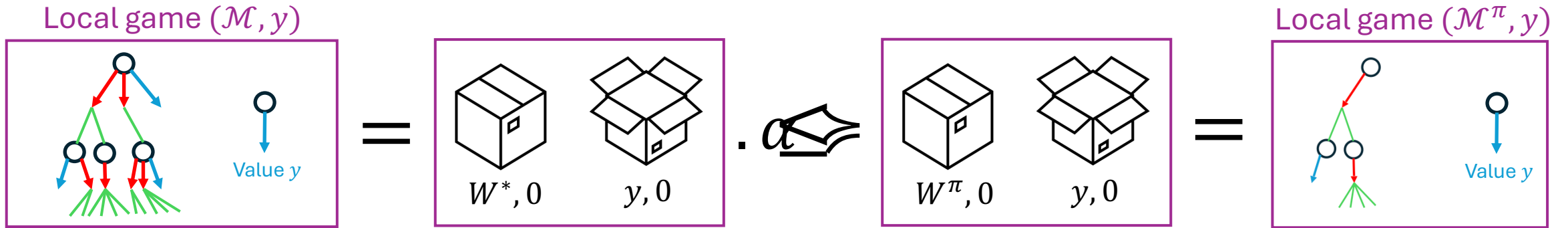
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Technique: Commitment Gap via Local Approximation

[Doval Scully '24]



- We say that a commitment π is an α local approximation to $\mathcal{M}$ if αW^* second order stochastically dominates W^π
- If for all i , π_i obtains an α local approximation to $\mathcal{M}_i$,
then $(\pi_1, \dots, \pi_n)$ obtains an α global approximation to $(\mathcal{M}_1, \dots, \mathcal{M}_n)$
- Extends **automatically** to objectives that admit good frugal algorithms

Local Approximation

$$\text{ComGap} \leq \max_i \text{LocApp}(\mathcal{M}_i) \cdot \text{Frugal}(F)$$

- Depends on the structure of the MDPs
- Applies to both minimization and maximization
- Might not hold for complex MDPs
- Potentially overcomes the correlation gap
- Requires computation of the commitment

Ex Ante Relaxation

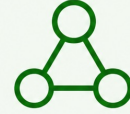
$$\text{ComGap} \leq \text{CorGap}(F) \cdot \text{Frugal}(F)$$

- Only depends on the selection constraint F
- Only meaningful for maximization
- Holds independently of the MDP structure
- Tied to the correlation gap of the constraint
- Computed via the ex-ante relaxation



General feasibility constraints

- ✓ Any constraints that admit good frugal algorithms



Correlated / dependent input variables

Next: correlated values

Simplest setting: Weitzman's Pandora's Box

- Single-element selection
- Independent alternatives
- Binary information state: known or unknown
- Linear objective: value of selected item minus inspection cost

- ✓ Multi-modal info. acquisition via ex ante relaxation or local approx
- ✓ Any Markov chain type process of info. acquisition



General, possibly nonlinear objectives



General process of information acquisition



Correlated /
dependent input
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Extension to correlated values

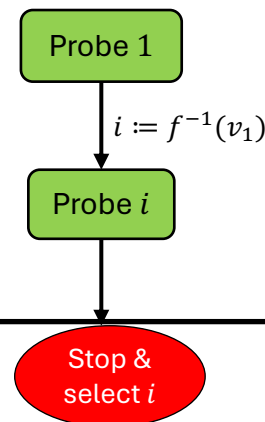
- Optimization problem: select one alternative
- Information acquisition: Pandora's Box
- **Minimize** value + opening cost
- Joint distribution over box values: $(v_1, \dots, v_n) \sim D$
 m “scenarios” representing the support of D

Example: may need to open “useless” boxes to find “useful” ones

- Let f be a random mapping from $[n]$ to a large domain.

