



VOYAGER: An Open-Ended Embodied Agent with Large Language Models

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What is necessary for an embodied agent?

World Knowledge

Continuous Exploration

Open-Ended Objectives

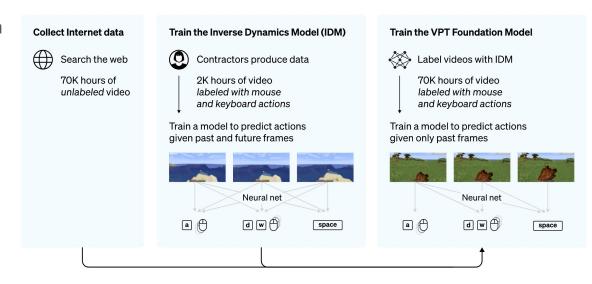






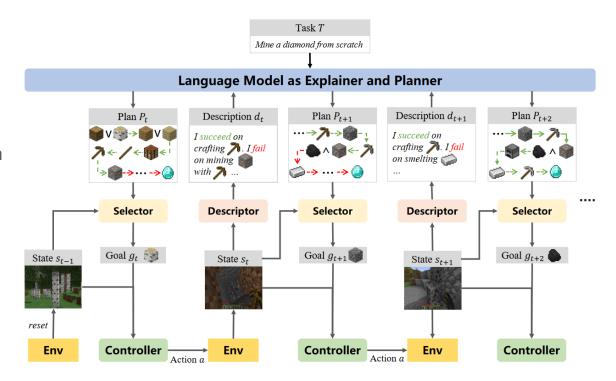
Video-Pretraining (VPT)

- OpenAl VPT: Extract policies from human-play videos
 - Use keyboard and mouse control
 - Internet-scale data
 - Continuous exploration
 - Do not have any objectives



Describe, Explain, Plan and Select

- DEPS: Use LLM as explainer and planner
 - Task driven
 - Top-down decomposition
 - Not continuous



Z. Wang, S. Cai, A. Liu, X. Ma, and Y. Liang, "Describe, Explain, Plan and Select: Interactive Planning with Large Language Models Enables Open-World Multi-Task Agents." arXiv, Feb. 03, 2023. doi: 10.48550/arXiv.2302.01560.

Minecraft AI NPC



In game Q&A



Task Completion using code

R. Volum et al., "Craft an Iron Sword: Dynamically Generating Interactive Game Characters by Prompting Large Language Models Tuned on Code," in Association of Computational Linguistics, Microsoft, Jul. 2022. [Online]. Available: https://www.microsoft.com/en-us/research/publication/craft-an-iron-sword-dynamically-generating-interactive-game-characters-by-prompting-large-language-models-tuned-on-code/

Finish task with supervision



Why not let the agent propose the task itself?

Automatic Curriculum

Curriculum (GPT-4)



