

# **CS344M**

# **Autonomous Multiagent Systems**

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# Good Afternoon, Colleagues

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Are there any questions?

# Logistics

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- Project proposal questions?

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  - Hand in 2 hard copies, mark 2D/3D

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Model the ant, not the colony

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Agents tied to environment

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Note: supports hierarchical agents

# Examples from Nature

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- Ants: path planning
- Ants: brood sorting
- Termites: nest building
- Wasps: task differentiation
- Birds and Fish: flocking
- Wolves: surrounding prey



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- Provide an “entropy leak”

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  - Multiple robots
  - Other metrics
- Experiments
  - Now multiple robots make a difference

# Real Robot Applications

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## Task Allocation :

- Also on real robots
- How many is too many?

# Discussion

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Hybrid systems?

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