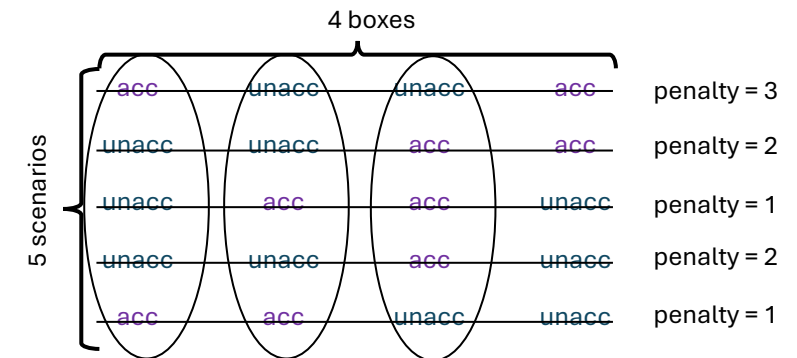
$$S^{(i)} = \begin{cases} v_1 = f(i) \\ v_i = 0 \\ v_{i'} = \infty \quad \text{for } i' \neq 1, i \end{cases}$$

- $\text{OPT} = 2$



A special case: the **Min Sum Set Cover** problem

- All costs are 0 or ∞ . I.e. boxes are “**acceptable**” or “**unacceptable**”.
- For simplicity: all probing penalties are 1; Uniform distribution over m scenarios.
- Think of the scenarios as elements and boxes as sets. If an “**acceptable**” box is opened in a scenario, the scenario gets covered.
- Objective: minimize total penalty a.k.a. covering time.





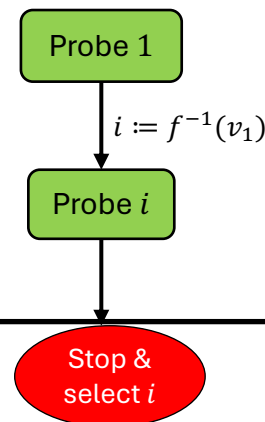
Correlated /
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Extension to correlated values

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Another special case: **Optimal Decision Tree**

- Use “tests” to discover which of m given hypotheses is true
- Objective: minimize probing cost
- m states of the world $\Rightarrow O(\log m)$ -approximation
[Gupta Nagarajan Ravi’18, Li Liang Musmann’20]
- Tight in general [Chakravarthy et al.’07]

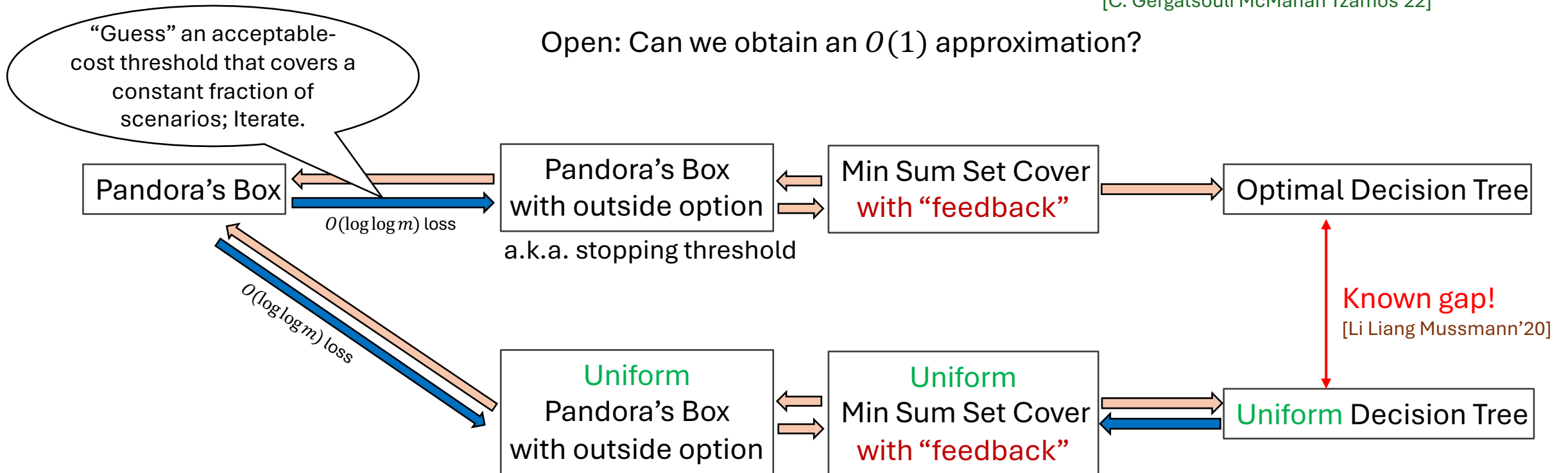
Technique: Reduction to Optimal Decision Tree

[C. Gergatsouli McMahan Tzamos '21]

Theorem: $\tilde{O}(\log m)$ -approximation where m = number of scenarios.