Wood Log



Crafting Table



Wooden Pickaxe



Stone Sword



Make Furnace



Make Shield



Hunt Cow



Cook Steak



Combat Zombie



Make Clock



Diamond Sword



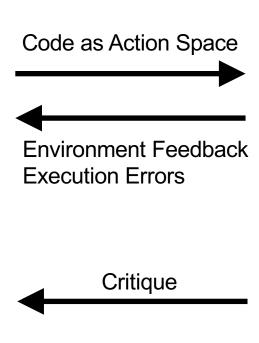
Beat Enderman

Automatic Curriculum



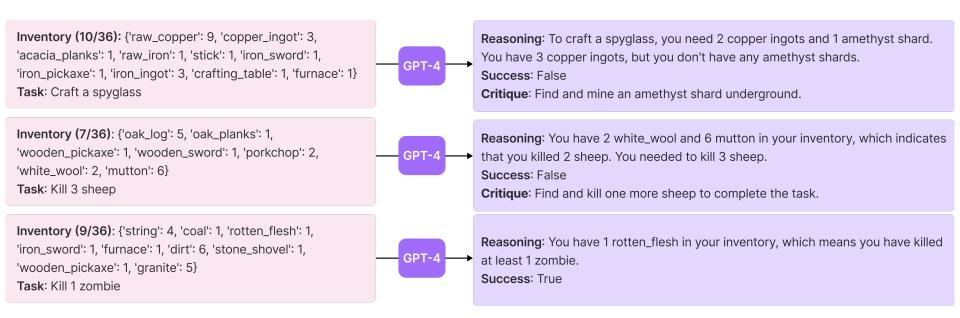
Action-Critic Loop Overview







Self-Critic Success Check



Environment and Error Feedback

Environment Feedback

I cannot make stick because I need: 2 more planks I cannot make stone_shovel because I need: 2 more stick

Actor (GPT-4)

Execution Error

```
throw new Error(`No item named ${name}`);
No item named acacia_axe
at line 18:await craftItem(bot, "acacia_axe", 1);
```

Actor (GPT-4)

Structure Overview

Automatic Curriculum



Iterative Prompting Mechanism

Skill Library



Mine Wood Log



Make Crafting Table



Craft Stone Sword



Craft Shield



Cook Steak



Combat Zombie

Skill Library

Actor (GPT-4) async function combatZombie(bot) { // Equip a weapon const sword = bot.inventory.findInventoryItem(mcData.itemsByName["stone sword"].id); if (sword) { await bot.equip(sword, "hand"); } else { await craftStoneSword(bot); // Craft and equip a shield await craftShield(bot); // Look for and combat a zombie



Skill Library



Mine Wood Log



Make Crafting Table



Craft Stone Sword



Craft Shield

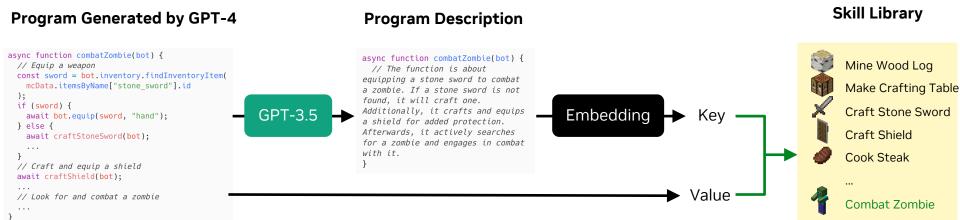


Cook Steak

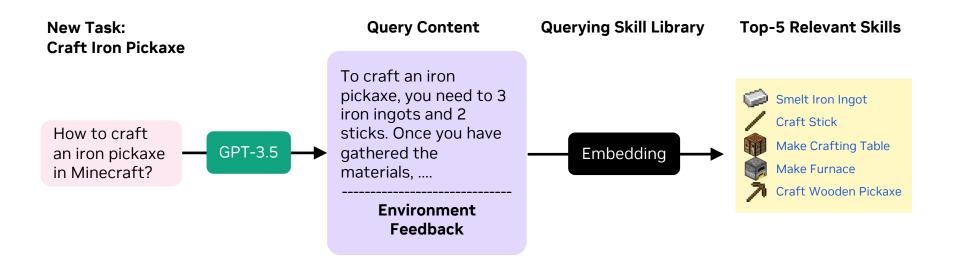


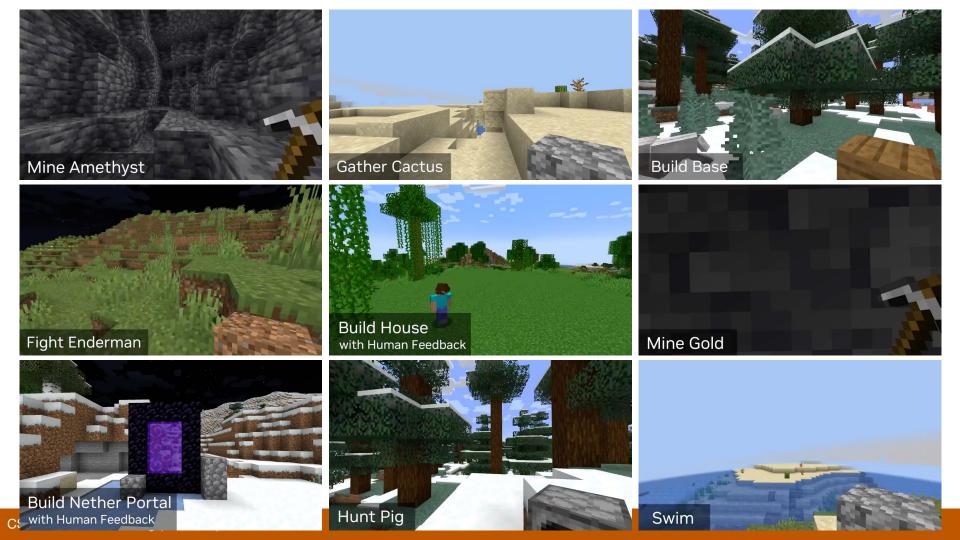
Combat Zombie

Adding new skills



Retrieving skills





Baseline: ReAct

- Reason before Act
 - Just like "Let's think step by step"
- Experiment setting:
 - No curriculum
 - No error feedback
 - No critic
 - No skill library

```
(2b) ReAct (Reason + Act)
Act 1: Think[First I need to find a pepper shaker...more
likely to appear in cabinets (1-6), countertops (1-3), ...
Act 2: Go to cabinet 1
Obs 2: On the cabinet 1, you see a vase 2.
(Here the agent go to cabinet 1, then cabinet 2, 3, then countertop 1 and 2)
Act 6: Go to countertop 3
Obs 6: On the countertop 3, you see a apple 1, a bread 1,
..... a pepper shaker 1, and a vase 3.
Act 7: Take pepper shaker 1 from countertop 3
Obs 7: You pick up the pepper shaker 1 from the countertop 3.
Act 8: Think [Now I find a pepper shaker 1. Next, I need to
put it in/on drawer 1. ]
Act 9: Go to drawer 1
Obs 9: Drawer 1 is closed.
Act 10: Open drawer 1
Obs 10: You open Drawer 1 ...
Act 11: Put pepper shaker 1 in/on drawer 1
Obs 11: You put pepper shaker 1 in/on the drawer 1.
```

Baseline: Reflexion

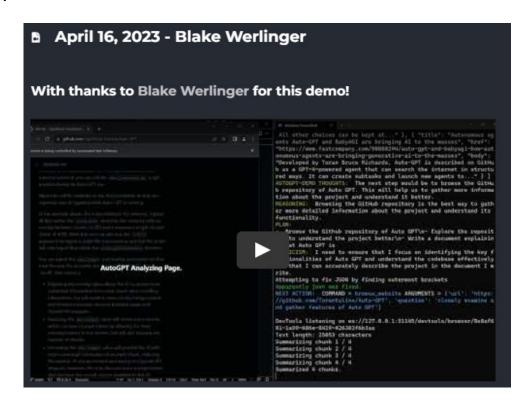
However, first, then will go to

eward

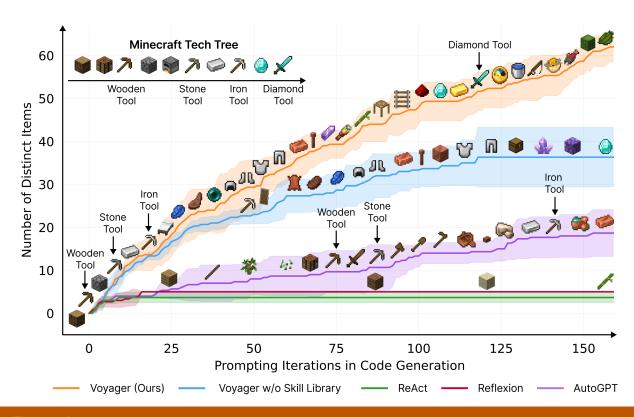
Reflection: In this environment, my plan was to find a mug then find and use a desklamp. However, the task says to examine the mug with the desklamp. I should have looked for the desklamp first, then looked for the mug. I noticed that the desklamp was found on desk 1. In the next trial, I will go to desk 1, find the lamp, then look for the mug and examine it with the desklamp.