[C. Gergatsouli McMahan Tzamos'22]

Open: Can we obtain an $O(1)$ approximation?



Can we say anything interesting when m is very large?



Correlated /
dependent input
variables

Extension to large support correlated distributions

Concept: Approximating the Partially Adaptive Optimum

Fully Adaptive Opt (FA-OPT)

- Probing order and stopping rule depend adaptively on obtained info.

Hard to approximate better than $\Omega(\log m)$

Inspired by Weitzman's solution

Partially Adaptive Opt. (PA-OPT)

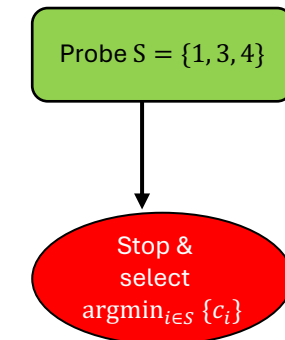
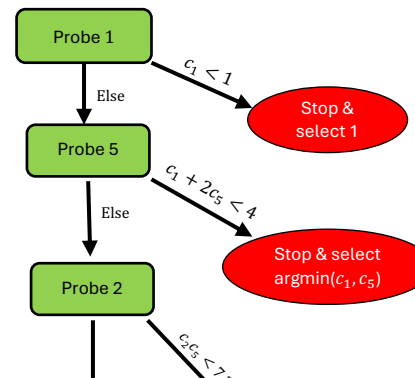
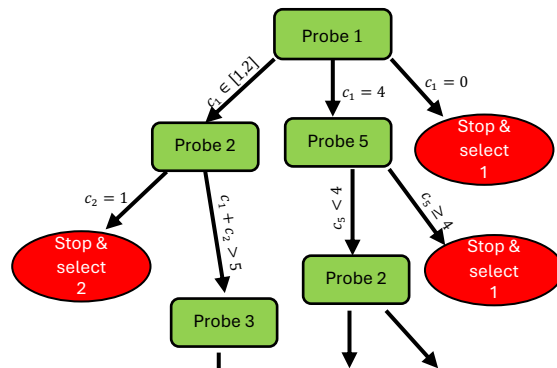
- Probing order is non-adaptive
- Stopping rule depends adaptively on obtained info.

Can approximate and learn from data!
[C. Gergatsouli Teng Tzamos Zhang '20]

Non Adaptive Optimum (NA-OPT)

- Selects a subset of boxes
- Opens all simultaneously
- Chooses the best box

Hard to approximate better than $\Omega(\log m)$
(captures set cover)



Theorem: Weitzman's algorithm, suitably adapted, is a 4.4-approximation to the PA-OPT.

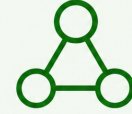
[Gergatsouli Tzamos'24]



General feasibility constraints

- ✓ Any constraints that admit good frugal algorithms

✗ Maximization?
Hard to approximate NA-OPT within any constant factor via fully adaptive algos



Correlated / dependent input variables

- ✓ Log approx. for small support
- ✓ Const approx. to PA-OPT

Simplest setting: Weitzman's Pandora's Box

- Single-element selection
- Independent alternatives
- Binary information state: known or unknown
- Linear objective: value of selected item minus inspection cost

- ✓ Multi-modal info. acquisition via ex ante relaxation or local approx
- ✓ Any Markov chain type process of info. acquisition



General, possibly nonlinear objectives

Preliminary investigations by
[Olszewski Weber'15, Berger Ezra Feldman Fusco'23]



General process of information acquisition

Some open directions

- Minimization in the MDP setting
 - Few and weak results
- Maximization in the correlated setting
 - Can we make suitable assumptions to simplify the problem?
- Short range correlations?
- General objectives
 - Going beyond frugality?
 - Non-linear objectives, e.g. Submodular over selected variables? Two-dimensional coverage?

Thanks for your attention!

Questions?