Baseline: AutoGPT (April 16th)

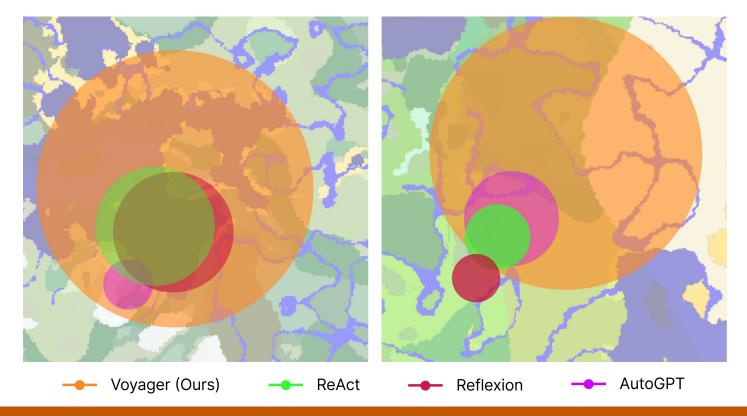
- Al agent for complex tasks
- Experiment setup:
 - Task decomposition
 - Replanning over iterations
 - No curriculum
 - No critic



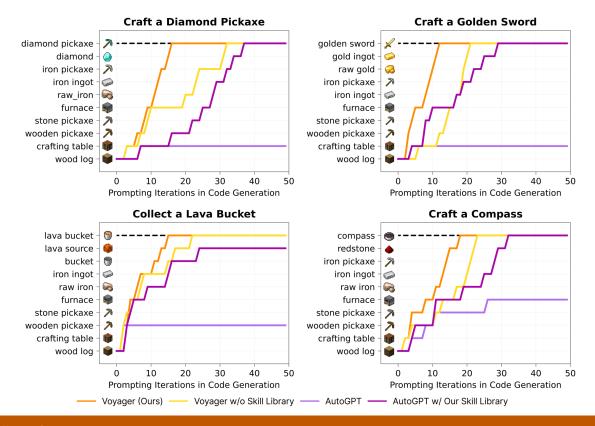
Open-Ended Exploration



Map Coverage



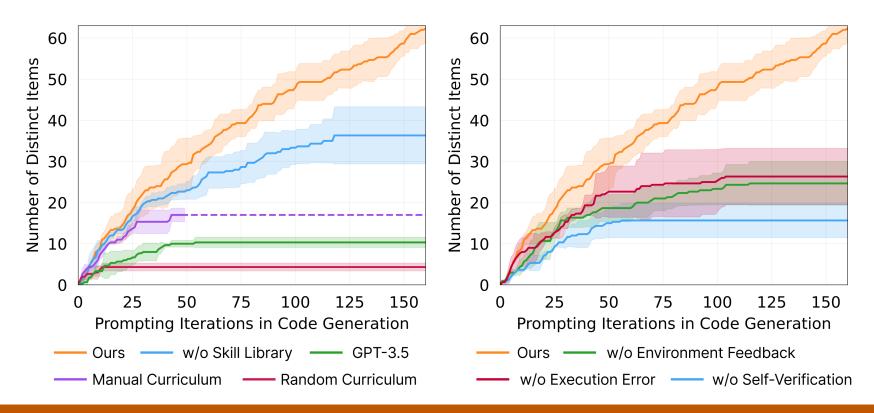
Zero-shot Generalization to Unseen Tasks



Human as Multimodal Feedback



Ablation Studies



Q&A